# **MITSUBISHI** MELSOFT FR Configurator SW3 INSTRUCTION MANUAL



## **INVERTER SETUP SOFTWARE**

# **FR-SW3-SETUP-WE**

-Windows<sup>®</sup>(English) Version-



## INTRODUCTION

Thank you for choosing this Mitsubishi Inverter Setup Software.

This instruction manual gives handling information and precautions for use of this software. Incorrect handling might cause an unexpected fault. Before using the software, please read this manual carefully to use the software to its optimum performance.

Please forward this manual to the end user.

When reading this manual, note the following.

- This manual is written on the basis that Windows<sup>®</sup> XP (English version) is the operating system.
- Drive D is described as the CD-ROM drive and Drive C as the hard disk drive.

Trademarks

- Microsoft Windows and Excel are registered trademark or trademark of Microsoft Corporation in the United States and/or other countries.
- (1) The formal name of Windows<sup>®</sup> 2000 is Microsoft Windows<sup>®</sup> 2000 operating system.
- (2) The formal name of Windows<sup>®</sup> XP is Microsoft Windows<sup>®</sup> XP operating system.
- "FR Configurator" is a registered trademark of Mitsubishi Electric Corporation.
- The copyright and other rights of this software all belong to Mitsubishi Electric Corporation.
- No part of this manual may be copied or reproduced without the permission of Mitsubishi Electric Corporation.
- Other company and product names herein are the trademarks and registered trademarks of their respective owners.
- SPREAD
- Copyright 2004 FarPoint Technologies, Inc..
- Visual Combo Copyright 2006 MCOR Co., Ltd

#### For Maximum Safety

- This product has not been designed or manufactured for use with any equipment or system operated under life-threatening conditions.
- Please contact our sales office when you are considering using this product in special applications such as passenger mobile, medical, aerospace, nuclear, power or undersea relay equipment or system.
- Although this product was manufactured under conditions of strict quality control, you are strongly advised to install safety devices to prevent serious accidents when it is used in facilities where breakdowns of the product are likely to cause a serious accident.

## -CONTENTS-

\_

1 (	DU'	TLI	NE
-----	-----	-----	----

1.1 B	efore Using This Software	. 2
1.1.1	Packing Confirmation	2
1.2 S	ystem Configuration	. 3
1.2.1	System Requirement	3
1.2.2	Compatible inverters	3
1.2.3	System configuration	4
1.3 lı	nstallation and Uninstallation	. 5
1.3.1	Installation of FR Configurator	5
1.3.2	Uninstallation of FR Configurator	8
1.3.3	Installation of VFD Setup Software SW1	9
1.4 C	connection and Parameter Setting	10
1.4.1	Connection Method	. 10
1.4.2	Connection using USB connector (FR-A700, E700 only)	. 12
1.4.3	Connection using PU connector	. 16
1.4.4	Connection of multiple inverters using RS-485 terminal	. 19
1.4.5	Connection through GOT (FA transparent function)	. 21
1.5 S	etting of Operation Mode of the Inverter	24
1.5.1	Operation mode setting	. 24
1.6 S	tart and Close	29
1.6.1	Starting FR Configurator	. 29
1.6.2	Start flow of FR Configurator	. 30
1.6.3	Closing FR Configurator	. 31
1.7 E	xplanation of Window	32
1.7.1	Main frame	. 32
1.7.2	Navigation area	. 34
1.7.3	System area	. 35
1.7.4	Monitor area	. 36
1.7.5	Menu and Tool bar	. 37
1.7.6	Status bar	. 39
1.7.7	Communication manager	. 39

## **2 WHEN USING FOR THE FIRST TIME**

41

1

2.1	St	tartup	42
2.2	E	asy Setup	43
2.	2.1	System Property	. 44

55

Communication Setting	45
Inverter Setting Method	47
Automatic Detection	48
Model Setting	49
Inverter Selection	50
Control Method	51
Motor setting	52
Start Command and Frequency (Speed) Setting Method	53
Parameter List	54
	Communication Setting Inverter Setting Method Automatic Detection Model Setting Inverter Selection Control Method Motor setting Start Command and Frequency (Speed) Setting Method Parameter List

## **3 SETTING WIZARD**

3.1	Overview of Setting Wizard	56
3.1	1.1 Function outline	
3.1	1.2 Individual setting window of Setting Wizard	57
3.1	1.3 Parameter List	58
3.2	Details of Setting Wizard	59
3.2	2.1 Acceleration/Deceleration Pattern and Time Setting	59
3.2	2.2 Output Terminal(FM, CA, AM) Calibration	60
3.2	2.3 Analog Input Terminal Calibration	61
3.2	2.4 Tuning (FR-A700, D700, E700 only)	63
3.3	Troubleshooting	65
3.3	3.1 Function Outline	65
3.3	3.2 Status Display	
3.3	3.3 Cause Estimate	67
3.3	3.4 Related Parameter	68
3.4	Details of troubleshooting	69
3.4	4.1 Motor does not rotate as commanded	69
3.4	4.2 Motor does not rotate, or motor rotation direction does not change	
3.4	4.3 Motor coasts	72
3.4	4.4 Motor current is large	73
3.4	4.5 Acceleration/deceleration is not as commanded	74
3.4	4.6 External device (peripherals) malfunctions	75
3.4	4.7 Operation mode does not change	
3.4	4.8 Unable to write parameter setting	79
3.4	4.9 Unable to communicate	81

## 4 FUNCTION

83

4.2	Options	85
4.2	2.1 Communication	
4.2	2.2 Preferences	
4.3	File Management and Print	
43	1 Type of files	87
4.3	32 Open	
4.3	3.3 Save	
4.3	3.4 Data import and export (File input and output)	
4.3	8.5 Print	
4.4	Test Operation (Navigation area)	
4.4	1 Test Operation screen	
4.4	.2 Indication of inverter frequency and fault	
4.4	.3 Indication of operation mode and switching	
4.4	.4 Setting of running frequency (speed, machine speed)	
4.4	5 Sending of forward/reverse rotation command	
4.5	System View (Navigation area)	
4.5	5.1 System Setting	
4.5	5.2 Setting Wizard	
4.6	Parameter List (System area)	
4.6	5.1 Explanation of screen	
4.6	2 Parameter List Display Format	99
4.6	3.3 Parameter clear and all parameter clear	
4.6	6.4 Read (Batch Read), Write (Batch Write) and Verification	
4.6	6.5 Edit Individual List	
4.6	6.6 Parameter Search	103
4.7	Convert (System area)	
4.7	7.1 Convert image	105
4.7	2.2 Explanation of window	
4.7	7.3 Example of converting	
4.7	7.4 Precautions for Convert	113
4.8	Diagnosis (System area)	121
4.8	8.1 Explanation of window	121
4.8	Procedure of Main circuit capacitor life measuring	122
4.9	Graph (Monitor area)	123
4.9	9.1 Basic flow of Sampling	124
4.9	0.2 Explanation of window	125
4.9	0.3 Sampling item setting	126
4.9	9.4 Sampling setting	128
4.9	0.5 Trigger setting	

IV

151

## **5 TROUBLE INDICATION**

5.1 E	5.1 Error Code		
5.1.1	Communication error with inverter	152	
5.1.2	Communication error when connected through GOT	156	
5.1.3	Other error (Task busy)	158	
5.2 E	rror Display on a Dialog	159	

4.9.6	Scale changing	
4.9.7	Cursor Function	
4.9.8	History display	
4.9.9	Example of Graph sampling (monitoring Output Frequency, terminal RUN, terminal F	U) 135
4.10 B	atch Monitor (Monitor area)	138
4.11 I/	0 Terminal Monitor (Monitor area)	140
4.12 I/	0 Terminal Assignment	141
4.13 M	achine Analyzer (Monitor area) (FR-A700 with Vector Con	trol).142
4.14 н	elp	147
4.14.1	Help	147
4.14.2	Version Information	149

<abbreviations></abbreviations>
PU: Operation panel and parameter unit (FR-PU04, FR-PU07)
· Inverter: Mitsubishi inverter
· FR-A700: Mitsubishi inverter FR-A700 series
· FR-D700: Mitsubishi inverter FR-D700 series
• FR-E700: Mitsubishi inverter FR-E700 series
• FR-F700: Mitsubishi inverter FR-F700 series
· Pr. : Parameter number
• PU operation: Operation using the PU (FR-PU04/FR-PU07)
External operation: Operation using the control circuit signals
· Combined operation: Operation using the PU (FR-PU04/FR-PU07) and external operation
· Standard motor: SF-JR
· Constant torque motor: SF-HRCA
<mark></mark>
<b>REMARKS</b> : Additional helpful contents and relations with other functions are written.
<b>Note</b> : Contents requiring caution or cases when set functions are not activated are written.
<b>POINT</b> : Useful contents and points are written.
indicates a button displayed in a window.
Settine Wizard : Indicates a tab displayed in a window.
[ ] : Indicates a menu selected from menu bar.
" : Indicates a title name of a window.



This chapter explains the "OUTLINE" for use of this product. Always read the instructions before using the software.

1.1	Before Using This Software	2
1.2	System Configuration	3
1.3	Installation and Uninstallation	5
1.4	Connection and Parameter Setting	10
1.5	Setting of Operation Mode of the Inverter	24
1.6	Start and Close	29
1.7	Explanation of Window	32

### **1.1 Before Using This Software**

- This software is a effective support tool for startup and maintenance of the Mitsubishi transistorized inverter. The following functions can be performed efficiently on the personal computer.
  - Startup (Desired function can be performed soon after starting up of this software)
  - Easy Setup (From station number to parameter setting, setting with wizard style dialog (interactive) is available)
  - Setting Wizard (Function setting without regard to parameter number)
  - Tuning (Available from Setting wizard) (FR-A700, E700 series only)
  - Troubleshooting (Estimating cause and counter measure at trouble occurrence)
  - Parameter List (Displaying of parameter list, functional list, initial value change list and editing of the parameters is available)
  - Convert (Converting a parameter setting of the conventional model into FR-A700, D700, E700, or F700 parameter setting)
  - Diagnosis (Displaying faults history and parts life, and measuring main circuit capacitor life )
  - Graph (Monitoring by High Speed sampling or Monitor sampling, and displays in graph form)
  - Batch Monitor (Displaying monitor items of the inverter at the same time)
  - I/O Terminal Monitor (Monitoring the state of input and output terminal)
  - I/O Terminal Assignment (Signal assignment of input and output terminal)
  - Test Operation (Send a start/stop command, or change the set frequency as if using the operation panel of the inverter)
  - Machine Analyzer (Resonance point and anti-resonance point of the machine system can be obtained) (For FR-A700 with vector control)
  - Help (Instruction manual of the inverter and this software can be displayed in a window)

#### () ▼) I• 1

#### Note

- If a file name or folder name is using Unicode, system file writing or reading may not be performed correctly. Please use a file name and folder name without Unicode.
- The following functions of Windows<sup>®</sup> XP are not compatible with this software.
- · Application starting with Windows<sup>®</sup> compatibility mode
- Starting using "Run As..."
- · Remote Desktop
- A part of this software is using a function of Internet Explorer. This software may not function properly depending on Internet Explorer setting. For example, if the user assistant is set in "Option", file opening or selecting function in "Startup" window may become unavailable. Please change the Internet Explorer setting into a default setting, or select the desired function from a main screen of the FR Configurator.
- FR Configurator is not available when inverter is activated with FR-PU07BB Battery mode. FR Configurator may not function properly.

#### 1.1.1 Packing Confirmation

After unpacking, check that the following items are contained in the package:

Item	Quantity
CD-ROM	1
Install Manual	1

#### **1.2 System Configuration**

#### 1.2.1 System Requirement

Components	Description *1		
	IBM PC/AT compatible machine with CD-ROM drive (for installation), USB port *3 or RS-232C port		
	OS	Windows <sup>®</sup> XP Professional SP2 or later, Windows <sup>®</sup> XP Home Edition SP2 or later,	
		Windows <sup>®</sup> 2000 Professional SP4 or later	
		Pentium <sup>®</sup> 133MHz or more (Windows <sup>®</sup> 2000 Professional)	
Personal computer *2	Processor	Pentium <sup>®</sup> 300MHz or more (Windows <sup>®</sup> XP Professional, Windows <sup>®</sup> XP Home	
		Edition)	
	Memory	32MB or more (Windows <sup>®</sup> 2000 Professional)	
		128MB or more (Windows <sup>®</sup> XP Professional, Windows <sup>®</sup> XP Home Edition)	
	Hard disk	Free area of 200MB or more	
Software	Internet Explorer 5.0 or more		
Display	Applicable to display at resolution of 1024 x 768 or more, and 256 colors or more. Compatible with the		
Display	above PC.		
Keyboard	Compatible with the above PC.		
Mouse	Compatible with the above PC.		
Printer	Compatible with the above PC.		

\*1 Windows is a registered trademark of Microsoft Corporation in the United States and other countries. Pentium is a registered trademark of Intel Corporation.

\*2 FR Configurator may not function properly depending on PC used.

\*3 Connection using USB port is available for FR-A700, E700 series.

#### 1.2.2 Compatible inverters

FR Configurator is compatible with the following inverters.

- FR-A700 series
- FR-D700 series
- FR-E700 series
- FR-F700 series

1

#### 1.2.3 System configuration

The following devices are required to use FR Configurator. Setup the system in accordance with the instruction manuals of each devices.



\*1: When using RS-232C of a personal computer, a commercially available converter is required.

Examples of product available on the market (as of September, 2006) Model: DINV-CABV (with connectors and cable) Diatrend Corp.

The converter cable cannot connect two or more inverters (the computer and inverter are connected on a 1:1 basis). Since the product is packed with the RS-232C cable and RS-485 cable (10BASE-T cable + RJ-45 connector), the cable and connector need not be prepared separately. Contact a maker for details of the product.

\*2: Communication with PU connector, RS-485 terminal, or USB connector is available.

(Refer to the instruction manual for details.)

\*3: Available communication port is USB or RS-232C (one of port 1 to 63), and set in Communication settings screen of the FR Configurator. (Using multiple port at the same time is unavailable) Connection of a computer to GOT is 1:1 connection. When using USB for connecting with GOT, use dedicated

cable GT09-C30USB-5P or GT09-C20USB-5P.

- \*4: Overall length of connection cable: 500m
- \*5: GOT RS-422 communication unit (GT15-RS4-9S) is required. Refer to GOT1000 series connection manual for details of RS-422 connection and compatible version of GOT. Up to 10 inverters can be connected with RS-422 connection. Inverter station number can be set from 0 to 31.

#### **1.3 Installation and Uninstallation**

#### 1.3.1 Installation of FR Configurator

To use the Configurator (FR-SW3-SETUP-WE), the files included on the setup disk (CD-ROM) or downloaded file must be installed onto the personal computer.

Check following items before the installation.

- · Close any other applications that have already been started.
- · For the installation, log on as an administrator (Administrator account) and start installation.
- $\cdot\;$  If an inverter is connected by the USB cable, disconnect the USB cable.
- · If the following window is displayed during the installation, click [continue Anyway] to continue the installation.



- Installation files are compressed. FR Configurator does not function with just copying the installation files. Please install the software with using the installation program.
- $\cdot$  To install the software, follow the installation procedure in Windows screen.
- If VFD Setup Software (FR-SW1-SETUP-WE) of an older version (CD-ROM) is installed after the installation of FR Configurator, FR Configurator does not function. In this case, please uninstall FR Configurator (*Refer to page 8*), and then install FR Configurator again.
- · If the older version of FR Configurator has been installed, the older version will be uninstalled during the installation.

#### Installation procedure

The following describes the procedures of installing FR Configurator.

(1) Insert the CD-ROM to an available CD-ROM drive. Installation starts automatically.

#### **REMARKS**

Installation can be started with double-clicking the icon of CD-ROM drive or the following procedure. 1) Choose the [Run...] command from [Start] menu.

2)"Run" window appears.

3)Type "D:\SETUP" (with one-byte characters) in "Open" field and click \_\_\_\_\_. (When CD-ROM drive is D drive)

(2) The window shown on the right is displayed. Click

<u>N</u>ext>



#### 7 Installation and Uninstallation

(3) The window shown on the right is displayed. MELSOFT FR Configurator - InstallShield Wizard Click Next> . Before installation Please read this before installation. For a customer who has older version of VFD Setup Software (CD-ROM) Before installing VFD Setup Software SW1 of this product, please uninstall the older version of VFD Setup Software (CD-ROM). Do not install the older version of VFD Setup Software (CD-ROM) after installing VFD Setup Software SW1 of this product. Applications of this product will not work correctly. <a><br/>
 <br/>
 <b (4) Enter user name and company name. IELSOFT FR Configurator Click Mext> after entering. Customer Information lease enter your information (User name and company name is required to Please enter your name and the name of the company for which you work. proceed to the next step.) User Name: FR Configurator Company Name MITSUBISHI ELECTRIC CORPORATION < Back Next > Cancel (5) Check the installation folder and click  $\underbrace{Next}$ . To change the installation folder, click [Change...] Choose Destination Location Select folder where setup will install files. and select the installation folder. A new folder Setup will install MELSOFT FR Configurator in the following folder. "invsup3" is created at the selected installation To install to this folder, click Next. To install to a different folder, click Browse and select another folder. folder. This software is installed in there. (If the installation folder is not changed, the software is installed at stination Folde "C:\Program Files\MELSOFT\invsup3\_e") C:¥Program Files¥MELSOFT Browse...



<a><br/>
 <br/>
 <b



(6) Check the installing application, and click

(FR Configurator is already selected when this window is shown.)

Check "VFD Setup Software SW1" if required, and

click <u>Next></u>. (Refer to page 9)

(7) Review the installation setting, and click  $\boxed{Next>}$ .



(8) Installation is completed.

Click **Finish** to close the window. Restart the personal computer before using the software.

MELSOFT FR Configurator – InstallShield Wizard				
	InstallShield Wizard Complete The InstallShield Wizard has successfully installed MUSAFF FR Configurator. Click Finish to exit the wizard.			
	K Back Finish Cancel			

(9) A shortcut is created in [Start] menu of Windows after installation is completed.

#### TREMARKS

 $(\mathbf{0})$ 

• If the user is not an administrator (Administrator account) with Windows XP/2000 OS, the installation cannot be made. Log in as a user with administrator permission, and start the installation again.

#### 1.3.2 Uninstallation of FR Configurator

Open the [Start] menu of Windows, and then click [Control panel]. Click "Add or Remove Programs" in the "Control panel" window.

When "Add or Remove Programs" window is displayed, select "MELSOFT FR Configurator SW3" and click remove to start uninstallation.

🐻 Add or Rer	nove Programs	
	Currently installed programs:	Sort by: Name
Change or	MI MELSOFT FR Configurator SW3	Size <u>9.12MB</u>
Programs	Click here for support information.	Used <u>occasionally</u>
•	To remove this program from your computer, click Remove.	Last Used On 8/30/2007 Remove
Add <u>N</u> ew Programs		
Add/Remove Windows Components		
Set Program Access and Defaults		

Click Remove , and a following dialog appears.



Click  $\underline{}_{\underline{Yes}}$  to proceed the uninstallation. (Click  $\underline{}_{\underline{N}0}$  to cancel the uninstallation.)

A following window is displayed when the uninstallation is completed. Click **Finish** to close the window.



#### 🖳 Note

Uninstallation is unavailable while the application is running. Perform the uninstallation after closing the application.

#### 1.3.3 Installation of VFD Setup Software SW1

To install VFD Setup Software SW1, select "VFD Setup Software SW1" in [Select Application] window during the installation.



Click end the installer creates a folder [invsup1] (for VFD Setup Software SW1), and copies required files.



#### Note

- If VFD Setup Software (FR-SW1-SETUP-WE) of an older version (CD-ROM) is installed after the installation of the FR Configurator, FR Configurator does not function. In this case, please uninstall FR Configurator (*Refer to page 8*), and then install FR Configurator again.
- If the older version of VFD Setup Software SW1 (Version information can be checked in "About VFD Setup S/W" window) is installed, uninstall the older version, and then install the new version of VFD Setup Software SW1 or FR Configurator SW2.

### **1.4 Connection and Parameter Setting**

#### 1.4.1 Connection Method

For FR Configurator, communication with USB connector or PU connector is available. Serial communication (PU connector) is the default setting.

 USB connection (FR-A700, E700 only) (*Refer to page 12*) Connect to USB connector of the inverter. 1:1 connection is supported. Connection with using USB hub is not supported.



(2) Serial communication using PU connector (*Refer to page 16*) Connect to PU connector of the inverter. RS-232C/RS-485 converter (cable) is required.



 (3) Serial communication using RS-485 terminal (*Refer to page 19*) Connect to RS-485 terminal of the inverter. Up to 32 inverters can be connected. (FR-E700 series requires RS-485 terminal block (Control terminal option FR-E7TR))



 (4) Communication through GOT (USB / Serial communication) (*Refer to page 21*)
 Connect to RS-485 terminal through GOT (Display). Up to 10 inverters can be connected when using RS-485 terminal. RS-422 communication unit is necessary for GOT.





#### Note

• Taking out and putting in the USB cable while FR Configurator is working may cause the inverter not to be recognized. Perform taking out and putting in the USB cable for some times, or perform inverter reset (reset GOT when communication through GOT) with the USB cable connected to PC.

#### 1.4.2 Connection using USB connector (FR-A700, E700 only)

A personal computer and inverter can be easily connected with one USB cable. 1:1 connection is supported. Connection with using USB hub is not supported.



#### (1) Cable

Interfase	Conforms to USB1.1	
Transmission	10Mbaa	
Speed	TZINIDPS	
Wiring Length	Maximum 5m	
Connector	FR-A700	USB B connector (B receptacle)
Connector	FR-E700	USB mini B-connector (receptacle mini B type)
Power supply	Self-power supply	

Example of FR-A700



Example of FR-E700



## 

•Recommended USB cable for computer-inverter connection (For FR-E700)

	Туре	Spe	cifications
Recommended USB cable	MR-J3USBCBL3M	Connector for inverter	Connector for personal computer
	Cable length 3m	mini B-connector (5 pin)	A-connector

#### (2) Related parameters for USB connection

Set the following communication parameter when connecting USB connector of the inverter. When performing parameter writing or run command input, set the following command source parameters, and switch the operation mode to PU operation mode.

Invertor	Parameter Setting			
inverter	Communication Parameter	Command Source Parameter	Mode	
FR-A700	<i>Pr. 548 USB communication check time interval</i> $\neq$ 0 (initial value 9999)	Pr: 551 PU mode operation command source selection = "3" (initial value 2)	PU	
FR-E700		Initial value	PU	

#### () REMARKS

• Switching of the operation mode is available at "Test Operation" window (*Refer to page 90*) in Navigation area.

Set 3s or more (or 9999) in *Pr. 548 USB communication check time interval.* 

• Set a station number of the each inverters in *Pr. 547 USB communication station number*. Perform inverter reset after setting the parameter.

Parameter Number	Name	Initial Value	Setting Range	Description
547	USB communication station number	0	0 to 31	Inverter station number specification
			0	USB communication is possible. Trips in the PU operation mode (E.USB)
548	548 USB communication check time interval	9999	0.1 to 999.8.0s	Sets the interval of communication check time. If a no-communication state persists for longer than the permissible time, the inverter will come to trip (E.USB).
			9999	No communication check
	PU mode operation	FR-A700 : 2	1 *2 2	Selects the RS-485 terminal as the PU
				operation mode command source.
				Selects the PU connector as the PU operation
			3	Selects the USB connector as the PU
				operation mode command source.
<b>551</b> *1				Selects the operation panel as the PU
	command source selection	FR-E700:9999	4 *3	operation mode command source.
				USB automatic recognition
				Normally, operation panel is the command
			9999 *3	source. When the parameter unit is connected
				to the PU connector, PU is valid. When USB is
				connected, USB is the command source.

\*1 Pr: 551 is always write-enabled.

\*2 Available for FR-A700.

\*3 Available for FR-E700.



#### Note

• Always reset the inverter after making the setting of the parameters. After you have changed the communicationrelated parameters, communication cannot be made until the inverter reset. (3) When connecting USB for the first time

If a personal computer and inverter are connected via USB for the first time with the inverter power ON, "Found New Hardware Wizard" window is displayed.

The following additional wizard is displayed for Windows XP. For Windows 2000, inverter is automatically detected.

1) Check "No, not this <u>t</u>ime", and click <u>Next></u>.

2) Check "Install the software automatically (Recommended)" and click Next> .

 If the screen shown on the right is displayed when using Windows XP, click <u>Continue Anyway</u> to proceed the installation.



4) The installation of the driver is completed. Click Finish to close the window.



nd New Hardware Wizard				
	Welcome to the Found New Hardware Wizard			
	This wizard helps you install software for:			
	MITSUBISHI FR-E700 USB Controller			
	If your hardware came with an installation CD or floppy disk, insert it now.			
	What do you want the wizard to do? Dinstall the software automatically [Recommended] Install from a list or gpecific location (Advanced)			
	Click Next to continue.			
	Cancel			





(Example of FR-E700)

#### 1.4.3 Connection using PU connector

PU connector is used for connecting with RS-232C port of a computer. RS-232C/RS-485 converter (cable) is required. 1:1 connection is supported.



#### (1) PU connector pin-outs



Pin Number	Name	Description
1)	80	Earth (Ground)
1)	1) SG	(Connected to terminal 5)
2)	—	Operation panel power supply
3)	RDA	Inverter receive+
4)	SDB	Inverter send-
5)	SDA	Inverter send+
6)	RDB	Inverter receive-
7)	50	Earth (Ground)
()	36	(Connected to terminal 5)
8)	—	Operation panel power supply

#### Example of FR-D700



Inverter (receptacle side) viewed from bottom 8) to 1)

Example of FR-E700







## 

• Refer to the following when fabricating the cable on the user side. Commercially available product example (as of November, 2006)

Product Name	Туре	Maker
10BASE-T cable	SGLPEV-T 0.5mm x 4P *1	Mitsubishi Cable Industries, Ltd.
RJ-45 connector	5-554720-3	Tyco Electronics Corporation

\*1 Do not use pins No. 2, 8 of the 10BASE-T cable.

• Distributor is necessary when connecting multiple inverters.

Refer to the inverter manual for connecting multiple inverters.



- Note
  Pins No. 2 and 8 provide power to the operation panel or parameter unit. Do not use these pins for RS-485 communication (R 6 double of the operation panel or parameter unit.)
  - communication. (*Refer to the inverter Instruction Manual for details.*)
    Do not connect the PU connector to the computer's LAN board, FAX modem socket or telephone modular connector. The product could be damaged due to differences in electrical specifications.

OUTLINE

#### Connection and Parameter Setting

(2) Related parameters for connection using PU connector

Set the following communication parameter when connecting PU connector of the inverter.

When performing parameter writing or run command input, set the following command source parameters, and switch the operation mode to the following operation mode.

Invertor	Communication	cation Parameter Setting		
inverter	Option	Communication Parameter	Command Source Parameter	Mode
FR-A700, F700	-	Pr. 122 PU communication check time	Initial value	PU
FR-D700	-	<i>interval</i> ≠ "0"	Initial value	NET
	No	(initial value 9999)	Initial value	NET
		Pr. 123 PU communication waiting time	Pr. 551 PU mode operation command	
FR-E700	Yes	<i>setting</i> ≠ "9999"	source selection $\neq$ "2"	PU
		(initial value)	(initial value 9999)	

#### REMARKS

· Switching of the operation mode is available at "Test Operation" (Refer to page 90) window in Navigation area.

· Set 3s or more (or 9999) in *Pr. 122 PU communication check time interval*.

Set a station number of the each inverters in *Pr. 117 PU communication station number* when connecting multiple inverters. Perform inverter reset after setting the parameter.

Parameter Number	Name	Initial Value	Setting Bange	Description
Number			Kange	Inverter station number specification
117	PU communication	0	0 to 31	Set the inverter station numbers when two or more inverters
	station number	Ū	(0 to 247) *1	are connected to one personal computer
				RS-485 communication can be made. Note that a
			0	communication fault (EPUE) occurs as soon as the inverter
			Ũ	is switched to the operation mode with control source
	PU communication			Communication check (signal loss detection) time interval
122	check time interval	0	0 1 to	If a no-communication state persists for longer than the
			999.8.0s	permissible time, the inverter will come to trip (depends on <i>Pr</i> .
				502 ).
			9999	No communication check (signal loss detection).
	123 PU communication waiting time setting	9999	<del>.</del> .	Set the waiting time between data transmission to the inverter
123			0 to 150ms	and response.
			9999	Set with communication data.
			1 +0	Selects the RS-485 terminal as the PU operation mode
			1 *3	command source.
			2	Selects the PU connector as the PU operation mode
				command source.
			3 *4	Selects the USB connector as the PU operation mode
				command source.
	PU mode operation	FR-A700/F700 : 2	4 *5	Selects the operation panel as the PU operation mode
<b>551</b> ∗2	command source	FR-D700/E700 :	<del>т</del> 5	command source.
	selection	9999		FR-D700: Parameter unit automatic recognition
				FR-E700: USB automatic recognition
				When USB is connected, USB is the command
			9999 *5	source.
				Normally, operation panel is the command source. When the
				parameter unit is connected to the PU connector, PU is the
				command source.

\*1 When "1" (Modbus-RTU protocol) is set in Pr. 549, the setting range within parenthesis is applied.

\*2 Pr. 551 is always write-enabled.

\*3 Available for FR-A700, F700.

\*4 Available for FR-A700, E700.

\*5 Available for FR-D700, E700.





 Always reset the inverter after making the setting of the parameters. After you have changed the communicationrelated parameters, communication cannot be made until the inverter reset.

#### 1.4.4 Connection of multiple inverters using RS-485 terminal

RS-485 terminal is used for connecting multiple inverters with RS-232C port of a computer. Up to 32 inverters can be connected. RS-232C/RS-485 converter (*Refer to page 16*) is required. (FR-E700 series requires control terminal option FR-E7TR.)



#### (1) Wiring

The following indicates connection diagram of the multiple inverters. Refer to the inverter manual for details.



\*1Make connection in accordance with the instruction manual of the computer to be used with.

Fully check the terminal numbers of the computer since they change with the model.

\*2For the inverter farthest from the computer, set the terminating resistor switch to ON (100 $\Omega$  position).

#### (2) Related parameters for multiple connection using RS-485 terminal

Set the following communication parameter when connecting RS-485 terminal of the inverter.

When performing parameter writing or run command input, set the following command source parameters, and switch the operation mode to the following operation mode.

Invertor	Communication	Parameter Setting			
inverter	Option	Communication Parameter	Command Source Parameter	Mode	Ч
FR-A700, F700	No	Set the station number of the each inverters in <i>Pr</i> : 331 <i>RS</i> -485 communication station number (when connecting multiple inverters) <i>Pr</i> 336 <i>RS</i> -485 communication check time interval $\neq$ "0"	Initial value	NET	OUTLIN
	Yes	<pre>(initial value 0) Pr. 337 RS-485 communication waiting time setting = "9999" (initial value)</pre>	<i>Pr. 551 PU mode operation</i> <i>command source selection</i> = "1" (initial value 2)	PU	
	No	Set the station number of the each inverters in Pr. 117 PU communication station number (when connecting multiple inverters) Pr. 122 PU communication check time interval $\neq$ "0"	Initial value	NET	
FR-E700	Yes	<pre>(initial value 0) Pr. 123 PU communication waiting time setting ≠ "9999" (initial value)</pre>	Pr. 551 PU mode operation command source selection = "2" (initial value 9999)	PU	

#### REMARKS

Switching of the operation mode is available at "Test Operation" window (*Refer to page 90*) in Navigation area. Set 3s or more (or 9999) in *Pr. 122 PU communication check time interval*, *Pr. 336 RS-485 communication check time interval*. Set a station number of the each inverters in *Pr. 117 PU communication station number*, *Pr. 331 RS-485 communication station number* when connecting multiple inverters.

Parameter Number	Name	Initial Value	Setting Range	Description
117	PU communication station number	0	0 to 31 (0 to 247) *1	Inverter station number specification Set the inverter station numbers when two or more inverters are connected to one personal computer.
			0	RS-485 communication can be made. Note that a communication fault (E.PUE) occurs as soon as the inverter is switched to the operation mode with control source.
122	PU communication check time interval	FR-A700/F700 : 9999 FR-E700 : 0	0.1 to 999.8s	Communication check (signal loss detection) time interval If a no-communication state persists for longer than the permissible time, the inverter will come to trip (depends on $Pr: 502$ ).
			9999	No communication check (signal loss detection).
123	PU communication	9999	0 to 150ms	Set the waiting time between data transmission to the inverter and response.
	waiting time setting		9999	Set with communication data.
<b>331</b> ∗₃	RS-485 communication station number	0	0 to 31 (0 to 247) *1	Set the inverter station number. Set the inverter station numbers when two or more inverters are connected to one personal computer.
220	RS-485	<u>.</u>	0	RS-485 communication is enabled. However, the inverter will come to trip if operation is changed to NET operation mode.
330 *3	communication check time interval	US	0.1 to 999.8s	Set the interval of communication check (signal loss detection) time. (same specifications as <i>Pr. 122</i> )
<b>337</b> ∗₃	RS-485 communication waiting time setting	9999	0 to 150ms, 9999	Set the waiting time between datatransmission to the inverter and response. (same specifications as <i>Pr. 123</i> )
			1 *3	Selects the PU connector as the PU operation mode command source.
			2	Selects the PU connector as the PU operation mode command source.
<b>551</b> to	PU mode operation	FR-A700/F700 : 2	3 *4	Selects the USB connector as the PU operation mode command source.
551 -2	selection	FR-E700 : 9999	4 *5	Selects the operation panel as the PU operation mode command source.
			9999 *5	USB automatic recognition Normally, operation panel is the command source. When the parameter unit is connected to the PU connector, PU is valid. When USB is connected, USB is the command source.

\*1 When "1" (Modbus-RTU protocol) is set in Pr. 549, the setting range within parenthesis is applied.

\*2 Pr: 551 is always write-enabled.

\*3 Available for FR-A700, F700.

\*4 Available for FR-A700, E700.

\*5 Available for FR-E700.



#### Note

 Always reset the inverter after making the setting of parameters. After you have changed the communication-related parameters, communication cannot be made until the inverter reset.

#### 1.4.5 Connection through GOT (FA transparent function)

Using FA transparent function of GOT1000 series, connecting inverter to FR Configurator is available through GOT (up to 10 inverters).

FA transparent function enables reading, writing and monitoring of programmable controller of Mitsubishi Electric Corporation through GOT, while connecting Mitsubishi programmable controller and PC.

RS-232C or USB is used for connecting between FR Configurator and GOT. RS-422 is used for connecting between GOT and inverter.

[Example of RS-485 terminal connection]



#### [Example of PU connector connection (FR-E700)]



GOT RS-422 communication unit (GT15-RS4-9S) is required. When using USB for connecting with GOT, use dedicated cable GT09-C30USB-5P or GT09-C20USB-5P.

Refer to GOT1000 series connection manual for details of RS-422 connection and compatible version of GOT.



#### Note

Do not perform the following operation during FA transparent function is valid and FR Configurator is ONLINE.
 Online operation (project download, etc.) from GT Designer/GT Designer2 to GOT
 Online operation to programmable controller CPU by using FA transparent function of GX Developer

When using FA transparent communication, communication error (Time Out) may occur when FR Configurator starts communication during Time Out occurrence in GOT (when GOT is monitoring the inverter which is not connected). In that case, set the Time Out value more than the following. (*Refer to page 45*)

Time Out value of GOT[s] x (Retry count of GOT + 1) x 3 x 1000[ms] (500ms increments)

If the value above is more than 30[s], make adjustment to "Time Out value"[s] and "Retry count" of GOT to make the value above become less than 30[s]. *Refer to page 45* for communication setting.

OUTLINE

#### 🏹 Connection and Parameter Setting

(1) Related parameter for connection of multiple inverters through GOT

Check a connection between the inverter and GOT, and set the following communication parameter when connecting through GOT.

When performing parameter writing or run command input, set the following command source parameters, and switch the operation mode to the following operation mode.

Invertor	Communication Bort	Param	neter Setting	Operation
inverter	Communication Fort	Communication Parameter	Command Source Parameter	Mode
	PU connector	Pr: 122 PU communication check time interval $\neq$ "0" (initial value 0) Pr: 123 PU communication waiting time setting = "0" (initial value 9999)	Initial value	PU
FR-A700, F700	RS-485 terminals (Without communication option)	Set the station number of the each inverters in <i>Pr. 331 RS-485</i> <i>communication station number</i> (when connecting multiple inverters)	Initial value	NET
	RS-485 terminals (With communication option)	Pr. 336 RS-485 communication check time interval $\neq$ "0" (initial value 0) Pr: 337 RS-485 communication waiting time setting = "0" (initial value 9999)	<i>Pr. 551 PU mode operation command source</i> <i>selection</i> = "1" (initial value 2)	PU
FR-D700	PU connector		Initial value	NET
	PU connector (Without communication option)	Set the station number of the each inverters in <i>Pr. 117 PU</i> <i>communication station number (when</i>	Initial value	NET
FR-F700	PU connector (With communication option)	<i>Pr. 122 PU communication check time</i> <i>interval</i> ≠ "0" (initial value 0)	Pr. 551 PU mode operation command source selection = "2" (initial value 9999)	PU
	RS-485 terminal block (Without communication option)	<i>Pr. 123 PU communication waiting time setting</i> = "0" (initial value 9999)	Initial value	NET
	RS-485 terminal block (With communication option)		Pr: 551 PU mode operation command source selection = "2" (initial value 9999)	PU

## 

Switching of the operation mode is available at "Test Operation" window (Refer to page 90) in Navigation area.

Set the station number of the each inverters in *Pr. 117 PU communication station number*, *Pr.331 RS-485 communication station number* when connecting multiple inverters. Perform inverter reset after setting the parameter.

Parameter			Setting	<b>_</b>
Number	Name	Initial Value	Range	Description
117	PU communication station number	0	0 to 31 (0 to 247) *1	Inverter station number specification Set the inverter station numbers when two or more inverters are connected to one personal computer.
			0	RS-485 communication can be made. Note that a communication fault (E.PUE) occurs as soon as the inverter is switched to the operation mode with control source.
122	PU communication check time interval	0	0.1 to 999.8s	Communication check (signal loss detection) time interval If a no-communication state persists for longer than the permissible time, the inverter will come to trip (depends on <i>Pr</i> : <i>502</i> ).
			9999	No communication check (signal loss detection).
123	PU communication	9999	0 to 150ms	Set the waiting time between data transmission to the inverter and response.
	waiting time setting		9999	Set with communication data.
<b>331</b> ∗₃	RS-485 communication station number	0	0 to 31 (0 to 247) *1	Set the inverter station number. Set the inverter station numbers when two or more inverters are connected to one personal computer.
	RS-485		0	RS-485 communication is enabled. However, the inverter will come to trip if operation is changed to NET operation mode.
<b>336</b> ∗₃	communication	0s	0.1 to	Set the interval of communication check (signal loss
	check time interval		999.8s	detection) time. (same specifications as <i>Pr. 122</i> )
	D0 405		9999	No communication check (signal lossdetection)
<b>337</b> ∗₃	RS-485 communication waiting time setting	9999	0 to 150ms, 9999	Set the waiting time between data transmission to the inverter and response. (same specifications as <i>Pr. 123</i> )
			1 *3	Selects the RS-485 terminal as the PU operation mode command source.
			2	Selects the PU connector as the PU operation mode command source.
			3 *4	Selects the USB connector as the PU operation mode command source.
<b>551</b> ∗2	PU mode operation command source	FR-A700/F700 : 2 FR-D700/E700 :	4 *5	Selects the operation panel as the PU operation mode command source.
	selection	9999	9999 *5	FR-D700: Parameter unit automatic recognition FR-E700: USB automatic recognition When USB is connected, USB is the command source. Normally, operation panel is the command source. When the parameter unit is connected to the PU connector, PU is the command source.

\*1 When "1" (Modbus-RTU protocol) is set in Pr. 549, the setting range within parenthesis is applied.

\*2 Pr. 551 is always write-enabled.

\*3 Available for FR-A700, F700.

\*4 Available for FR-A700, E700.

\*5 Available for FR-D700, E700.



Note

 Always reset the inverter after making the setting of the parameters. After you have changed the communication-related parameters, communication cannot be made until the inverter reset.

OUTLINE

### **1.5 Setting of Operation Mode of the Inverter**

#### 1.5.1 Operation mode setting

The inverter has three operation modes.

- (1) PU operation [PU]..... Controls the inverter from the key of the control panel (FR-DU07) mounted on the inverter.
- (2) External operation [EXT] ...... Controls the inverter by switching on/off external signals connected to the control circuit
- (3) Network operation [NET] ....... Controls the inverter with instructions from the network via the communication option. (The operation signal and running frequency can be entered from the control circuit terminals depending on the *Pr. 338 Communication operation command source* and *Pr. 339 Communication speed command source* setting.)

Pr. 79 Setting	Operation Mode at Power on or Power Restoration Operation Mode	Operation Mode Switchover
0 (initial value)	External operation mode	Switching among the external, PU, and NET operation mode is enabled 1
1	PU operation mode	PU operation mode fixed
2	External operation mode	Switching between the external and NET operation mode is enabled Switching to PU operation mode is disabled
3, 4	External/PU combined operation mode	Operation mode switching is disabled
6	External operation mode	Switching among the external, PU, and NET operation mode is enabled while running.
7	X12 (MRS) signal ONexternal operation mode	Switching among the external, PU, and NET operation mode is enabled +1
/	X12 (MRS) signal OFFexternal operation mode	External operation mode fixed (Forcibly switched to external operation mode)

\*1 Operation mode can not be directly changed between the PU operation mode and network operation mode.



\* When using USB connection, operation mode changing is available from FR Configurator. (Refer to page 90)

Setting of Operation Mode of the Inverter

Refer to the following table to select the appropriate operation mode for the connection. Switching of the operation mode is available at "Test Operation" window (*Refer to page 90*) in Navigation area. Refer to the inverter manual (applied) for details of each parameters.

Controllability through communcation

·Monitoring and parameter read can be performed from any operation regardless of operation mode.

•FR-A700, F700 series

Operation Location	Condition (Pr. 551 Setting)	Operation Mode Item	PU Operation	External Operation	External/PU Combined Operation Mode 1 ( <i>Pr. 79</i> = 3)	External/PU Combined Operation Mode 2 ( <i>Pr. 79</i> = 4)	NET Operation (when RS-485 terminals are used) *6	NET Operation (when communication option is used) *7
5		Run command (start)	0	×	×	0		×
ecto		Run command (stop)	0	∆ *3	∆ *3	0	4	∆ *3
J conne	2	Running frequency setting	0	×	0	×		×
٦PL	(PU	Monitor	0	0	0	0		0
fron	connector)	Parameter write	O *4	X *5	O *4	O *4	:	× *5
tion		Parameter read	0	0	0	0		0
nica		Inverter reset	0	0	0	0		0
nmn		Run command (start)	×	×	×	×		×
con		Run command (stop)	∆ *3	∆ *3	∆ *3	∆ *3	4	∆ *3
S-485		Running frequency setting	×	×	×	×		×
y R	Except for 2	Monitor	0	0	0	0		0
rolt		Parameter write	× *5	× *5	X *5	X *5	:	≺ *5
Cont		Parameter read	0	0	0	0		0
		Inverter reset	0	0	0	0		0
		Run command(start, stop)	0	×	×	0		×
	1	Running frequency setting	0	×	0	×		×
тот	(RS-485	Monitor	0	0	0	0		0
on f	terminals)	Parameter write	O *4	X *5	O *4	O *4	:	≺ *5
icati		Parameter read	0	0	0	0		0
mun term		Inverter reset	0	0	0	0		0
y comi S-485 t		Run command (start, stop)	×	×	×	×	O *1	×
ntrol b RS		Running frequency setting	×	×	×	×	O *1	×
Õ	Except for 1	Monitor	0	0	0	0	0	0
		Parameter write	X *5	X *5	X *5	× *5	O *4	× *5
		Parameter read	0	0	0	0	0	0
		Inverter reset	×	×	×	×	O *2	×

OUTLINE

#### 7 Setting of Operation Mode of the Inverter

Operation Location	Condition (Pr. 551 Setting)	Operation Mode Item	PU Operation	External Operation	External/PU Combined Operation Mode 1 (Pr. 79 = 3)	External/PU Combined Operation Mode 2 ( <i>Pr. 79</i> = 4)	NET Operation (when RS-485 terminals are used) *6	NET Operation (when communication option is used) *7
		Run command (start, stop)	0	×	×	0		×
8*	2 (1100	Running frequency setting	0	×	0	×		×
ector	3 (USB connector)	Monitor	0	0	0	0	0	
onne	connector)	Parameter write	O *4	X *5	X *5	X *5	× *5	
SB C		Parameter read	0	0	0	0		0
e US		Inverter reset	0	0	0	0		0
om the		Run command (start, stop)	×	×	×	×		×
ation fr		Running frequency setting	×	×	×	×		×
pera	Except for 3	Monitor	0	0	0	0		0
0		Parameter write	X *5	X *5	X *5	X *5	;	< *5
		Parameter read	0	0	0	0		0
		Inverter reset	0	0	0	0		0

 $\bigcirc$ : Enabled,  $\times$ : Disabled,  $\triangle$  : Some are enabled

\*1 As set in Pr. 338 Communication operation command source and Pr. 339 Communication speed command source. (Refer to the inverter Instruction Manual )

\*2 At occurrence of RS-485 communication error, the inverter cannot be reset from the computer.

\*3 Enabled only when stopped by the PU. At a PU stop, PS is displayed on the operation panel. As set in *Pr. 75 Reset selection/disconnected PU detection/PU stop selection. (Refer to the inverter Instruction Manual )* 

\*4 Some parameters may be write-disabled according to the Pr. 77 Parameter write selection setting and operating status. (Refer to the inverter Instruction Manual )

\*5 Some parameters are write-enabled independently of the operation mode and command source presence/absence. When *Pr*: 77 = 2, write is enabled. (*Refer to the inverter Instruction Manual*) Parameter clear is disabled.

\*6 When *Pr. 550 NET mode operation command source selection* = 1 (RS-485 terminals valid) or *Pr. 550 NET mode operation command source selection* = 9999 and the communication option is not fitted.

\*7 When *Pr. 550 NET mode operation command source selection* = 0 (communication option valid) or *Pr. 550 NET mode operation command source selection* = 9999 and the communication option is fitted.

\*8 FR-A700 series only.

#### •FR-D700 series

Operation Location	Condition (Pr. 551 Setting)	Operation Mode Item	PU Operation	External Operation	External/PU Combined Operation Mode 1 ( <i>Pr. 79</i> = 3)	External/PU Combined Operation Mode 2 ( <i>Pr. 79</i> = 4)	NET Operation
		Run command (start)	0	×	×	0	×
		Run command (stop)	0	∆ *3	△ *3	0	×
Control by	2 (PU connector)	Running frequency setting	0	×	0	×	×
RS-485		Parameter write	O *4	× *5	O *4	O *4	× *5
communica		Inverter reset	0	0	0	0	×
tion from		Run command (start)	×	×	×	×	O *1
PU		Run command (stop)	×	×	×	×	O *1
connector	Other than the above	Running frequency setting	×	×	×	×	O *1
		Parameter write	× *5	× *5	× *5	× *5	O *4
		Inverter reset	×	×	×	×	O *2
Control		Inverter reset	0	0	0	0	0
circuit external	_	Run command (start, stop)	×	0	0	×	× *1
terminals		Frequency setting	×	0	∆ *6	0	× *1

#### O: Enabled, $\times:$ Disabled, $\bigtriangleup:$ Some are enabled

\*1 As set in Pr.338 Communication operation command source and Pr. 339 Communication speed command source (Refer to the inverter Instruction Manual )

\*2 At occurrence of RS-485 communication error, the inverter cannot be reset from the computer.

\*3 Enabled only when stopped by the PU. At a PU stop, PS is displayed on the operation panel. As set in *Pr. 75 PU stop selection. (Refer to the inverter Instruction Manual )* 

 \*4 Some parameters may be write-disabled according to the *Pr. 77 Parameter write selection* setting and operating status. (*Refer to the inverter Instruction Manual*)
 \*5 Some parameters are write-enabled independently of the operation mode and command source presence/absence. When *Pr. 77* = "2", write is enabled. (*Refer to the inverter Instruction Manual*) Parameter clear is disabled.

\*6 Available with multi-speed setting and terminal 4-5 (valid when AU signal is ON).

#### •FR-E700 series

Operation Location	Condition (Pr. 551 Setting)	Operation Mode Item	PU Operation	External Operation	Exrnal/PU Combined Operation Mode 1 (Pr. 79 = 3)	Exrnal/PU Combined Operation Mode 2 (Pr. 79 = 4)	NET Operation (when using PU connector) *6	NET Operation (when using communication option) *7
ion		Run command (Start, stop)	0	∆ *3	∆ *3	0	Δ	*3
nunicat or	2 (PU	Running frequency setting	0	×	0	×	>	<
omn	connector)	Parameter write	O *4	X *5	O *4	O *4	×	*5
5 cc		Inverter reset	0	0	0	0	C	)
RS-48 m PU o		Run command (Start, stop)	×	×	×	×	O *1	×
fro fro	Other than the above	Running frequency setting	×	×	×	×	O *1	×
Cor		Parameter write	X *5	X *5	X *5	X *5	O *4	× *5
		Inverter reset	×	×	×	×	O *2	×
tor	3 (USB	Run command (Start, stop)	0	×	×	0	>	<
connec	connector) 9999	Running frequency setting	0	×	0	×	>	<
SB	(automatic	Parameter write	O *4	X *5	X *5	X *5	×	*5
e	recognition)	Inverter reset	0	0	0	0	C	)
from th		Run command (Start, stop)	×	×	×	×	>	<
eration	Other than the above	Running frequency setting	×	×	×	×	>	<
Ope		Parameter write	× *5	X *5	× *5	X *5	×	*5
		Inverter reset	0	0	0	0	C	)
ation option		Run command (Start, stop)	×	×	×	×	×	O *1
mmunic ication		Running frequency setting	×	×	×	×	×	O *1
ommun	_	Parameter write	★ *5	X *5	X *5	X *5	× *5	O *4
Contro from o		Inverter reset	×	×	×	×	×	O *2

O: Enabled, ×: Disabled, △: Some are enabled

\*1 As set in *Pr. 338 Communication operation command source*, *Pr. 339 Communication speed command source* 

\*2 At occurrence of RS-485 communication error from PU connector, the inverter cannot be reset from the computer.

\*3 Enabled only when stopped by the PU At a PU stop, PS is displayed on the operation panel. As set in Pr. 75 PU stop selection.

\*4 Some parameters may be write-disabled according to the Pr. 77 Parameter write selection setting and operating status.

\*5 Some parameters are write-enabled independently of the operation mode and command source presence/absence. When *Pr*: 77 = 2, write is enabled. Parameter clear is unavailable.

\*6 When *Pr. 550 NET mode operation command source selection* = "2" (PU connector valid) or *Pr. 550 NET mode operation command source selection* = "9999" and the communication option is not fitted.

\*7 When *Pr. 550 NET mode operation command source selection* = "0" (communication option valid) or *Pr. 550 NET mode operation command source selection* = "9999" and the communication option is fitted.

#### **1.6 Start and Close**

#### 1.6.1 Starting FR Configurator

There are following ways to start FR Configurator.

#### (1) Start from Start menu

Click [Start] on the Taskbar of Windows, and point to [All Programs], [MELSOFT Application], [FR Configurator], [SW3 (700 Series)], and click [FR Configurator SW3] to start FR Configurator.

All <u>P</u> rograms 🏓	💼 MELSOFT Application 🔹 🕨	G	🖥 FR Configurator 🔸	🛅 SW3(E700 Series) 🔸	M	FR Configurator SW3
	Log Off 🚺 Tyrn Off Comput	er			ß	FR Configurator SW3 HELP
🏄 start						

#### (2) Start from system file (me3)

Double-click (or type Enter key) a desired system file (me3) to start FR Configurator with reading the setting of the system file. [Startup] window is not displayed. (*Refer to page 87* for system file (me3))

#### (3) Start from command line

Specify an executable file of FR Configurator (invsup3\_e.exe) to [Run...] window in the [Start] menu of Windows, to start FR Configurator.

	Type the name of a program, folder, document, or Internet resource, and Windows will open it for you.
Open:	C:\Program Files\MELSOFT\invsup3\invsup_e.exe

Specify the system file (me3) after the executable file, and the setting of the system file (me3) is read at the starting up of the software. "Startup" window is not displayed at starting up of the software when the system file (me3) is specified.



#### (4) Start from Windows Explorer

Select the executable file of FR Configurator (invsup3\_e.exe) by using Windows Explorer, and double-click (or type Enter key) to start FR Configurator.


#### 1.6.2 Start flow of FR Configurator

After starting FR Configurator, splash screen is displayed, and proceeds the starting up.





# **FR Configurator**



"Startup" windows is displayed when FR Configurator is started. Each functions can be directly selected from the "Startup"

window. (*Refer to page 42* for the detail of "Startup") Click **Startup** to close "Startup" window and switch to the main window of FR Configurator.



#### 1.6.3 Closing FR Configurator

There are following ways to close FR Configurator.

(1) Close from menu

Select [Exit] in [File] menu to close FR Configurator. (Typing Alt + F to open [File] menu, and type Ctrl + X also closes FR Configurator)

(2) Close from title bar

Click 🔀 on the right end of the title bar to close FR Configurator.

	Click to close
MI FF	Configurator SW3
	<b>REMARKS</b> If a system file (me3) is not saved yet when closing FR Configurator, a dialog box is displayed to confirm the closing.
	FR Configurator SW3       Save System File?       Yes     No       Cancel
	Click res to open "Save As" window for saving the system file (me3).
	Click <b>b</b> to close FR Configurator without saving the system file (me3).
	Click <b>cancel</b> to cancel the closing of FR Configurator, and switch to the Main frame window.

# **1.7 Explanation of Window**

The following describes FR Configurator window.

#### 1.7.1 Main frame

The Main frame (main window) of FR Configurator consists of 3 areas.

• Navigation area (Refer to page 34)

An area for showing information of the registered inverter, or for making settings. "Test Operation", "System Settings", "Setting Wizard", and "Troubleshooting" are available in this area.

- Monitor area (Refer to page 36)
   An area for showing obtained monitor data of inverter. "Graph", "I/O Terminal Monitor", "Machine Analyzer", "Batch Monitor" are available in this area.
- System area (Refer to page 35)

An area for showing and read/write parameters, or for converting from parameter setting of conventional model. "Parameter List", "Diagnosis" and "Convert" are available in this area.



#### • Explanation of Main frame

No.	Name	Function and description	Refer to
		IFD Configurator (WOI) is displayed on the title has If a system file has been read, or has	гауе
Α	Title bar	"FR Configurator SW3" is displayed on the title bar. If a system file has been read, or has	_
		been saved, the file name and file location is displayed.	
В	Menu bar	Each functions are available by selecting from the menu.	37
С	Tool bar	Each functions are available by clicking icons of the tool bar.	37
D	Status bar	A model name, Operating status, etc. are shown.	39
Е	Split line	Adjustment of System area size and Monitor area size is available.	—
F	Conceal button	Conceals the Monitor area and System area.	—
G	Minimize button	Minimizes the Main frame window size of FR Configurator.	—
Н	Maximize button	Maximizes the Main frame window size of FR Configurator.	_
I	Close button	Closes FR Configurator.	—



#### Detection of fault and communication error

FR Configurator checks operating status of connected inverter, and detects fault and communication error (*Refer to page 152*). If a fault or communication error is detected, a following dialog appears. Click to show a related Help information.



• When a fault is detected

Commur	nication Error
1	St. No. 0 Unable to connect to inverter properly. Communication Error Code: 0x80010101 Failed to make communication with the inverter during the time set with Time Out.

When a communication error is detected

#### 1.7.2 Navigation area

Navigation area is for showing registered inverter information, switching of operation mode and ONLINE/OFFLINE, sending of start/stop command, changing of the set frequency, or starting Setting Wizard. "Test Operation", "System Settings", "Setting Wizard" and "Troubleshooting" are available in this area.

Upper part of Navigation area displays "Test Operation" (*Refer to page 90*), and lower part displays "System View" (*Refer to page 94*).

Select [System Setting], [Setting <u>Wizard</u>] or [Troubleshooting] under [View] menu to switch the function displayed in "System View".



#### 1.7.3 System area

System area is for showing and reading/writing parameters, or for diagnosis and converting from parameter setting of conventional model. "Parameter List", "Diagnosis", and "Convert" are available in this area.

Select [Parameter List], [Diagnosis], or [Convert] under [View] menu, or click icons on the tool bar to switch the function displayed in System area.



#### 1.7.4 Monitor area

Monitor area is for showing obtained monitor data of inverter. "Graph", "I/O Terminal Monitor", "Machine Analyzer", and "Batch Monitor" are available in this area.

Select [Graph], [Machine Analyzer], [I/O Terminal Monitor], or [Batch Monitor] under [View] menu, or click an icon on the tool bar to display the function in System area.







Batch Monito

Graph (Refer to page 123)

Machine Analyzer (*Refer to page 142*)

I/O Terminal Monitor (Refer to page 140)





#### 1.7.5 Menu and Tool bar

Desired function is available by selecting them from the menu or the tool bar.

#### (1) Menu/Tool bar list

Following functions are available from the menu.

			Tool bar		Refer
Menu	Pull-do	wn menu		Function/Operation	to
			icon		Page
				Clears the all current settings to create a new setting.	
	<u>N</u> ew			Confirmation dialog for new setting appears, and then	30
			New	displays "Startup" window.	
	<u>O</u> pen		Dpen	Opens the system file (me3).	87
	<u>S</u> ave		L Save	Overwrites the system file (me3) by current data. When the system file (me3) has not been read or not created yet, then "Save As" window is displayed, and saving of the system file is available.	87
<u>F</u> ile	Save <u>A</u> s		—	Puts a name and creates a new system file (me3) from the current setting.	87
	P <u>r</u> operty		—	Checks and edits system name, application and comments.	44
				Imports an exported saved file of the currently using function.	
	Import		—	Confirmation dialog for erasing the current data appears, and	88
				then the import window is displayed.	
	Export		—	Exports the data of currently using function and creates a file.	88
	<u>P</u> rint		en e	Prints a whole window.	89
	E <u>x</u> it		—	Closes FR Configurator.	—
	Graph		Craph	Displays "Graph" window in Monitor area.	123
	I/O Terminal Monitor		 I∕O Terminal Monitor	Displays "I/O Terminal Monitor" window in Monitor area.	140
	Machine Analyz	er	—	Displays "Machine Analyzer" window in Monitor area.	142
	Batch Monitor		Batch Monitor	Displays "Batch Monitor" window in Monitor area.	138
<u>V</u> iew	Parameter List		Parameter List	Displays "Parameter List" window in System area.	97
	Di <u>a</u> gnosis		Vy Diagnosis	Displays "Diagnosis" window in System area.	121
	<u>C</u> onvert		—	Displays "Convert" window in System area.	104
		S <u>y</u> stem Setting	_	Displays "System Setting" window in System View of Navigation area.	95
	Na <u>v</u> igation	Tro <u>u</u> bleshooting	_	Displays "Troubleshooting" window in System View of Navigation area.	65
		Setting Wizard	—	Displays "Setting Wizard" in System View of Navigation area.	96
		Test Operation	—	Displays or hides the command sending part of "Test Operation".	90
Tool	Model Setting		—	Displays "Model Setting" window.	84
1001	Options		—	Displays "Option" window.	85
<u>H</u> elp	<u>H</u> elp		<b>?</b> Help	Displays "Help" window.	147
	About FR Configurator SW3		—	Displays "About FR Configurator SW3" window.	149

# OUTLINE

#### 💙 Explanation of Window

#### (2) [View] menu and Main frame

Each function screen of FR Configurator is displayed from [View] menu. Inside of [View] menu is divided into 3 segments. Function screen in Monitor area from above, and screen in System area, screen in Navigation area follows.



A check mark appears on a left of the item inside the [View] menu for each screen displayed in each area. One function each from Monitor area, System area and Navigation area can be displayed. Check on the [Test Operation] under [Navigation] menu to display the command sending part of "Test Operation".



Click and uncheck the checked item of the currently displaying function to hide. To hide Navigation area itself, click and uncheck the item of the System View under [Navigation] menu.

When a function in Monitor area is performing monitoring, all functions in Monitor area are unavailable. Stop the monitoring, and then select a menu.

#### REMARKS

- Depending on connected inverter, with or without of Model Setting, or ONLINE/OFFLINE condition, some functions are unavailable. If an item in menu is displayed in gray, the item is unavailable.
- When functions in both Monitor area and System area are checked, click and uncheck the one of them will maximize the window size of another.



#### 1.7.6 Status bar

 Operation Mode
 PU
 Operating Status
 Stop
 Model
 FR-E720-0.1K
 Comment
 Conveyor1

 A
 B
 C
 D
 E

Status bar shows operation mode of the inverter and model information etc.

No.	Name	Function and description
		Shows the operation mode of the selected inverter (station).
		When model setting (system setting) has not made, "" is displayed.
Α	Operation Mode	At an occurrence of warning, both operation mode and warning are displayed.
		Example:Stall prevention (overcurrent) occurred at external operation mode
		"EXT(OL)"
В	Operating Status	Shows the operating status of the selected inverter (station).
С	Model	Shows a model of the selected inverter (station).
D	Comment	Shows a comment.
F	Programmable Controller	Show the programmable controller status of the selected inverter (station)
	Status	

#### 1.7.7 Communication manager

When FR Configurator is started, an icon appears at Windows taskbar indicating communication state. When FR Configurator is closed, the icon disappears.



The icon displays ONLILNE/OFFLINE status of FR Configurator.

Indication	Status	Connection
	OFFLINE	_
		RS-232C connection(Blue) RS-232C connection through GOT(Blue)
		USB connection (Green) USB connection through GOT(Green)

# MEMO



This chapter explains the "Startup" and "Easy Setup" of this product.

Always read the instructions before using the software.

2.1	Startup 4	2
2.2	Easy Setup4	3



42

# 2.1 Startup

"Startup" windows is displayed when FR Configurator is started. Each functions can be directly selected from the "Startup" window.



No.	Name	Function and description
		Shows up to 5 recent used files.
Α	Open	Point a cursor on "Open File", and 5 recent used files are shown. Click the file name, then "Startup"
		window is closed, and Main frame is displayed with the file contents reflected.
		Click to start Easy Setup.
В	Easy Setup	From System Property setting to Model setting and parameter setting, the setting up is easily made
		with wizard style (interactive). (Refer to page 43)
С	Functions	Shows a list of functions.
D	Help	Displays Help window. (Refer to page 147)
Е	Cancel	Click to close this window, and returns to Main frame.

#### 2.2 Easy Setup

Setting from system setting to parameter setting is easily made with Easy Setup. Even without FR Configurator knowledge, without regard to the parameter number, system setting and basic parameter setting is easily made.



#### 

When <u>cancel</u> is clicked in each setting screen, the setting input made so far becomes invalid, and the window returns to "Startup".

(Communication setting is saved even when **Cancel** is clicked.)

2

# ZEasy Setup

#### 2.2.1 System Property

Input an information for creating system file.

Type a system name (up to 32 one byte characters) for this system file. Click \_\_\_\_\_\_ after input the system name. When \_\_\_\_\_\_ is clicked, the screen proceeds to "Communication Setting".

4 <b></b>	->System Property Communication Setting Inverter Setting Method Automatic Detection Model Setting Inverter Selection Control Method Motor Setting Start Command and Frequency Goed Setting Method Parameter List	System File Property Type System Name Type machine name, application or etc. in Comment field, as required. System Name Inverter System	——— E
		Help Cancel (Back Next) Emith	

No.	Name	Function and description
Α	Setting procedure	Shows description of current setting and next/previous setting in Easy Setup.
В	System Name	Type a system name up to 32 one byte characters.
С	Comment	A field for comments (up to 256 one byte characters) to describe the system.
D	<u>N</u> ext>	Proceeds to "Communication Setting" (Refer to page 45).
Е	Cancel	Closes Easy Setup with the setting made invalid.
F	Help	Displays Help window. (Refer to page 147)

#### 2.2.2 Communication Setting

Make a communication setting between a personal computer and inverter.

When communicating with inverter using an USB port of the personal computer, select "USB" in "PC side <u>P</u>ort" field, and click

When communicating with inverter using a RS-232C of the personal computer, select "RS-232C" in "PC side Port" field.

# 

Default communication setting is matching to an initial value of inverter.

Check the personal computer side port (RS-232C/USB) and personal computer port number (1 to 63).



No.	Name	Initial	Function and description
		value	
^	PC side Port	RS-	Select the communication port from RS-232C or USB.
~		232C	
В	Port Number	1	Select the personal computer communication port number. (Refer to page 46)
С	T <u>h</u> rough		Select when connecting through GOT.
D	Communication Speed	19200	Set the communication speed. (Refer to Pr. 118, Pr. 332)
Е	Data <u>L</u> ength	8	Set the data bit length. (Refer to Pr. 119, Pr. 333)
F	Pa <u>r</u> ity	Even	Specify the parity bit. (Refer to Pr. 120, Pr. 334)
G	<u>S</u> top Bit	2	Set the stop bit length. (Refer to Pr. 119, Pr. 333)
н	Delimi <u>t</u> er	CR	Specify the delimiter of the data end. (Refer to Pr. 124, Pr. 341)
I	Advanced		Displays "Advanced" window. Setting of TimeOut and Retry Count is available.
J	Default <u>V</u> alue		Restores default value of communication setting.
К	<u>N</u> ext >		Proceeds to "Inverter Setting Method" (Refer to page 47).
L	< <u>B</u> ack		Returns to "System Setting" (Refer to page 44).
М	Cancel		Closes Easy Setup with the setting made invalid.
N	Help		Displays Help window. (Refer to page 147)

#### () REMARKS

- When "USB" is selected for personal computer side port, unnecessary setting item turns to gray and unavailable for making setting.
- Communication Setting is also available from [Option] in a [Tool] menu.
- Refer to the inverter manual for details of the parameters.

2

#### REMARKS

The communication port can be checked by the following procedure.

- Click [Start] of the Taskbar of Windows, and point to [All Programs], point to [Accessories], point to [System Tools], and then click [System Information]. [System Information] window shown on the right is displayed.
- 2. Select [Serial] in [Port] folder of [Component] in the left pane.
- 3. Check the [COM] number of "Communication port" displayed in the right pane.
  - Example: "1" for "Communication port (COM1)"
- 4. Set the confirmed value to the "Port Number" of B.

System Summary Andread System Summary System Summary System Summary System Syst	Item Name Status	Value Communications Port (CDM1)	^
Hardware Resources     Components     Multimedia     CD-RDM	Name Status	Communications Port (COM1)	
Sound Device Display Infrared	PMI/ Denote ID Meaimum injord Buffer Size Meaimum Output Buffer Size Settable Baux II Alar Settable Party Settable Party Settable Party Settable Party Settable Party Settable Party Settable Size Bau Settable PLSD Supports II SB Mode Supports II Bit Mode Baux Rate Baux Rate	DK ALCHYPHPOS0111 0 Ves Yes Yes Yes Yes Yes Yes No No 8600 8	
- Problem Devices	Stop Bits	1	

#### (1) Advanced

Click <u>Advanced</u> to display "Advanced" window.



No	Namo		Eurotion and description
NO.	Naille	Initial	
			Set a time between personal computer sends a data for inverter, and then personal computer
Α	Time Out *	100ms	receives a reply. When there is no reply after the set time, "Time Out Occurrence" error
			dialog appears.
В	Retry Count	1	Set the number of retries.
C	сок		Returns to "Communication Setting" window with the setting in "Advanced" window made
C			valid.
D	Cancel		Returns to "Communication Setting" window with the setting made invalid.
Е	Help		Displays Help window. (Refer to page 147)

\*1 When connecting with FA transparent function, set the time-out value in 500ms increments (Example: 500 / 1000 / 1500 /... / 30000).

#### **REMARKS**

 $\mathbf{0}$ 

FR Configurator sends a data with 100ms interval, for the operation mode and error checking. Set 3s or more (or 9999) for communication check time interval setting of the inverter (*Pr. 122 or Pr. 548*). If the value less than 3s is set, the inverter may come to trip. (*Refer to page 12, 16*)

#### 2.2.3 Inverter Setting Method

Select inverter setting method between automatic recognition of the connected inverter, or manually model setting for this system.



No.	Name	Function and description
А	Perform <u>A</u> utomatic Recognition of the Connected Inverter	Choose "Perform <u>A</u> utomatic Recognition of the Connected Inverter" and click <u>Next</u> to automatically detect the connected inverter. After finishing the automatic detection of the inverter, the window proceeds to "Inverter Selection" ( <i>Refer to page 50</i> )
в	Perform Model Setting <u>M</u> anually	Make the model setting manually. (Refer to page 49)
с	<u>N</u> ext>	When "Perform <u>A</u> utomatic Recognition of the Connected Inverter" is selected, the window proceeds to "Automatic Detection" ( <i>Refer to page 48</i> ). If "Perform Model Setting <u>M</u> anually" is selected, the window proceeds to "Model Setting" ( <i>Refer to page 49</i> ).
D	< <u>B</u> ack	Returns to "Communication Setting" (Refer to page 45).
E	Cancel	Closes Easy Setup with the setting made invalid.
F	Help	Displays Help window. (Refer to page 147)

#### 2.2.4 Automatic Detection

Click start to detect inverter of which communication is available.



No.	Name	Function and description
Α	Message area	Shows a state of automatic detection. When an inverter is detected, the color turns blue, and shows a result of detection. (If an error occurred during automatic detection, the color turns red, and shows error description.)
в	Detection Results	Shows a result of automatic detection. A station during detecting is displayed in blue. And when an inverter is detected, inverter model name is displayed. (For a station failed for detection, the color turns red, and shows error code. <i>Refer to page 152</i> for the error code)
С	<u>S</u> tart	Starts automatic detection when clicked.
D	Abort	Aborts automatic detection.
Е	<u>N</u> ext>	Proceeds to "Inverter Selection" (Refer to page 50).
F	< <u>B</u> ack	Returns to "Inverter Setting Method" (Refer to page 47).
G	Cancel	Closes Easy Setup with the setting made invalid.
Н	Help	Displays Help window. (Refer to page 147)

#### 2.2.5 Model Setting

Make the inverter model setting manually.



No.	Name	Function and description
Α	St. <u>N</u> o.	Set the inverter station number from 0 to 31.
В	C <u>o</u> mment	A field for comments.
С	In <u>v</u> erter	Select the connected inverter model.
D	<u>C</u> apacity	Select the connected inverter capacity.
F	Option Connector <u>1</u> to <u>3</u> ,	Select the option connected to an option connector of the inverter. (Option Connector 1 to 3 is available
-	Terminal Block 3	for FR-A700 series.)
F	<u>N</u> ext>	Proceeds to "Inverter Selection" (Refer to page 50).
G	< <u>B</u> ack	Returns to "Inverter Setting Method" (Refer to page 47).
н	Cancel	Closes Easy Setup with the setting made invalid.
Ι	Help	Displays Help window. (Refer to page 147)

#### **REMARKS**

"Model Setting" is also available from [Model Setting] in a [Tool] menu.

#### 2.2.6 Inverter Selection

Click Register System Setting to fix the system setting, and then parameter setting is available.

Choose an inverter (station number) for parameter setting, and click \_\_\_\_\_. After parameter setting is finished, the window returns to "Inverter Selection" again.

Click **Enish** to close Easy Setup, and proceeds to the Main frame window.

Stat Command and 00 FR-E720-011K
Control Method Motor Setting

No.	Name	Function and description
Α	Reflect Basic Setting	Reflects the system setting made in Easy Setting.
		Shows the inverter reflected into system setting. Choose a station number for parameter setting, and
в	Inverter selecting field	click <u>Next</u> . A check mark is displayed on the station number if the parameter setting has already made. (Click <u>Register System Setting</u> to fix the system setting first, and the field is available.)
С	<u>F</u> inish	Click to close Easy Setup, and proceeds to the Main frame window.
D	Next>	Proceeds to "Control Method" (Refer to page 51).
Е	< <u>B</u> ack	Returns to "Model Setting" (Refer to page 49) or "Automatic Detection" (Refer to page 48).
F	Cancel	Closes Easy Setup with the setting made invalid.
G	Help	Displays Help window. (Refer to page 147)

#### 2.2.7 Control Method

Set a control method of the inverter. Select the control method, and click \_\_\_\_\_.



No.	Name	Function and description
Α	Select a Control Method.	Select the control method.
В	Select a Control Mode	Select the control mode (speed, torque control). (FR-A700 only)
С	<u>N</u> ext>	Proceeds to "Motor Setting" (Refer to page 52).
D	< <u>B</u> ack	Returns to "Inverter Selection" (Refer to page 50).
Е	Cancel	Closes Easy Setup with the setting made invalid.
F	Help	Displays Help window. (Refer to page 147)

#### • Changing parameter

Parameters related to control method. (Refer to the inverter manual for details of the parameters.)

Parameter Number	Name
60	Energy saving control selection
80	Motor capacity
81	Number of motor poles
800	Control method selection

#### 2.2.8 Motor setting

Make a motor setting of the inverter. Click \_\_\_\_\_ after inputting the motor information.



No.	Name	Function and description
^	Applied Motor	Select a type of motor. Type of selectable motors are different according to the control method selected
~		in "Control Method" window (or Pr: 71 setting).
Б	Motor information	Fill in a motor information. Required motor information to fill in is different according to the control
Б		method setting selected in "Control Method" window.
С	Next>	Proceeds to "Start Command and Frequency (Speed) Setting Method" (Refer to page 53).
D	< <u>B</u> ack	Returns to "Control Method" (Refer to page 51).
Е	Cancel	Closes Easy Setup with the setting made invalid.
F	Help	Displays Help window. (Refer to page 147)

#### • Changing parameter

Parameters related to motor setting. (Refer to the inverter manual for details of the parameters.)

Parameter Number	Name
9	Electronic thermal O/L relay
71	Applied motor
80	Motor capacity
81	Number of motor poles
83	Rated motor voltage
84	Rated motor frequency

#### 2.2.9 Start Command and Frequency (Speed) Setting Method

Select an input method of start command and frequency (speed) setting.



No.	Name	Function and description
Α	Start Command Input	Select the start command input method of the inverter.
	Method	
в	Frequency (Speed)	Select the frequency (speed) setting input method of the inverter
Б	Setting Input Method	Select the frequency (speed) setting input method of the inverter.
С	<u>N</u> ext>	Proceeds to "Parameter List" (Refer to page 54).
D	< <u>B</u> ack	Returns to "Motor Setting" (Refer to page 52).
Е	Cancel	Closes Easy Setup with the setting made invalid.
F	Help	Displays Help window. (Refer to page 147)

#### • Changing parameter

Parameters related to "Start Command and Frequency (Speed) Setting Method". (Refer to the inverter manual for details of the parameters.)

Parameter	Namo	
Number	Name	
79	Operation mode selection	
338	Communication operation command source	
339	Communication speed command source	
340	Communication startup mode selection	

2

#### 2.2.10 Parameter List

After the required item is all set, parameter setting is configured based on the input setting. Parameter name and configured value is displayed in the Parameter List. To write the parameter setting to the inverter, write from the Parameter List in the Main frame. (*Refer to page 97*)

Click <u>lext</u> to return to "Inverter Selection" window *(Refer to page 50)*. To close Easy Setup, click <u>linish</u> in "Inverter Selection" window.



No.	Name	Function and description	
Α	Parameter setting field Shows the parameter setting configured by Easy Setup in the list.		
В	<u>N</u> ext>	Proceeds to "Inverter Selection" (Refer to page 50).	
С	< <u>B</u> ack	Returns to "Start Command and Frequency (Speed) Setting Method" (Refer to page 53).	
D	Cancel	el Closes Easy Setup with the setting made invalid.	
Е	Help	Displays Help window. (Refer to page 147)	



This chapter explains the "Setting Wizard" of this product. Always read the instructions before using the software.

3.1	Overview of Setting Wizard	. 56
3.2	Details of Setting Wizard	. 59
3.3	Troubleshooting	. 65
3.4	Details of troubleshooting	. 69



# 3.1 Overview of Setting Wizard

#### 3.1.1 Function outline

Setting Wizard can set parameters with wizard style dialog (interactive). Inputting or selecting required items for each function, and parameter setting can be made without regard to parameter number.

Double-click a desired function in the "Setting Wizard" (Refer to page 96) in System View (or select a function and click

**Execute**) to start the Setting Wizard of the selected function. Parameter setting is configured based on the input setting after the required item in each window is filled in. Configured parameter setting is displayed in Parameter List (*Refer to page 58*) when every setting is finished. Configured setting can be written to the inverter from Parameter List.

#### (1) Basic flow of Setting Wizard



#### (2) Functions available for Setting Wizard

Function Name	Setting Item	Refer to Page
Acceleration/deceleration pattern and time setting	Acceleration/Deceleration Pattern Adjustment of Acceleration/Deceleration Pattern (when backlash measures are selected for FR-A700, FR-F700) Acceleration/Deceleration Time	59
Output Terminal (FM, CA, AM) Calibration	Output Terminal (FM, CA, AM) Calibration	60
Analog Input Terminal Calibration	Calibrating Terminal and Method Calibration Method (1) Calibration Method (2)	61
Tuning	Control Method Motor Setting Tuning Method Tuning	63

#### 3.1.2 Individual setting window of Setting Wizard

Select a desired function of the "Setting Wizard" (*Refer to page 96*) in System View, and start the Setting Wizard. Input or select in a required field of each individual setting window, and click Number of the items required to fill in is different according to the selected Setting Wizard.



No.	Name	Function and description
Α	Selected station number	Shows the selected station number, inverter type and a comment.
В	Setting procedure	Shows current setting description and next/previous setting in Setting Wizard.
С	Setting item field	Make a setting input. (Setting items are different according to each Setting Wizard and individual
_	Holp	Displaya Holp window. (Defer to pres 147)
D	пер	Displays help window. ( <i>Refer to page 147</i> )
Е	Cancel	Closes the window with the setting made invalid.
F	< <u>B</u> ack	Returns to the previous setting window.
G	<u>N</u> ext>	Proceeds to the next window.
Н	<u>F</u> inish	Shows "Parameter List" with the setting made valid. (Parameter writing is not performed here.)

#### 3.1.3 Parameter List

Click \_\_\_\_\_\_\_ after the required item in each setting is filled in, and then the parameter setting is configured based on the inputted setting. Configured parameter setting is displayed in Parameter List after every setting is finished. To write the parameter setting to the inverter, write from the Parameter List in the Main frame. (*Refer to page 97*)



No.	Name	Function and description
Α	Selected station number	Shows the selected station number, inverter type and a comment.
В	Setting procedure	Shows the past settings in Setting Wizard.
С	Parameter setting field	Shows the parameter setting configured in Setting Wizard in the list.
D	Help	Displays Help window. (Refer to page 147)
Е	Cancel	Closes the window with the setting made invalid.
F	< <u>B</u> ack	Returns to the previous setting window.
		Closes Setting Wizard with the setting made valid.
G	<u>F</u> inish	Configured setting by Setting Wizard is reflected into Parameter List.
		(Parameter writing to the inverter is not performed.)

### 3.2 Details of Setting Wizard

#### 3.2.1 Acceleration/Deceleration Pattern and Time Setting

Select "Acceleration/Deceleration Pattern and Time Setting" from "Setting Wizard" (*Refer to page 61*) in System View to start the wizard of "Acceleration/Deceleration Pattern and Time Setting". Make acceleration/deceleration pattern and acceleration/ deceleration time setting.

#### (1) Setting flow



#### (2) Related parameters

Refer to the inverter manual for details of the parameters.

#### • Parameters related to "Acceleration/Deceleration Pattern"

Parameter Number	Name
29	Acceleration/deceleration pattern selection

#### • Parameters related to "Adjustment of Acceleration/Deceleration Pattern"

Parameter Number	Name
140	Backlash acceleration stopping frequency
141	Backlash acceleration stopping time
142	Backlash deceleration stopping frequency
143	Backlash deceleration stopping time

#### • Parameters related to "Acceleration/Deceleration Time"

Parameter	Namo	
Number	Name	
7	acceleration time	
8	Deceleration time	
20	Acceleration/deceleration reference frequency	
21	Acceleration/deceleration time increments	

#### Details of Setting Wizard

#### 3.2.2 Output Terminal(FM, CA, AM) Calibration

Select "Output Terminal (FM, CA, AM) Calibration" from "Setting Wizard" (*Refer to page 96*) in System View to start "Output Terminal (FM, CA, AM) Calibration". Terminal FM, terminal CA and terminal AM are calibrated.

#### (1) Setting flow



#### (2) Window explanation of Output Terminal Calibration



(FM terminal calibration)

No.	Name	Function and Description
Α	Output Frequency	Monitors frequency and displays.
В	Adjustment Button	Press up and down to make calibration.

#### (3) Related parameters

Refer to the inverter manual for details of the parameters.

#### • Parameters related to "Output Terminal (FM, CA, AM) Calibration"

Parameter	Name
Number	
000	FM terminal calibration
900	CA terminal calibration
901	AM terminal calibration

#### 3.2.3 Analog Input Terminal Calibration

Select "Analog Input Terminal Calibration" from "Setting Wizard" (*Refer to page 96*) in System View to start "Analog Input Terminal Calibration". Terminal 2 and terminal 4 are calibrated.

#### (1) Setting flow



#### (2) Window explanation of Analog Input Terminal Calibration



No.	Name	Function and Description
А	Frequency setting Gain frequency, Bias frequency	Set the frequency on the gain side, bias side.
В	Frequency setting Bias, Gain	Set the converted % of the voltage (current) on the gain or bias side.
		Available when making calibration without inputting to terminal.
С	Write	Writes a calibration value. (Available when making calibration without inputting to terminal.)
D	Apples Input Menitor	Monitors input to terminal 2, terminal 4 at intervals.
		Displays when making calibration with inputting to the terminal.

#### (3) Related parameters

Refer to the inverter manual for details of the parameters.

#### • Parameters related to "Analog Input Terminal Calibration"

Parameter Number	Name
125	Terminal 2 frequency setting gain frequency
126	Terminal 4 frequency setting gain frequency
241	Analog input display unit switchover
C2(902)	Terminal 2 frequency setting bias frequency
C3(902)	Terminal 2 frequency setting bias
C4(903)	Terminal 2 frequency setting gain
C5(904)	Terminal 4 frequency setting bias frequency
C6(904)	Terminal 4 frequency setting bias
C7(905)	Terminal 4 frequency setting gain

#### 3.2.4 Tuning (FR-A700, D700, E700 only)

Select "Tuning" in the "Setting Wizard" (*Refer to page 96*) in System View to start "Tuning" wizard. Tuning is performed after necessary parameter setting. Tuning is executed during the ONLINE mode only.

#### (1) Setting flow



#### (2) Window explanation of Tuning



No.	Name	Function and Description
Α	Tuning monitor	Displays progress of tuning.
В	Reverse rotation	Sends reverse rotation command to the inverter to start tuning.
С	Forward rotation	Sends forward rotation command to the inverter to start tuning.
D	Stop	Sends stop command to the inverter to stop tuning.

#### (3) Related parameters

Refer to the inverter manual for details of the parameters.

#### Parameters related to "Control Selection"

Parameter Number	Name	
60	Energy saving control selection	
80	Motor capacity	
81	Number of motor poles	
800	Control method selection	

#### Parameters related to "Motor Setting"

Parameter Number	Name	
9	Electronic thermal O/L relay	
60	Energy saving control selection	
71	Applied motor	
80	Motor capacity	
81	Number of motor poles	
83	Rated motor voltage	
84	Rated motor frequency	
359	Encoder rotation direction	
369	Number of encoder pulses	
800	Control method selection	

#### • Parameters related to "Tuning Method Selection"

Parameter Number	Name
96	Auto tuning setting/status

• Refer to the inverter manual for details of the parameter set by the tuning result.

#### 3.3 Troubleshooting

#### 3.3.1 Function Outline

Troubleshooting is a function that estimates causes of various troubles and measures against them. By selecting necessary items and making a communication with the inverter, trouble causes can be estimated for taking measures.

Double-click an item in the "Troubleshooting" in System View (or select a function and click \_\_\_\_\_\_) to start Troubleshooting.

#### (1) Basic flow of troubleshooting





#### POINT

Troubleshooting includes items that estimate a cause by making communication with the inverter. Set the system ONLINE to perform Troubleshooting if possible. When a troubleshooting which requires communication is started during OFFLINE, the screen on the right appears. Refer to Help to find trouble causes, and take appropriate measures.

Troubleshootine Cause estimating and countermeasure is available only when ONLINE for this item. Try each after turning to ONLINE. Click Help to display Causes and Measures of this trouble in the Help.



#### Note

When simple mode parameters or user group parameters are displayed, troubleshooting which requires communication can not be started. Cancel simple mode parameter or user group parameter display before starting troubleshooting. (*Pr. 160 User group read selection=*"0")

#### (2) Check item of troubleshooting

Item	Require Communication	Refer to Page
Motor does not rotate as commanded	Yes	69
Motor does not rotate	Yes	70
Motor rotation direction does not change	Yes	70
Motor coasts.	Recommended	72
Motor current is large	Recommended	73
Acceleration/deceleration is not as commanded	Recommended	74
External device (peripheral) malfunctions	No	75
Operation mode does not change	Yes	76
Unable to write parameter setting	Yes	79
Unable to communicate	No	81
### 3.3.2 Status Display

Status Display window appears when Troubleshooting is started. (Note that Cause Estimate window (*Refer to page 67*) appears instead of Status Display for Troubleshooting which does not require communication with the inverter.)

The current inverter state and I/O terminal (signal) is shown. Condition setting field of trouble occurrence is provided according to Troubleshooting items. Click distribution after selecting conditions.



No.	Name	Function and Description
Α	Setting Procedure	Displays the current, previous, and next setting in Troubleshooting.
В	Condition setting field	Select a condition of trouble occurrence.
C	Stop	Stops monitoring and holds the status. Use when trouble occurs at a certain condition. Click at the
U	Stop	trouble occurrence and stop the monitor, to narrow down the causes.
D	Start	Click to restart monitoring.
Е	State	Displays the inverter state and I/O terminal (signal).
F	Help	Displays Help window. (Refer to page 147)
G	Cancel	Closes the window with the setting made invalid.
Н	Next>	Display Cause Estimate window. (Refer to page 67)

### 3.3.3 Cause Estimate

Displays estimated causes and measures. Set conditions in the condition setting field if OFFLINE, to display estimated causes and measures. Select a probable cause from the list and click <u>Mext</u>.



No.	Name	Function and Description
Α	Expand	Expands the field of causes and measures.
В	Causes and Measures	Displays causes of the trouble and measures. Click differ selecting a probable cause. Double click (or select and press F1 key) the cause in the table to show the corresponding Help window.
С	Condition setting field	Select the condtion of the trouble occurrence.
D	Help	Displays Help window.(Refer to page 147)
E	Cancel	Closes the window with the setting made invalid.
F	< <u>B</u> ack	Returns to the Status Display window. (Refer to page 66)
G	<u>N</u> ext>	Displays Related Parameter window. (Refer to page 68)

### 3.3.4 Related Parameter

Displays parameters related to the selected cause. Check the measures, and change parameter settings. Click <u>Enish</u> to reflect the changed setting into the Parameter List, and returns to the Main frame.

To write the parameter setting to the inverter, write from the Parameter List in the Main frame. (Refer to page 97)



No.	Name	Function and Description
А	Parameter setting field	Displays parameters related to the cause. Check the measures, and change parameter settings.
В	Help	Displays Help window.(Refer to page 147)
С	Cancel	Closes the window with the setting made invalid.
D	< <u>B</u> ack	Returns to the Cause Estimate window. (Refer to page 67)
		Closes Troubleshooting with the setting valid.
Е	<u>F</u> inish	Configured setting by Troubleshooting is reflected into Parameter List.
		(Parameter writing to the inverter is not performed.)

## 3.4 Details of troubleshooting

The following shows a list of causes supported in the troubleshooting. Take measures after checking possible causes. Refer to the inverter manual for details.

### 3.4.1 Motor does not rotate as commanded

#### Main causes

Cause	Measures	Related Parameters
The set frequency is higher than the maximum frequency ( <i>Pr. 1, 18</i> ).	Set the maximum frequency (Pr. 1, 18) higher than the set frequency.	Pr. 1, 18
The set frequency is lower than the minimum frequency ( <i>Pr. 2</i> ).	Set the minimum frequency (Pr: 2) lower than the set frequency.	Pr. 2
The set frequency is within the frequency jump ( <i>Pr. 31 to Pr. 36</i> ).	Change the range of the frequency jump <i>Pr. 31 to Pr. 32, Pr. 33 to Pr. 34, Pr. 35 to Pr. 36</i> so that the set frequency will not overlap.	Pr. 31 to 36
PID control activated	Cancel PID control.	Pr: 128
Stall prevention (current limit/voltage limit) is activated.	<ol> <li>Adjust torque boost (<i>Pr. 0, etc.</i>)</li> <li>Set a larger value in acceleration/deceleration time (<i>Pr. 7, Pr. 8, etc.</i>).</li> <li>Reduce the load weight.</li> <li>Try other control method.</li> <li>Increase stall prevention level (<i>Pr. 22, etc.</i>), or limit stall prevention operation using stall prevention selection (<i>Pr. 156</i>).</li> </ol>	<ul> <li>(1) Pr. 0, 46, 112</li> <li>(2) Pr. 7, 8, 44, 45, 110, 111</li> <li>(4) Pr. 71, 80, 81, 83, 84, 96, 450, 451, 453, 454, 456, 457, 463, 800</li> <li>(5) Pr. 22, 23, 48, 114, 156</li> </ul>

#### Causes related to V/F control

Cause	Measures	Related Parameters
Torque boost setting may not be an appropriate value.	Adjust torque boost (Pr: 0, etc.)	Pr. 0, 46, 112
V/F pattern setting may not be an appropriate value.	Adjust V/F pattern related parameters(Pr. 3, 14, 19, etc.)	Pr. 3, 14, 19, 47, 113
Set frequency is unstable due to external	(1) Take EMI measures.	Pr 74 822 832
EMI	(2) Set a larger value in filter time constant parameter ( <i>Pr. 74, etc.</i> ).	17. 74, 022, 052
Load fluctuation	Take measures to prevent load from changing.	-
Power supply voltage fluctuation	Check the power supply voltage.	-

#### • Causes other than V/F control

Causo	Moseuroe	Related
Cause	incasules	Parameters
		Pr. 71, 80, 81, 83,
Frequency fluctuation of magnetic flux	Try other control method.	84, 96, 450, 451,
vector control		453, 454, 456, 457,
		463, 800
Set frequency is unstable due to external	(1) Take EMI measures.	Du 74 012 022
EMI	(2) Set a larger value in filter time constant parameter (Pr. 74, etc.).	<i>PT.</i> 74, 022, 032
Load fluctuation	Take measures to prevent load from changing.	-
Power supply voltage fluctuation	Check the power supply voltage.	-

### 3.4.2 Motor does not rotate, or motor rotation direction does not change

#### Main causes

Called         Interaction         Parameter           The motor is at a stop due to fault courrence.         Refer to the item related to faults in "Help" and then take measures.         -           Occurred fault : xxx         Check the main circuit power (RL1, SL2, TL3) is ON.         Fr. 30           The main circuit power (RL1, SL2, TL3) is not ON or the power supply phase is lost.         Check the main circuit power (RL1, SL2, TL3) is ON.         Fr. 30           Power is not ON or input voltage is insufficient.         Check that the power is ON. Check that the input voltage is not insufficient.         -           Both STF and STR signals are ON or OFF.         Tum OF the signal to the direction which the motor is supporsed to run and frequency.         -           The MSF signal is ON.         Tum off the MRS signal.         -           The signal signal is ON.         Tum off the MRS signal.         -           The which the running speed is entered to tand the signal to the direction or reverse rotation command.         -           Although the running speed is entered to tan othered.         Set the maximum frequency (Pr. 1, Pr. 18) larger than the start frequency.         Pr. 1, 13, 18           The maximum frequency is smaller than the start frequency.         Cancel automatic restart after instantaneous power failure is valid and CS signal is OFF.         CS signal ON.         Pr. 73           Automatic restart after instantaneous power failure is valid and CS signal is OFF.         CS sig	Causo	Мозециое	Related
The motor is at a stop due to fault       Refer to the item related to faults in "Help" and then take measures.       -         Occurred fault : xxx       Check the main circuit power (RL1, SJL2, TL3) is ON.       Pr. 30         The main circuit power (RL1, SJL2, TL3)       Check the main circuit power supply regeneration common converter, c.s. is used (driving by DC power input to P and N), check the setting of regenerative function selection (Pr. 30).       Pr. 30         Power is not ON or input voltage is insufficient.       Check that the power is ON. Check that the input voltage is not insufficient.       -         Both STF and STR signals are ON or OFF.       Tum ON the signal.       -       -         The MRS signal is ON.       Tum off the MRS signal.       -       -         The start frequency is larger than the set frequency.       Pr. 13       -       -         Although the running speed is entered to terminal 4, the AU signal SOFF.       Tum the AU signal ON.       -       -         The inverter operates in PU mode and forward rotation or reverse rotation command.       -       -       -         Is not entered.       Set the maximum frequency (Pr. 1, Pr. 13) arger than the start frequency (Pr. 1, Pr. 13).       -       -       -         The inverter oparates in PU mode and forward rotation or reverse rotation command.       -       -       -       -       -       -       -       -       -	Cause	Medsures	Parameters
The main circuit power (RU.1, SU.2, TI.3) is ON. When high power factor converter, power supply page is is not ON or input voltage is insufficient.Check the main circuit power (RU.1, SU.2, TI.3) is ON. When high power factor converter, power supply regeneration common converter, etc. is used (driving by DC power input to P and N), check the insufficient. $Pr. 30$ Power is not ON or input voltage is insufficient.Check that the power is ON. Check that the input voltage is not insufficientBoth STF and STR signals are ON or OFF. The MRS signal is ON.Turn ON the signal to the direction which the motor is supporsed to run and OFF the other signalThe start frequency is larger than the set frequency.Turn off the MRS signalAlthough the running speed is entered to terminal 4, the AU signal is OFF.Turn the AU signal ONThe inverter oparates in PU mode and is not entered.Set the maximum frequency ( $Pr. 1, Pr. 18$ ) larger than the start frequency ( $Pr. 13$ , or set the start frequency ( $Pr. 1, Pr. 18$ ) larger than the start frequency ( $Pr. 1, Pr. 18$ ). $Pr. 1, 13, 18$ Automatic restart after instantaneous power failure is valid and CS signal is OFF.Cancel automatic restart after instantaneous power failure, or turn the power failure is valid and CS signal is OFF.Change the reverse rotation prevention selection ( $Pr. 76$ ) setting to allow the desired rotation direction. $Pr. 73$ PID control activatedCancel PID control. $Pr. 72, 8. etc.)$ (3) digits VF pattern parameters ( $Pr. 3, 1, 19, etc.$ ) $Pr. 73, 8. 83, 3. 43, 44, 44, 45, 453, 453, 453, 453, 453$	The motor is at a stop due to fault occurrence. Occurred fault : xxx	Refer to the item related to faults in "Help" and then take measures.	-
Power is not ON or input voltage is insufficient.       Check that the power is ON. Check that the input voltage is not insufficient.       -         Both STF and STR signals are ON or OFF.       Turn ON the signal to the direction which the motor is supporsed to run and OFF the other signal.       -         The MRS signal is ON.       Turn Off the MRS signal.       -         The start frequency is larger than the set frequency.       Set the start frequency ( <i>Pr. 13</i> ) lower than the set frequency. <i>Pr. 13</i> Although the running speed is entered to terminal 4, the AU signal is OFF.       Turn the AU signal ON.       -         The inverter operates in PU mode and forward rotation command.       Give forward rotation or reverse rotation command.       -         is not entered.       Set the maximum frequency ( <i>Pr. 1, Pr. 18</i> ) larger than the start frequency ( <i>Pr. 13, or</i> set the start frequency ( <i>Pr. 1, Pr. 18</i> ) smaller than the maximum frequency ( <i>Pr. 1, Pr. 18</i> ). <i>Pr. 1, 13, 18</i> Automatic restart after instantaneous power failure is valid and CS signal is OFF.       Cancel automatic restart after instantaneous power failure, or turn the CS signal ON. <i>Pr. 78</i> PID control activated       Cancel PID control. <i>Pr. 128 Pr. 1.90</i> 1. Common Check the motor connection.       2.       (2) <i>Pr. 0, 46, 112</i> (3) <i>Pr. 3, 14, 19, 10, 113</i> Stall prevention (current limit/voltage limit) or regeneration avoidance is activated.       (3) Adjust Vir pattern paramet	The main circuit power (R/L1, S/L2, T/L3) is not ON or the power supply phase is lost.	Check the main circuit power (R/L1, S/L2, T/L3) is ON. When high power factor converter, power supply regeneration common converter, etc. is used (driving by DC power input to P and N), check the setting of regenerative function seleciton ( $Pr: 30$ ).	Pr. 30
Both STF and STR signals are ON or OFF.       Turn ON the signal.       -         The MRS signal is ON.       Turn off the MRS signal.       -         The start frequency is larger than the set frequency.       Set the start frequency (Pr. 13) lower than the set frequency.       Pr. 13         Although the running speed is entered to terminal 4, the AU signal is OFF.       Turn the AU signal ON.       -         The inverter operates in PU mode and forward rotation/reverse rotation command.       Give forward rotation reverse rotation command.       -         The maximum frequency is smaller than the start frequency (Pr. 1, Pr. 18).       Set the maximum frequency (Pr. 1, Pr. 18) larger than the start frequency (Pr. 13). or set the start frequency (Pr. 13). smaller than the maximum frequency (Pr. 1, Pr. 18).       Pr. 1, 13, 18         Automatic restart after instantaneous power failure is valid and CS signal is OFF.       Cancel automatic restart after instantaneous power failure, or turn the de signal on direction.       Pr. 57         PID control activated       Cancel PID control.       Pr. 78         PID control activated       Cancel PID control.       Pr. 78.         Stall prevention (current limit/voltage limit) or regeneration avoidance is activated.       (5) Reduce the load weight.       (6) Try other control method.         (7) Increase stall prevention level (Pr. 22, etc.), or limit stall prevention operation avoidance is activated.       (7) Increase stall prevention level (Pr. 22, etc.), or limit stall prevention (Pr. 156). <td>Power is not ON or input voltage is insufficient.</td> <td>Check that the power is ON. Check that the input voltage is not insufficient.</td> <td>-</td>	Power is not ON or input voltage is insufficient.	Check that the power is ON. Check that the input voltage is not insufficient.	-
The MRS signal is ON.         Turn off the MRS signal.         -           The start frequency.         Set the start frequency (Pr. 13) lower than the set frequency.         Pr. 13           Although the running speed is entered to terminal 4, the AU signal IS OFF.         Turn the AU signal ON.         -           The inverter operates in PU mode and forward rotation/reverse rotation command.         Give forward rotation or reverse rotation command.         -           The maximum frequency is smaller than the start frequency.         Set the maximum frequency (Pr. 1, Pr. 18) larger than the start frequency (Pr. 13) core the start frequency (Pr. 13) smaller than the start frequency (Pr. 1, Pr. 18).         -           Automatic restart after instantaneous power failure, or turn the power failure is valid and CS signal is OFF.         CS signal ON.         Pr. 57           Reverse rotation prevention selection is set.         Change the reverse rotation prevention selection (Pr. 78) setting to allow the desired rotation direction.         Pr. 78           PID control activated         Cancel PID control.         Pr. 128           1. Common Check the motor connection.         2.         (2) Pr. 0, 46, 112           (3) Adjust V/F pattern parameters (Pr. 3, 14, 19, etc.)         (4) Pr. 7, 80, 81         83, 84, 96, 43           (4) The control method.         (7) Increase stall prevention operation selection (Pr. 156).         3. Voltage limit set a longer deceleration time (Pr. 8).         3. Pr. 8	Both STF and STR signals are ON or OFF.	Turn ON the signal to the direction which the motor is supporsed to run and OFF the other signal.	-
The start frequency.       Set the start frequency (Pr. 13) lower than the set frequency.       Pr. 13         Although the running speed is entered to terminal 4, the AU signal is OFF.       Turn the AU signal ON.       -         The inverter operates in PU mode and forward rotation/reverse rotation command.       Give forward rotation or reverse rotation command.       -         is not entered.       Set the maximum frequency (Pr. 1, Pr. 18) larger than the start frequency (Pr. 1, Pr. 18) larger than the start frequency (Pr. 13) or set the start frequency (Pr. 13) smaller than the maximum frequency (Pr. 13) or set the start frequency (Pr. 13) smaller than the maximum frequency (Pr. 13).       Pr. 1.13, 18         Automatic restart after instantaneous power failure is valid and CS signal is OFF.       Cancel automatic restart after instantaneous power failure, or turn the CS signal ON.       Pr. 57         Reverse rotation prevention selection is set.       Change the reverse rotation prevention selection (Pr. 78) setting to allow the desired rotation direction.       Pr. 128         PID control activated       Cancel PID control.       Pr. 128         1. Common       Change the route shouting of "Motor current is large"       (2)         (2) Adjust V/F pattern parameters (Pr. 3, 14, 19, etc.).       Stall prevention (current limit/voltage limit) or regeneration avoidance is activated.       (5) Reduce the load weight.       (6) Tr. 7, 8, 8, 40, 64, 30, 00(T) Pr. 22, etc.). or limit stall prevention (Pr. 7, Pr. 8, etc.).         Stall prevention (current limit/voltage limit) or rege	The MRS signal is ON.	Turn off the MRS signal.	-
Although the running speed is entered to terminal 4, the AU signal is OFF.       Turn the AU signal ON.       -         The inverter operates in PU mode and forward rotation/reverse rotation command is not entered.       Give forward rotation or reverse rotation command.       -         The maximum frequency is smaller than the start frequency ( <i>Pr. 1, Pr. 18</i> ) larger than the start frequency ( <i>Pr. 13</i> , or set the start frequency ( <i>Pr. 13</i> ) smaller than the maximum frequency ( <i>Pr. 1, Pr. 18</i> ).       Pr. 1, 13, 18         Automatic restart after instantaneous power failure is valid and CS signal is OFF.       Cancel automatic restart after instantaneous power failure, or turn the CS signal ON.       Pr. 57         Reverse rotation prevention selection is set.       Change the reverse rotation prevention selection ( <i>Pr. 78</i> ) setting to allow the desired rotation direction.       Pr. 78         PID control activated       Cancel PID control.       Pr. 128         1. Common       Check the motor connection.       2.         2. Current limit       1) Excecute trouble shooting of "Motor current is large"       (2) <i>Pr. 0, 46, 112</i> 3. Adjust V/F pattern parameters ( <i>Pr. 3, 14, 19, etc.</i> )       Sat alorger value in acceleration/deceleration ( <i>Pr. 7, Pr. 8, etc.</i> ).       83, 84, 96, 43         51. Stall prevention (current limit/voltage limit) or regeneration avoidance is activated.       (3) Adjust V/F pattern parameters ( <i>Pr. 3, 14, 19, etc.</i> )       (3) Adjust V/F pattern parameters ( <i>Pr. 22, etc.</i> ), or limit stall prevention ( <i>Pr. 156</i> ).       3. <i>Pr. 8</i>	The start frequency is larger than the set frequency.	Set the start frequency (Pr. 13) lower than the set frequency.	Pr. 13
The inverter operates in PU mode and forward rotation/reverse rotation command.       Give forward rotation or reverse rotation command.       -         The maximum frequency is smaller than the start frequency.       Give forward rotation or reverse rotation command.       -         Automatic restart after instantaneous power failure is valid and CS signal is OFF.       Set the maximum frequency ( <i>Pr. 1, Pr. 18</i> ).       Barage than the start frequency ( <i>Pr. 13</i> ) smaller than the maximum frequency ( <i>Pr. 13</i> ) smaller than the maximum frequency ( <i>Pr. 13</i> ). <i>Pr. 1, 13, 18</i> Automatic restart after instantaneous power failure is valid and CS signal is OFF.       Cancel automatic restart after instantaneous power failure, or turn the CS signal ON. <i>Pr. 57</i> Reverse rotation prevention selection is set.       Change the reverse rotation prevention selection ( <i>Pr. 78</i> ) setting to allow the desired rotation direction. <i>Pr. 78</i> PID control activated       Cancel PID control. <i>Pr. 128</i> 1. Common Check the motor connection.       2.       (2) <i>Pr. 0, 46, 112</i> (3) Adjust V/F pattern parameters ( <i>Pr. 3, 14, 19, etc.</i> )       83, 84, 96, 43         (4) Set a larger value in acceleration/deceleration time ( <i>Pr. 7, Pr. 8, etc.</i> ).       83, 84, 96, 43         (5) Reduce the load weight.       Try other control method.       79, <i>Pr. 2, 3, 44</i> (7) Increase stall prevention operation selection ( <i>Pr. 156</i> ).       3. <i>Pr. 8</i> 3. V	Although the running speed is entered to terminal 4, the AU signal is OFF.	Turn the AU signal ON.	-
The maximum frequency is smaller than the start frequency.Set the maximum frequency (Pr. 1, Pr. 18) larger than the start frequency (Pr. 13), or set the start frequency (Pr. 13) smaller than the maximum frequency (Pr. 1, Pr. 18).Pr. 1, 13, 18Automatic restart after instantaneous power failure is valid and CS signal is OFF.Cancel automatic restart after instantaneous power failure, or turn the CS signal ON.Pr. 57Reverse rotation prevention selection is set.Cancel automatic restart after instantaneous power failure, or turn the CS signal ON.Pr. 78PID control activatedCancel PID control.Pr. 1282.Cancel PID control.Pr. 1282.Current limit (1) Excecute trouble shooting of "Motor current is large" (2) Adjust V/F pattern parameters (Pr. 3, 14, 19, etc.)113 (4) Pr. 7, 8, etc.).Stall prevention (current limit/voltage limit) or regeneration avoidance is activated.Stall prevention level (Pr. 22, etc.), or limit stall prevention operation using stall prevention level (Pr. 22, etc.), or limit stall prevention operation using stall prevention new (Pr. 7, Pr. 8, etc.).3. Pr. 83. Voltage limit Set a longer deceleration time (Pr. 8).3. Pr. 84. (1) Pr. 8	The inverter operates in PU mode and forward rotation/reverse rotation command is not entered.	Give forward rotation or reverse rotation command.	-
Automatic restart after instantaneous power failure is valid and CS signal is OFF.       Cancel automatic restart after instantaneous power failure, or turn the CS signal ON.       Pr. 57         Reverse rotation prevention selection is set.       Change the reverse rotation prevention selection (Pr. 78) setting to allow the desired rotation direction.       Pr. 78         PID control activated       Cancel PID control.       Pr. 128         1. Common       Check the motor connection.       2.         2. Current limit       Current limit       2.         (1) Excecute trouble shooting of "Motor current is large"       (1) Pr. 7, 8, 44, 4         (2) Adjust torque boost (Pr. 0, etc.)       (3) Adjust V/F pattern parameters (Pr. 3, 14, 19, etc.)         (4) Set a larger value in acceleration/deceleration time (Pr. 7, Pr. 8, etc.).       83, 84, 96, 43         (5) Reduce the load weight.       (6) Try other control method.       (7) Increase stall prevention level (Pr. 22, etc.), or limit stall prevention operation using stall prevention selection (Pr. 156).       3. Voltage limit       3. Pr. 8         3. Voltage limit       Set a longer deceleration time (Pr. 8).       4.       (1) Pr. 8	The maximum frequency is smaller than the start frequency.	Set the maximum frequency ( <i>Pr. 1, Pr. 18</i> ) larger than the start frequency ( <i>Pr. 13</i> ), or set the start frequency ( <i>Pr. 13</i> ) smaller than the maximum frequency ( <i>Pr. 1, Pr. 18</i> ).	Pr. 1, 13, 18
Reverse rotation prevention selection is set.       Change the reverse rotation prevention selection (Pr. 78) setting to allow the desired rotation direction.       Pr. 78         PID control activated       Cancel PID control.       Pr. 128         1. Common Check the motor connection.       2.         2. Current limit       (1) Excecute trouble shooting of "Motor current is large"       (2) Pr. 0, 46, 112         (3) Adjust V/F pattern parameters (Pr. 3, 14, 19, etc.)       (4) Set a larger value in acceleration/deceleration time (Pr. 7, Pr. 8, etc.).       (5) Reduce the load weight.         (6) Try other control method.       (7) Increase stall prevention level (Pr. 22, etc.), or limit stall prevention operation using stall prevention selection (Pr. 156).       3. Voltage limit Set a longer deceleration time (Pr. 8).         3. Voltage limit       3. Voltage limit       4.         (1) Pr. 8       (1) Pr. 8	Automatic restart after instantaneous power failure is valid and CS signal is OFF.	Cancel automatic restart after instantaneous power failure, or turn the CS signal ON.	Pr. 57
PID control activatedCancel PID control.Pr. 1281. Common Check the motor connection.1. Common Check the motor connection.2.2. Current limit (1) Excecute trouble shooting of "Motor current is large" 	Reverse rotation prevention selection is set.	Change the reverse rotation prevention selection ( <i>Pr. 78</i> ) setting to allow the desired rotation direction.	Pr. 78
1. Common Check the motor connection.2.2. Current limit (1) Excecute trouble shooting of "Motor current is large" (2) Adjust torque boost (Pr. 0, etc.)3. Adjust V/F pattern parameters (Pr. 3, 14, 19, etc.)3. Adjust V/F pattern parameters (Pr. 3, 14, 19, etc.) (4) Set a larger value in acceleration/deceleration time (Pr. 7, Pr. 8, etc.).(6) Pr. 71, 80, 81 83, 84, 96, 45 451, 453, 454 456, 463, 800 (7) Pr. 22, 23, 48 114, 1563. Voltage limit Set a longer deceleration time (Pr. 8).3. Pr. 84. Regeneration avoidance operation4.	PID control activated	Cancel PID control.	Pr. 128
(1) Set a longer deceleration time (Pr. 8).(2) Pr. 665, 882, 883, 884, 885(2) Adjust regeneration avoidance parameters883, 884, 885	Stall prevention (current limit/voltage limit) or regeneration avoidance is activated.	<ol> <li>Common Check the motor connection.</li> <li>Current limit         <ol> <li>Excecute trouble shooting of "Motor current is large"</li> <li>Adjust torque boost (<i>Pr. 0, etc.</i>)</li> <li>Adjust V/F pattern parameters (<i>Pr. 3, 14,19, etc.</i>)</li> <li>Set a larger value in acceleration/deceleration time (<i>Pr. 7, Pr. 8, etc.</i>).</li> <li>Reduce the load weight.</li> <li>Try other control method.</li> <li>Increase stall prevention level (<i>Pr. 22, etc.</i>), or limit stall prevention operation using stall prevention operation selection (<i>Pr. 156</i>).</li> </ol> </li> <li>Voltage limit Set a longer deceleration time (<i>Pr. 8</i>).</li> <li>Regeneration avoidance operation             <ol> <li>Set a longer deceleration time (<i>Pr. 8</i>).</li> <li>Adjust regeneration avoidance narameters</li> </ol> </li> </ol>	<ol> <li>2.</li> <li>(2) Pr. 0, 46, 112</li> <li>(3) Pr. 3, 14, 19, 47, 113</li> <li>(4) Pr. 7, 8, 44, 45, 110, 111</li> <li>(6) Pr. 71, 80, 81, 83, 84, 96, 450, 451, 453, 454, 456, 463, 800</li> <li>(7) Pr. 22, 23, 48, 114, 156</li> <li>3. Pr. 8</li> <li>4.</li> <li>(1) Pr. 8</li> <li>(2) Pr. 665, 882, 883, 884, 885,</li> </ol>

 Causes related to V/F control, general-purpose magnetic flux vector control/advanced magnetic flux vector control

Cause	Measures	Related Parameters
The current limit is activated.	<ol> <li>Excecute trouble shooting of "Motor current is large"</li> <li>Increase stall prevention level (<i>Pr. 22, etc.</i>) or limit stall prevention operation using stall prevention operation selection (<i>Pr. 156</i>).</li> </ol>	( <b>2</b> ) Pr. 22, 23, 48, 114, 156
Load is heavy.	Check the load.	-
The motor is not connected securely.	Check the motor connection.	-

#### Causes related to real sensorless vector control

Cause	Measures	Related Parameters
Torque limit is activated.	<ol> <li>Excecute trouble shooting of "Motor current is large"</li> <li>Adjust torque limit level (<i>Pr. 22, etc.</i>)</li> </ol>	(2) Pr. 22, 803, 812, 813, 814, 815, 816, 817, 874
Load is heavy.	Check the load.	-

### Causes related to vector control

Cause	Measures	Related Parameters
Torque limit is activated.	<ul><li>(1) Excecute trouble shooting of "Motor current is large"</li><li>(2) Adjust torque limit level (<i>Pr. 22, etc.</i>)</li></ul>	(2) Pr. 22, 803, 812, 813, 814, 815, 816, 817, 874
Load is heavy.	Check the load.	-
The encoder setting is not an appropriate value.	Check the setting of encoder rotation direction ( <i>Pr. 359</i> ) and number of encoder pulses ( <i>Pr. 369</i> ).	Pr. 359, 369
The motor is not connected securely.	<ul><li>(1) Check the motor connection.</li><li>(2) Check the phase sequence of the motor.</li></ul>	-

### 3.4.3 Motor coasts

Cause	Measures	Related Parameters
The stop selection (Pr. 250) is selected.	Change the stop selection (Pr. 250) setting to cansel coasting to a stop.	Pr. 250
Check that the output stop signal (MRS) or selection of automatic restart after instantaneous power failure (CS) is ON/ OFF during operation or reset is input.	<ul><li>(1) Check for input terminal connection and communication command.</li><li>(2) Take measures againt EMI to the input terminal wires.</li></ul>	-
The magnetic contactor on the motor side turns OFF.	Check operation of the magnetic contactor.	-
Power failure occurs.	Check for input power supply.	-
Inverter fault occurs.	Check for a fault occurs. Refer to the item related to faults in "Help" and then take measures.	-
Braking torque of DC injection brake is insufficient or coasting is set.	Adjust DC injection brake operation frequency ( <i>Pr. 10</i> ), DC injection brake operation time ( <i>Pr. 11</i> ), DC injection brake operation voltage ( <i>Pr. 12</i> ).	Pr. 10, 11, 12

### 3.4.4 Motor current is large

#### • Causes under V/F control

Cause	Measures	Related Parameters
Torque boost ( <i>Pr. 0, etc.</i> ) setting is too large.	Decrease torque boost (Pr. 0, etc.) setting.	Pr. 0, 46, 112
V/F control related parameter setting is not	Adjust torque boost (Pr. 0, etc.), base frequency (Pr. 3, etc.), base	Pr. 0, 3, 14, 19, 46,
an appropriate value.	frequency voltage (Pr. 19), load pattern selection (Pr. 14).	47, 112, 113
Load is heavy.	Check the load.	-
The acceleration/deceleration time (Pr. 7,	Set a larger value in appendix $d_{2}$	Pr. 7, 8, 44, 45, 110,
Pr. 8, etc.) setting is too small.	Set a larger value in acceleration/deceleration time ( <i>Pr. /, Pr. 8, etc.</i> ).	111
Load inertia (GD2) is too large.	(1) Decrease inertia (GD2)	(2) Pr: 7, 8, 44, 45,
	(2) Set a larger value in acceleration/deceleration time (Pr. 7, Pr. 8, etc.).	110, 111

#### Causes other than V/F control

Course	Measures	Related
Cause		Parameters
Motor specifications sotting is not		Pr. 71, 80, 81, 83,
appropriato	Check that the motor specifications setting is correct.	84, 450, 453, 454,
appropriate.		456, 457
Offline auto tuning is not performed.	Perform Offline auto tuning.	Pr. 96, 463
Load is heavy.	Check the load.	-
The acceleration/deceleration time (Pr. 7,	Set a larger value in acceleration/deceleration time (Pr. 7, Pr. 8, etc.).	Pr. 7, 8, 44, 45, 110,
Pr. 8, etc.) setting is too small.		111
Load inartia (GD2) is too large	<ul> <li>(1) Decrease inertia (GD2)</li> <li>(2) Set a larger value in acceleration/deceleration time (<i>Pr. 7, Pr. 8, etc.</i>).</li> </ul>	(2) Pr: 7, 8, 44, 45,
		110, 111

### 3.4.5 Acceleration/deceleration is not as commanded

#### • Causes under V/F control

Cause	Measures	Related Parameters
The acceleration/deceleration time(Pr: 7,	Set a larger value in acceleration/deceleration time (Pr. 7, Pr. 8, etc.). (In	$P_{\rm H} = 7 - 4A - 110$
Pr. 8, etc.) setting is too small.	vertical lift applications, set a smaller value.)	<i>II</i> . <i>/</i> , <i>44</i> , <i>110</i>
V/F control related parameter setting is not	Adjust torque boost (Pr. 0, etc.), base frequency (Pr. 3, etc.), base	Pr. 0, 3, 14, 19, 46,
an appropriate value.	frequency voltage (Pr. 19), load pattern selection (Pr. 14).	47, 112, 113
Stall prevention is activated due to heavy	Increase stall prevention level (Pr: 22, etc.) or limit stall prevention	Dr. 22 156
load (GD2).	operation using stall prevention operation selection (Pr. 156).	<i>FT. 22, 130</i>

### Causes under control other than V/F control

Cause	Measures	Related Parameters
The acceleration/deceleration time( <i>Pr. 7, Pr. 8, etc.</i> ) setting is too small.	Set a larger value in acceleration/deceleration time ( <i>Pr. 7, Pr. 8, etc.</i> ). (In vertical lift applications, set a smaller value.	Pr. 7, 44, 110
Motor specifications setting is not appropriate.	Check that the motor specifications setting is correct.	Pr: 71, 80, 81, 83, 84, 450, 453, 454, 456, 457
Stall prevention operation or regeneration avoidance function is set.	<ol> <li>(1) Excecute trouble shooting of "Motor current is large"</li> <li>(2) Set a larger value in acceleration/deceleration time (<i>Pr. 7, Pr. 8, etc.</i>).</li> <li>(3) Try other control method.</li> <li>(4) Increase stall prevention level (<i>Pr. 22, etc.</i>) or limit stall prevention operation using stall prevention operation selection (<i>Pr. 156</i>).</li> <li>(5) Adjust regeneration avoidance related parameters.</li> </ol>	<ul> <li>(2) Pr. 7, 8, 44, 45, 110, 111</li> <li>(3) Pr. 71, 80, 81, 83, 84, 96, 450, 451, 453, 454, 456, 457, 463, 800</li> <li>(4) Pr. 22, 23, 48, 114, 156</li> <li>(5) Pr. 665, 882, 883, 884, 885, 886</li> </ul>
Offline auto tuning is not performed.	Perform Offline auto tuning.	Pr. 96, 463
Load is heavy.	Check the load.	-

### 3.4.6 External device (peripherals) malfunctions

### Causes related to overcurrent relay

Cause	Measures	Related Parameters
Current is large.	Excecute trouble shooting of "Motor current is large"	-
Leakage current is large.	<ol> <li>Decrease the setting value of PWM frequency selection (<i>Pr: 72</i>).</li> <li>[FR-A700 and FR-F700]</li> <li>(2) Connect the EMC filter ON/OFF connector to OFF.</li> </ol>	(1) <i>Pr</i> : 72
The overcurrent relay (OCR) setting is small.	Set a value 1.1 times of 60Hz rated current.	-

#### Causes related to the earth leakage current breaker

Cause	Measures	Related Parameters
	(1) Decrease the setting value of PWM frequency selection (Pr. 72).	
	(2) Use a breaker designed for harmonic and surge suppression	
	(3) Use a low-permittivity cable.	
Leakage current is large.	(4) Shorten the wiring length between the motor and inverter.	(1) Pr. 72
	[FR-A700 and FR-F700]	
	(5) Connect the EMC filter ON/OFF connector to OFF.	
The rated sensitivity current of the earth	Increase the rated sensitivity current of the earth leakage current	
leakage current breaker is small	breaker.	-

### Other causes

Cause	Measures	Related Parameters
The setting value of PWM frequency selection ( <i>Pr. 72</i> ) is too large.	Decrease the setting value of PWM frequency selection (Pr. 72).	Pr. 72
	(1) Separate a signal cable from a power cable.	
	(2) Install a common mode filter.	
	(3) Use a twisted pair cable	
Electromagnetic interference	(4) Route wires using metal conduit.	-
	[FR-A700 and FR-F700]	
	(5) Connect the EMC filter ON/OFF connector to OFF.	
Misoperation caused by undesirable		
currents when a programmable controller	Use terminal PC as a common terminal, and perform wiring.	-
is connected.		

### 3.4.7 Operation mode does not change

### Causes during operation

Cause	Measures	Related Parameters
Operation mode can not be changed	Change the operation mode after stopping operation.	
during operation with the current parameter	Change operation mode selection(Pr. 79) to change the operation mode	Pr: 79
setting.	during operation.	

#### Causes when changing from NET operation mode to PU operation mode

Cause	Measures	Related Parameters
Operation mode can not be directly changed from NET operation to PU operation with the current parameter	After changing to EXT operation, change to PU operation. If the operation mode will not change to EXT operation, return to "Status Display" screen to execute troubleshooting of "Operation mode does not change to EXT".	Pr. 340
setting.	Change communication start up mode selection( <i>Pr. 340</i> ) to change directly to PU operation. After changing <i>Pr. 340</i> , reset the inverter.	
By making parameter setting, operation mode can be changed.	Set 1 in operation mode selection(Pr: 79).	Pr. 79
Operation mode is specified with X16, X65, and X66 signals. (when X16, X65, and X66 signals are assigned)	<ul> <li>Change to the PU operation mode by setting as shown below.</li> <li>(1) X65 signal is ON (when only X65 signal is assigned)</li> <li>(2) X66 signal is OFF, and X16 signal is OFF (when only X16 and X66 signals are assigned)</li> <li>(3) X66 signal is OFF, and X65 signal is ON or X16 signal is OFF (when all X16, X65 and X66 signals are assigned)</li> </ul>	-
Command for changing to PU operation mode from NET operation mode is given only from the operation location with PU operation control source. (when X16, X65, and X66 signals are not assigned)	Change the operation mode from the operation location with control source.	-

### Causes when changing from EXT and NET operaiton mode to PU operation mode

Cause	Measures	Related Parameters
Operation mode is specified with X16, X65, and X66 signals. (when X16, X65, and X66 signals are assigned) Command for changing to PU operation mode from EXT operation mode is given only from the operation location with PU operation control source.	<ul> <li>Change to the PU operation mode by setting as shown below.</li> <li>(1) X16 signal is OFF (when only X16 signal is assigned)</li> <li>(2) X66 signal is OFF, and X16 signal is ON (when only X16 and X66 signals are assigned)</li> <li>(3) X66 signal is OFF, and X65 signal is ON or X16 signal is OFF (when all X16, X65 and X66 signals are assigned)</li> <li>Change the operation mode from the operation location with control source.</li> </ul>	-
(when X16, X65, and X66 signals are not assigned) By making parameter setting, operation	Set 1 in operation mode selection ( $Pr$ , 79)	Pr 79
mode can be changed. Operation mode change is restricted with X12 and MRS signals.	When X12 signal is assigned, turn X12 signal ON. When X12 signal is not assigned, turn MRS signal ON.	-

#### Causes when changing from PU operaiton mode to EXT operation mode

Causa	Maggurag	Related
Cause	Medsures	Parameters
	Change to the EXT operation mode by setting as shown below.	
Operation mode is specified with X16, X65,	(1) X16 signal is ON (when only X16 signal is assigned)	
and X66 signals.	(2) X66 signal is OFF, and X16 signal is ON	
(when X16, X65, and X66 signals are	(when only X16 and X66 signals are assigned)	-
assigned)	(3) X66 signal is OFF, and X65 signal is OFF and X16 signal is ON	
	(when all X16, X65 and X66 signals are assigned)	
Command for changing to EXT operation		
mode from PU operation mode is given		
only from the operation location with PU	Change the operation mode from the operation location with control	
operation control source.	source.	-
(when X16, X65, and X66 signals are not		
assigned)		
By making parameter setting, operation		
mode can be changed.	Set 2 in operation mode selection $(P_{\rm ff}, 70)$	$D_{\rm H}$ 70
(when X16, X65, and X66 signals are not	Set 2 in operation mode selection( <i>P1. 79</i> ).	<i>IT.</i> /9
assigned)		
Restricted by parameter setting	Set 0, 1, or 2 in communication startup mode selection (Pr. 340), and	Pr 310
Restricted by parameter setting.	reset the inverter.	11. 570
Operation mode change is restricted with	When X12 signal is assigned, turn X12 signal OFF. When X12 signal is	_
X12 and MRS signals.	not assigned, turn MRS signal OFF.	-

### Causes when changing from NET operation mode to EXT operation mode

Cause	Measures	Related Parameters
Restricted by parameter setting.	Set 0, 1, or 2 in communication startup mode selection ( <i>Pr. 340</i> ), and reset the inverter.	Pr. 340
Operation mode is specified with X16, X65, and X66 signals. (when X16, X65, and X66 signals are assigned)	<ul> <li>Change to the EXT operation mode by setting as shown below.</li> <li>(1) X66 signal is ON (when only X66 signal is assigned)</li> <li>(2) X66 signal is OFF, and X16 signal is ON (when only X16 and X66 signals are assigned)</li> <li>(3) X66 signal is OFF, and X65 signal is OFF and X16 signal is ON (when all X16, X65 and X66 signals are assigned)</li> </ul>	-
Command for changing to EXT operation mode from NET operation mode is given only from the operation location with NET operation control source. (when X16, X65, and X66 signals are not assigned)	Change the operation mode from the operation location with control source.	-
Operation mode change is restricted with X12 and MRS signals.	When X12 signal is assigned, turn X12 signal OFF. When X12 signal is not assigned, turn MRS signal OFF.	-

### • Causes when changing from EXT operaiton mode to NET operation mode

Causa	Magauraa	Related
Cause	Measures	Parameters
Operation mode is specified with X16, X65,	Change to the NET operation mode by setting as shown below.	
and X66 signals.	(1) X66 signal is ON (when only X66 signal is assigned)	
(when X16, X65, and X66 signals are	(2) X66 signal is ON (when only X16 and X66 signals are assigned)	-
assigned)	(3) X66 signal is ON (when all X16, X65 and X66 signals are assigned)	
Command for changing to NET operation		
mode from EXT operation mode is given		
only from the operation location with NET	Change the operation mode from the operation location with control	
operation control source.	source.	-
(when X16, X65, and X66 signals are not		
assigned)		
By making parameter setting, operation		
mode can be changed.	Set a value other than 0 in communication startup mode selection (Pr.	Du 240
(when X16, X65, and X66 signals are not	<i>340)</i> to reset the inverter.	<i>PT.</i> 340
assigned)		
Destricted by perspector setting	Set 0 in operation mode selection (Pr. 79). After changing to PU	Du 70
Resulcted by parameter setting.	operation mode, change to NET operation mode.	11. / 7
Operation mode change is restricted with	When X12 signal is assigned, turn X12 signal ON. When X12 signal is	
X12 and MRS signals.	not assigned, turn MRS signal ON.	-

### Causes when changing from PU operaiton mode to NET operation mode

Cause	Measures	Related Parameters
Operation mode can not be directly changed from PU operation to NET operation with the current parameter setting.	After changing to EXT operation, change to NET operation. If the operation mode will not change to EXT operation, return to "Status Display" screen to execute troubleshooting of "EXT Operation". Change communication start up mode selection( <i>Pr. 340</i> ) to change directly to PU operation. After changing <i>Pr. 340</i> , reset the inverter.	Pr: 340
Operation mode is specified with X16, X65, and X66 signals. (when X16, X65, and X66 signals are assigned)	<ul> <li>Change to the NET operation mode by setting as shown below.</li> <li>(1) X65 signal is ON</li> <li>(2) X66 signal is ON (when only X16 and X66 signals are assigned)</li> <li>(3) X66 signal is ON (when all X16, X65 and X66 signals are assigned)</li> </ul>	-
Command for changing to NET operation mode from PU operation mode is given only from the operation location with PU operation control source. (when X16, X65, and X66 signals are not assigned)	Change the operation mode from the operation location with control source.	-

### 3.4.8 Unable to write parameter setting

#### Causes during operation

Cause	Measures	Related Parameters
Parameters can not be changed during operation with the current setting.	Change parameters after stopping operation.	
	Some parameters can be changed during operation by setting "2" in	Pr. 77
	parameter write selection (Pr. 77).	

#### · Causes related simple mode and user group setting

Cause	Measures	Related Parameters
There are restricted parameters for	Set 0 in User group read selection ( <i>Pr. 160</i> ) to cancel restrictions.	Pr. 160
displaying and changing.	operation panel or parameter unit to unlock the password lock.	Pr. 297

#### Causes related to parameter write selection

Cause	Measures	Related Parameters
Parameter write is restricted.	Set 0 or 2 in parameter write selection (Pr. 77).	Pr: 77

#### • Causes when writing from the FR-E700 inverter operation panel

Cause	Measures	Related Parameters
Parameter write command souce is not	After removing the parameter unit and USB, set "9999" in PU mode	Du 551
set.	control source selection (Pr. 551), and reset the inverter.	FT. JJ1
PU operation mode is not selected.	Change to PU operation mode.	Pr. 79, 340

#### • Causes when writing from the PU connector (operation panel/parameter unit)

Cause	Measures	Related Parameters
Parameter write command souce is not set.	<ol> <li>After removing the USB, set "9999" in PU mode control source selection (<i>Pr: 551</i>), and reset the inverter.</li> <li>After setting "2" in PU mode command source selection (<i>Pr: 551</i>), reset the inverter.</li> </ol>	Pr. 551
PU operation mode is not selected.	Change to PU operation mode.	Pr. 79, 340

### • Causes when writing from the PU connector (RS-485 communication) of the FR-E700

Cause	Measures	Related Parameters
Parameter write command souce is not set.	<ol> <li>After removing the communication option, set "9999" in NET mode command source selection (<i>Pr. 550</i>) to reset the inverter.</li> <li>After setting "2" in NET mode command source selection (<i>Pr. 550</i>) and a value other than 2 in PU mode command source selection (<i>Pr. 551</i>), reset the inverter.</li> </ol>	Pr. 550, 551
Parameter write command source is set in the PU mode	After setting a value other than "2" in PU mode command source selection ( <i>Pr. 551</i> ), reset the inverter.	Pr. 551
NET operation mode is not selected.	Change to NET operation mode.	Pr: 79, 340

### Causes when writing from the USB connector

Cause	Measures	Related Parameters
Parameter write command souce is not set.	<ul> <li>[FR-E700]</li> <li>After setting "9999, 3" in PU mode command source selection (<i>Pr. 551</i>), reset the inverter.</li> <li>[FR-A700]</li> <li>After setting "3" in PU mode command source selection (<i>Pr. 551</i>), reset the inverter.</li> </ul>	Pr. 551
PU operation mode is not selected.	Change to PU operation mode.	Pr. 79, 340

### · Causes when writing from the RS-485 terminal

Cause	Measures	Related
Parameter write command souce is not set.	<ol> <li>After removing the communication option, set "9999" in NET mode command source selection (<i>Pr. 550</i>) to reset the inverter.</li> <li>After setting "1" in NET mode command source selection (<i>Pr. 550</i>) and a value other than 1 in PU mode command source selection (<i>Pr. 550</i>)</li> </ol>	Pr: 550, 551
	551), reset the inverter.	
Parameter write command source is set in	After setting a value other than "1" in PU mode control source selection	Du 551
the PU mode	(Pr. 551), reset the inverter.	11. 331
NET operation mode is not selected.	Change to NET operation mode.	Pr. 79, 340

### Causes when writing from the communication option

Cause	Measures	Related Parameters
Parameter write command souce is not	After setting "0" in NET mode command source selection (Pr: 550) , reset	Pr. 550
set.	the inverter.	17. 550
NET operation mode is not selected.	Change to NET operation mode.	Pr. 79, 340

### 3.4.9 Unable to communicate

#### Causes related to RS-232C port

Cause	Measures	Related Parameters
Communication port setting of the PC and FR Configurator SW3 are not the same.	<ul> <li>Select [Options] in [Tool] menu. Select [Communication] tab on the option screen and check the following items.</li> <li>(1) Check "RS-232C" is selected for "PC Side Port".</li> <li>(2) Check that the COM port number of the personal computer and "Port Numer" setting are the same.</li> <li>(3) Check that the "Through" setting is "None".</li> <li>When connecting through the GOT</li> <li>(4) Check that the "Through" setting is "GOT".</li> </ul>	-

#### Causes related to RS-232C communication

Cause	Μορεικος	Related
Cause	inicasui es	Parameters
Parameter setting for PU connector communication is not an appropriate value.	<ol> <li>Check that the correct station number is set for PU communication station number (<i>Pr</i>: 117). When multiple inverters are connected, set a different station number for each inverter.</li> <li>Set 3s or more, or "9999" in PU communication check time interval(<i>Pr</i>: 122).</li> <li>Set "9999" in PU communication waiting time setting (<i>Pr</i>: 123).</li> <li>Select [Options] in [Tool] menu, and click [Communication] tab on the option screen. Check that the "Communication Speed", "Stop Bit", "Delimiter", and "Parity" settings are the same as the parameter setting for PU connector communication (<i>Pr</i>: 118, 119, 120, 124).</li> <li>Select [Options] in [Tool] menu. Click [Communication] tab on the option screen and press [Advanced]. Increase the value of "TimeQut" and "Betry Count"</li> </ol>	Pr. 117, 118, 119, 120, 121, 122, 123, 124, 549
	(6) Set "0" in protocol selection ( $Pr$ : 549).	
Parameter setting for RS-485 terminal communication is not an appropriate value.	<ol> <li>Check that the correct station number is set for RS-485 communication station number (<i>Pr. 331</i>). When multiple inverters are connected, set a different station number for each inverter.</li> <li>Set 3s or more, or "9999" in RS-485 communication check time interval(<i>Pr. 336</i>).</li> <li>Set "9999" in RS-485 communication waiting time setting (<i>Pr. 337</i>).</li> <li>Select [Options] in [Tool] menu, and click [Communication] tab on the option screen. Check that the "Communication Speed", "Stop Bit", "Delimiter", and "Parity" settings are the same as the parameter setting for RS-485 terminal communication (<i>Pr. 332, 333, 334, 341</i>).</li> <li>Select [Options] in [Tool] menu. Click [Communication] tab on the option screen and press [Advanced]. Increase the value of "TimeOut" and "Retry Count".</li> <li>Set "0" in protocol selection(<i>Pr. 549</i>).</li> </ol>	Pr. 331, 332, 333, 334, 335, 336, 337, 341, 549

3

### Causes related to RS-232C communication through GOT

Causa	Moasuros	Related
Cause	Weasules	Parameters
Parameter setting for PU connector communication is not an appropriate value.	<ol> <li>Check that the correct station number is set for PU communication station number (<i>Pr. 117</i>). When multiple inverters are connected, set a different station number for each inverter.</li> <li>Set 3s or more, or "9999" in PU communication check time interval (<i>Pr. 122</i>).</li> <li>Set "0" in PU communication waiting time setting (<i>Pr. 123</i>).</li> <li>Select [Options] in [Tool] menu, and click [Communication] tab on the option screen. Check that the "Communication Speed", "Stop Bit", "Delimiter", and "Parity" settings are the same as the parameter setting for PU connector communication (<i>Pr. 118, 119, 120, 124</i>).</li> <li>Select [Options] in [Tool] menu. Click [Communication] tab on the option screen and press [Advanced]. Increase the value of "Timeout" and "<u>R</u>etry Count".</li> </ol>	Pr. 117, 118, 119, 120, 121, 122, 123, 124, 549
Parameter setting for RS-485 terminal communication is not an appropriate value.	<ul> <li>(6) Set "0" in protocol selection (<i>Pr</i>: 549).</li> <li>(1) Check that the correct station number is set for RS-485 communication station number (<i>Pr</i>: 331). When multiple inverters are connected, set a different station number for each inverter.</li> <li>(2) Set 3s or more, or "9999" in RS-485 communication check time interval(<i>Pr</i>: 336).</li> <li>(3) Set "0" in RS-485 communication waiting time setting (<i>Pr</i>: 337).</li> <li>(4) Select [Options] in [Tool] menu, and click [Communication] tab on the option screen. Check that the "Communication speed", "Stop Bit", "Delimiter", and "Parity" settings are the same as the parameter setting for RS-485 terminal communication (<i>Pr</i>: 332, 333, 334, 341).</li> <li>(5) Select [Options] in [Tool] menu. Click [Communication] tab on the option screen and press [Advanced]. Increase the value of "TimeOut" and "Retry Count".</li> <li>(6) Set "0" in protocol selection(<i>Pr</i>: 549).</li> </ul>	Pr. 331, 332, 333, 334, 335, 336, 337, 341, 549

### Causes related to USB communication

Cause	Measures	Related Parameters
Communication port setting of the FR Configurator SW3 is not an appropriate value.	<ul> <li>Select [Options] in [Tool] menu. Select [Communication] tab on the option screen and check the following items.</li> <li>(1) Check "USB" is selected for "PC Side Port".</li> <li>(2) Check that the "Through" setting is "None".</li> </ul>	-
Parameter setting for USB connector communication is not an appropriate value.	<ol> <li>Check that the correct station number is set for USB communication station number (<i>Pr</i>: 547). When multiple inverters are connected, set a different station number for each inverter.</li> <li>Set 3s or more, or "9999" in USB communication check time interval (<i>Pr</i>: 548).</li> </ol>	Pr. 547, 548

### Causes related to USB communication via GOT

Cause	Measures	Related Parameters
Communication port setting of the FR Configurator SW3 is not an appropriate value.	<ul> <li>Select [Options] in [Tool] menu. Click [Communication] tab on the option screen and check the following items.</li> <li>(1) Check "USB" is selected for "PC Side Port".</li> <li>(2) Check that the "Through" setting is "GOT".</li> </ul>	-



This chapter explains the "FUNCTION" for use of this product. Always read the instructions before using the software.

4.1	Model Setting	84
4.2	Options	85
4.3	File Management and Print	87
4.4	Test Operation (Navigation area)	90
4.5	System View (Navigation area)	94
4.6	Parameter List (System area)	97
4.7	Convert (System area)	104
4.8	Diagnosis (System area)	121
4.9	Graph (Monitor area)	123
4.10	Batch Monitor (Monitor area)	138
4.11	I/O Terminal Monitor (Monitor area)	140
4.12	I/O Terminal Assignment	141
4.13	Machine Analyzer (Monitor area) (FR-A700 with Vector Control)	142
4.14	Help	147

### 4.1 Model Setting

Make setting of inverter model in "Model Setting" window. There are following ways to display "Model Setting" window.

- (1) Select [Model Setting] in [Tool] menu.
- (2) Double-click a station number in "System Setting" of System View.



No.	Name	Function and description
Α	St. <u>N</u> o.	Set the inverter station number from 0 to 31.
В	C <u>o</u> mment	A field for comments.
С	Inverter	Select the connected inverter model.
D	<u>C</u> apacity	Select the connected inverter capacity.
E	Option Connector 1 to 3,	Select the option connected to an option connector. (Option Connector 1 to 3 is available for FR-A700
	Terminal Block 3	series)
F	OK	Reflects the Model Setting into the system, and closes the "Model Setting" window.
G	Cancel	Returns to the Main frame with the setting made invalid.
н	<u>A</u> pply	Reflects the Model Setting into the system.
I	Help	Displays Help window. (Refer to page 147)

### () REMARKS

Inverter model will change if capacity or option setting field is changed, therefore current value, setting value and comment in "Parameter List" are also cleared. If you want to reuse the current value, setting value and comment, export the "Parameter List" data beforehand, and then change the model setting. After making model setting, import the exported data in "Parameter List" window to reuse the current setting, setting value and comment.

### 4.2 **Options**

Communication and preference setting is available in "Option" window. Displays the communication and preference setting windows by switching tabs.

Select [Options] in [Tool] menu to display "Option" window.

### 4.2.1 Communication

Click Communication [ of "Option" window to make a communication setting.

	Option
	Communication Method
	PC side <u>Port</u> Port Number T <u>hrough</u> RS-232C Set following parameter for RS-232C communication with the inverter.
Α ——	Set a value other than 0 in Pr. 122 PU communication check time interval
	Communication Speed     19200     bps     Stop Bit     2     bit       Data Length     8     bit     Delimiter     CR     Image: CR       Parity     Even     Image: CR     Image: CR     Image: CR
	Default <u>Value</u> A <u>d</u> vanced
	Communication Preferences
	в с D Е

No.	Name	Function and description
Α	Setting items	Refer to page 45 for details of each communication setting items.
В	OK	Closes Option window with the setting made valid.
С	Cancel	Closes the window with the setting made invalid.
D	<u>A</u> pply	Reflects the setting into the system without closing the window.
E	Help	Displays Help window. (Refer to page 147)

### The REMARKS

- Communication setting window is active only when OFFLINE. During ONLINE, every item is turned gray and unavailable for making setting.
- When "USB" is selected for personal computer side port, unnecessary setting item turns to gray and unavailable for making setting.

4

### 4.2.2 Preferences

Test operation setting is available.

Click Preferences of "Option" window to display the Preferences window.



No.	Name	Function and description
А	Release Test Operation	If checked, clicking we or we button of the test operation window once keeps the motor
		running.

#### Note

• When test operation is being performed, check button of "Release Test Operation" can not be checked.

 Setting of "<u>Release Test Operation</u>" is not stored. At starting of the FR Configurator, this setting is always return to unchecked.

# 

When communication is stopped (cable disconnection, etc.), personal computer can not stop the inverter. Make sure that safety precaution is provided with using signal loss detection (*Pr. 122, Pr. 336, or Pr. 548*), or installing an external stop command device.

### 4.3 File Management and Print

### 4.3.1 Type of files

Extension	Description Corresponding screen		Refer to Page
*.me3	Manages system setting, model information, data of Parameter List and Graph with a single file.		-
*.gp3	Manages Graph sampling data at the moment of exporting. Graph		123
*.pr3	Manages Parameter List data at the moment of exporting (text format).       Parameter List         Used to copy the parameter setting into the other inverters.       Parameter List		97
*.hdt	Manages retrieved data of Machine Analyzer at the time of exporting. Data created by the FR Configurator SW2 can be read too.	Machine Analyzer	142

### 4.3.2 Open

"Open" is a command to read data such as model information and other functions in system file (me3), and reflect to each screens. (For \*.gp3 or \*pr3 file, data can be read using [Import] at a window of each function. *Refer to page 88*) Select [Open] in [File] menu to display "Open" window. Select the desired file, and click \_\_\_\_\_\_\_ to read the saved data. Whether each function screens are currently displayed or not, data in the file are reflected into each functions.

### REMARKS

- When copying the current value of the parameter to other station or other inverter, use import and export of data (\*.pr3).
- System file (\*.mel) of older version (FR Configurator SW2) can not be opened. In this case save the parameter setting of the FR Configurator SW2 into PRM file and import it to FR Configurator SW3.
- When several station settings exist, it may take several tens of seconds to open a system file.

### 4.3.3 Save

Select [Save <u>As...</u>] in [<u>File</u>] menu to display "Save As" window. Check the saving location, put a name on a file, and save. Select [<u>Save</u>] in [<u>File</u>] menu to save the file with the same name. When saving a file for the first time, the same window as "Save As" is displayed.

### 4.3.4 Data import and export (File input and output)

Data of Graph and Parameter List can be input or output as a file. When copying parameter settings to other inverter, export data of the Parameter List, and import it to the other inverter for copying.

#### (1) Import (file input)

Exported data of Graph or Parameter List can be read (import) and reflected into a screen. Select [Import] in [File] menu to display a window for selecting the importing file.



• Importing data of "Graph" is available only when inverter type, capacity, model and option connector are all matched with the exported data.

Importing data of "Parameter List" is available when inverter type is matched with the exported data.

#### (2) Export (file output)

Data of "Graph" or "Parameter List" can be output (export) into a file separately to the system file. Select [Export] in [File] menu to display a window for exporting file. The exported file can be imported (displayed) with "Graph Function" and "Parameter List".



## • Exported file is saved in a text format. If the contents of the file is edited, the file may not be read correctly when importing. Do not edit the contents of the exported file.

#### REMARKS

Parameter file (\*.prm) of older version S/W (FR Configurator SW2) can not be imported. Note that exported file is pr3 format.

Import and export of "Parameter List"

Exported file of Parameter List contains both "Current" field data and "Setting" field data.

When importing the exported file, select which data to be imported between "Current" value or "Setting" value in the file ("Selection of Import Data" window is displayed after selecting a file). And the selected data is reflected into "Setting" field of the Parameter List.



#### 4.3.5 Print

The FR Configurator window can be printed as-is. The Parameter List can be printed as a list. Select [Print...] from the [File]

menu or click

of the tool bar.

Please make printer setting beforehand.

Print



### POINT

For printing specific screen, hide other unused screens to print the one you want. (*Refer to page 37*)
As for the parameter list, you can select between printing in a list form and printing as is displayed. Select in a window displayed at printing.

## **4.4 Test Operation (Navigation area)**

Frequency (fault) indication, operation mode indication and switching, sending of forward/reverse rotation command and writing of the set frequency is available.



the FR Configurator. If operation continues unintentionally, press **STOP** to stop operation.

### 4.4.1 Test Operation screen



No.	Name	Function and description
А	Frequency (Speed) indication	Shows frequency (speed) or fault indication etc. of the selected inverter.
В	Set frequency (speed) input field	Input the set frequency and click to write the set frequency to the selected inverter. Pressing while the field is empty shows the output frequency of the selected station.
С	<u>S</u> ET	Writes the value of "Frequency (speed) input" field as the set frequency of the selected inverter.
D	ST <u>O</u> P	Sends stop command to the selected inverter.
Е	<u>P</u> U	Changes the operation mode of the selected inverter to PU operation mode.
F	EXT	Changes the operation mode of the selected inverter to external operation mode.
G	<u>N</u> ET	Changes the operation mode of the selected inverter to network operation mode.
Н	Operation mode indication	Shows the operation mode of the selected inverter in red.
I	Rotation direction indication	At forward rotation, "FWD" turns red, and at reverse rotation "REV" turns red.
J	FWD	Sends forward rotation command to the selected inverter. Performing test operation during the button is pressed. (When Release Test Operation is selected, clicking button once keeps operation. <i>Refer to page 85</i> )
к	REV	Sends reverse rotation command to the selected inverter. Performing test operation during the button is pressed. (When Release Test Operation is selected, clicking button once keeps operation. <i>Refer to page 85</i> )

### 4.4.2 Indication of inverter frequency and fault

Shows output frequency or fault indication etc. of the selected inverter. If model setting of the selected station has been made and set to ONLINE, the indicator shows output frequency. During OFFLINE, or if model setting of the selected station has not been made, indicator turns to blank. If unit of frequency (speed, machine speed) has been changed by parameter setting, output frequency of selected station is indicated along with the change of the unit.

JOG, PS, PU STOP, Pr. CL, PCPY, Warning and Alarm are not displayed.



### 4.4.3 Indication of operation mode and switching

Click <u>PU</u>, <u>EXT</u>, <u>NET</u> to switch the operation mode. Operation mode of the selected inverter is shown at the operation mode indicating part.



#### REMARKS

• Depending on the current operation mode or parameter setting, some operation mode are unavailable for change. For example, at the initial state, switching between PU operation mode and network operation mode is unavailable. (*Refer to page 24 or the inverter manual for details.*)

4

### 4.4.4 Setting of running frequency (speed, machine speed)

Input set frequency (speed, machine speed) in "Frequency (Speed) input" field, and click into the inverter. Use the button on the right of input field, to add or decrease the setting frequency by minimum setting increments. (Available only when ONLINE.)



When the set frequency is written, "F" and the set frequency is displayed alternately 3 times. After displaying 3 times, the display shows output frequency (speed, machine speed).



### 4.4.5 Sending of forward/reverse rotation command

inverter.

- · When performing inverter test operation Test operation is performed during [FWD], REV is pressed. To stop the test operation, release FWD , REV РU NET PU EXT NET Displays inverter running frequency Perform test operation during Freguency (Sp FWD REV. the button is pressed 60.00 SET STOP · At releasing of test operation Releasing test operation enables operation to continue by pressing **FWD** or **REV** once. Press **STOP** to stop operation. To release test operation, select [Options] in [Tool] menu to display "Option" window (Refer to page 86). Click references, then check "Release Test Operation" on the Preferences window and click ( or Apply ). Note • If the selected station has been changed during Test Operation, FR Configurator sends stop command, and stops the
  - Due to Windows operation style, test operation may be kept operating without pressing FWD or REV if the following movement is made. To stop the operation, click STOP.

Dragging a mouse cursor out of FWD or REV while the button is pressed.

Test operation ( \_\_\_\_\_\_, \_\_\_\_, does not function during graph sampling of two or more stations with communication through GOT (FA transparent function).

# 

▲ When communication is stopped (cable disconnection, etc.), personal computer can not stop the inverter. Make sure that safety precaution is provided with using signal loss detection (*Pr. 122, Pr. 336, or Pr. 548*), or installing an external stop command device.

Δ

### 4.5 System View (Navigation area)

"System Setting" (*Refer to page 95*), "Troubleshooting" (*Refer to page 65*) and "Setting Wizard" (*Refer to page 96*) can be displayed in System View by switching tabs.



Switching of the display is also available using [Navigation] sub-menu in [View] menu.

### 4.5.1 System Setting

Function for browsing setting information of all 32 stations. Click <u>System Setting</u> in System View or select [System Setting] submenu under [Navigation] of [View] menu to display "System Setting".



No.	Name	Function and description
А	Station number, inverter type	Shows station number and inverter type.
В	OFFLINE	Changes to OFFLINE. (Disconnect all inverters registered to the system)
С	ONLINE	Changes to ONLINE. (Connect to all inverters registered to the system)
D	ON, OFF indicator	Shows ONLINE, OFFLINE state.
E	System Setting	Right-click the item on "System Setting" to display a pop-up menu. System Batch Read (Refer to page 48) is available from the pop-up menu.
F	Station number, inverter type	<ul> <li>Shows inverter type on the right of station number if model setting has already made to that station number.</li> <li>Clicking the station number selects the station number. (Press ↑ or ↓ to select the station number set upward or downward.</li> <li>Click 🖶 on the left of the icon to open a tree view for checking a detail of the model setting.</li> <li>Double-click on the station number to display Model Setting window.</li> </ul>
G	Comment	Displays a comment.
Н	OP1 to OP3	Shows a name of plug-in option installed to the selected inverter.

### 4.5.2 Setting Wizard

Setting Wizard is a function to make parameter setting without regard to parameter number. Double-click a desired function in the "Setting Wizard" (or select the function and click <u>Execute</u>) to start the Setting Wizard of the selected function.

Click **Setting Weard** in System View or select [Setting <u>Wizard</u>] sub-menu under [Navigation] of [View] menu to display "Setting Wizard".



No.	Name	Function and description	
Α	Inverter type information	Shows station number, inverter type, capacity and comment of the selected inverter.	
		Shows Setting Wizard items. Select a desired function (Up-key and Down-key is also available) and	
В	Setting Wizard item	double-click (or click <b>Execute</b> ) to start the Setting Wizard of the selected function ( <i>Refer to page 56</i> ).	
		(If Model Setting has not made yet, color turns gray and unavailable to select.)	
С	Execute	Click to start the Setting Wizard of the selected function. (Refer to page 56)	
		(If Model Setting has not made yet, color turns gray and unavailable to select.)	

#### 4.6 **Parameter List (System area)**

"Parameter List" has following functions.

- Showing parameters (all list, functional, individual, changed parameter, verification result parameter)
- Editing Individual List
- Reading and batch reading of parameter setting value
- · Input, writing and batch writing of parameter setting value
- · Parameter clear and all parameter clear
- Parameter verification (verifies parameter values set on the FR Configurator and values already written into the inverter)
- · Parameter searching
- File output of parameter verification results, batch read, and batch write.
- Writing of comment
- Parameter copy (use import/export. Refer to page 88.)

Select [Parameter List] under [View] menu, or click on the tool bar to display "Parameter List". Parameter List

Functions available in "Parameter List" is different between ONLINE or OFFLINE.

Function	ONLINE	OFFLINE
All Parameter Clear	0	×
Parameter Clear	0	×
Batch Read	0	×
Batch Write	0	×
Verification	0	×
Read	0	×
Write	0	×
Input of parameter setting value	0	0
Edit Individual List	0	0
Search	0	0
Display list selection	0	0
Writing of comment	0	0



#### Note

Parameter name in an inverter manual and the one in FR Configurator can be different, but the function of each parameter is the same. • *Pr. 296 and 297* are not shown in Parameter List. *Pr. 296 and 297* do not change when importing parameter setting from

other inverters. Change the Pr. 296 and 297 setting from the operation panel or parameter unit.

### 4.6.1 Explanation of screen



No.	Name	Function and description			
Λ	Parameter List display	Select a "Parameter List" display format. Click ▼ to display format of "Parameter List" from the			
A	format	menu. (Refer to page 99)			
В	All clear	Performs all parameter clear with the connected inverter.			
С	Parameter Clear	Performs parameter clear with the connected inverter.			
D	Batch Read	Reads all parameter settings of the connected inverter.			
Е	Batch Write	Writes values of Setting value field into the the connected inverter.			
F	Verification	Verifies parameter values set on the FR Configurator and values already written into the inverter.			
G	Read	Reads a current value of the selected parameter from the connected inverter.			
Н	Write	Writes a setting value of the selected parameter into the the connected inverter.			
Ι	Search	Displays Search window. (Refer to page 103)			
J	Edit Individual List	Click to edit parameter Individual List. (Refer to page 103)			
K	ALL List	Returns display format of the Parameter List to All Parameter List.			

ltem	Function and description			
Shows parameter number. When the current value and parameter initial value is different, " > " appear				
No.	next to the number and the color turns green.			
	(Calibration parameters, Pr. 902, 903, 904, 905 etc. are displayed with ().)			
Name	Shows parameter name.			
Setting Range	Shows setting range.			
Unit	Shows minimum setting increments.			
Initial Value	Shows parameter initial value.			
Current Value	Shows the value read from the inverter or the value written to the inverter.			
Setting	Input a value desired to write to the inverter. Click <u>wite</u> or <u>Batch wite</u> to write the value into the inverter. (Numeric value and a decimal point can be input up to 6 characters including a decimal point.)	0		
Comment	A field for comments. Available to write one byte code up to 128 characters (2 byte code up to 64 characters).	0		

### 4.6.2 Parameter List Display Format

Display format of "Paramter List" can be changed to other display format according to your purposes. Click 💌 and select a display format from the list menu to change the display.

Parameter	List							
All cle	ear Paramet	eter Clear Batch Read B		Batch Write Verification		fication		
All Parame	eter List ameter List	<u> </u>					ALL List	Switch to All Parameter List
Function Individu	nal Parameter List → al Parameter List	Motor/T Frequen Accelera	orque cy Setting ation/Deceleration		Unit 0.1% 0.01Hz	<sup>7</sup> Initis I Value 6 120	Current	
Verifica 4	d Parameter List ation Results [Multi-speed setting (hic	Protectio Monitor Braking	on		0.01Hz 0.01Hz 0.01Hz	0 60 60		
5	Multi-speed setting (min Multi-speed setting (low	Termina Magnetic Intelliger	l Assignment c Flux Vector nt		0.01Hz 0.01Hz	30 10		Click to display List Display Menu
7 8 9	Acceleration time Deceleration time Electronic thermal O/L	Calibrati Option Special	ion Operation		0.1s 0.1s 0.01A	5 0.68		
10	DC injection brake ope frequency	ration	U to 120Hz	1/	0.01Hz	3		<ul> <li>Select a display format from List Display Menu</li> </ul>
11	DC injection brake ope	ration time	U to 1Us		U.1s	0.5		

Display Format	Description
All Parameter List	Displays all parameters of the selected inverters.
	(Option parameter of the selected inverter is displayed when selecting Option.)
Functional Parameter list	Select a desired function from the sub-menu to display related parameters.
	"Functional parameters" - "funtion name" are displayed on the list field.
Individual Parameter List	Displays parameters set in the individual list.
Changed Parameter List	Displays parameters whose setting is different from the initial value.
	(Displays parameters which have ">" at parameter number.)
Verification Results	Displays parameters of verification result. Displays verification result performed last time. ( <i>Refer to page 102</i> )

Changed Parameter List and Verification Results can be displayed along with other display format.

### Parameter List items according to the FR-A700 series functions

Function	Description	
Basic Functions	Basic function parameters	
Frequency Setting	Parameters related to frequency	
Acceleration/	Parameters related to acceleration/deceleration	
Deceleration Setting		
V/F Characteristic	Parameters related to V/F characteristic	
Protection	Parameters related to protective function	
Operation Mode	Parameters related to operation mode	
Monitor	Parameters related to monitor function	
Braking	Parameters related to frequency, time, etc. at brake operation	
Terminal	Parameters related to control circuit terminal	
Additional Function	Other parameters	
Maintenance	Parameters related to maintenance	
Magnetic Flux Vector	Parameters related to advanced magnetic flux vector control (general-purpose magnetic flux vector control)	
Vector	Parameters related to vector control	
Calibration	Parameters for calibrating terminal FM, AM and setting bias/gain of frequency (speed) setting voltage and	
Calibration	current.	
Communication	Parameters related to communication	
Option	Parameters related to option	

### Parameter List items according to the FR-E700 series, FR-D700 series and FR-F700 series functions

Function	Description			
Motor/Torque	Parameters related to motor and torque			
Frequency Setting	Parameters related to frequency			
Acceleration/				
Deceleration				
Protection	Parameters related to protective function			
Monitor	Parameters related to monitor function			
Braking	Parameters related to frequency, time, etc. at brake operation			
Terminal Assignment	Parameters related to control circuit terminal			
Magnetic Flux Vector	lagnetic Flux Vector Parameters related to advanced magnetic flux vector control (general-purpose magnetic flux vector control)			
Intelligent	Parameteres related to intelligent mode which automatically set appropriate parameters and operate.			
Calibration	Parameters for calibrating terminal FM, AM and setting bias/gain of frequency (speed) setting voltage and			
Calibration	current.			
Option	Parameters related to option			
Special Operation	Parameters related to special operation such as communication, program operation which are set before acual			
Special Operation	use.			

### 4.6.3 Parameter clear and all parameter clear

Performing parameter clear or all parameter clear can initialize parameter setting value.

Click Parameter Clear or All clear to display the following dialog to confirm the parameter clear or all parameter clear. Refer to the inverter manual for availability of parameter clear and all parameter clear for each parameters.



No.	Name	Function and description
А	Icon display of clearing	Icon display switches during parameter clear.
В	ОК	Click to perform parameter clear. (The color turns to gray during parameter clear, and unavailable to use.)
С	Cancel	Click to cancel parameter clear. (The color turns to gray during parameter clear, and unavailable to use.)
D	Message	Shows a message to confirm parameter clear, and shows a message during parameter clear.

#### REMARKS

When parameter clear or all parameter clear were performed from the FR Configurator, the following communication parameters are not cleared. Refer to the inverter manual or communication option manual for details of each parameter.

Pr. 117, Pr. 118, Pr. 119, Pr. 120, Pr. 121, Pr. 122, Pr. 123, Pr. 124, Pr. 331, Pr. 332, Pr. 333, Pr. 334, Pr. 335, Pr. 336, Pr. 337, Pr. 338, Pr. 339, Pr. 340, Pr. 341, Pr. 345, Pr. 346, Pr. 347, Pr. 348, Pr. 349, Pr. 409, Pr. 431, Pr. 434, Pr. 435, Pr. 436, Pr. 438, Pr. 439, Pr. 440, Pr. 452, Pr. 500, Pr. 502, Pr. 539, Pr. 541, Pr. 542, Pr. 543, Pr. 544, Pr. 547, Pr. 548, Pr. 549, Pr. 550, Pr. 551

4
### 4.6.4 Read (Batch Read), Write (Batch Write) and Verification

С

Performing Read or Write gains access to inverter parameter, and parameter reading and writing is performed. Performing Verification verifies parameter values set on the FR Configurator and one already written in the inverter.



	icon display during access					
В	Cancel	Click to cancel batch read, batch write or verification. If is clicked, access is canceled and data already processed are displayed.				
С	Message	Shows a message during parameter access.				

After verifcaton, the following dialog appears. The results can be saved as a text file. (Also appears at reading error and writing error.)



No.	Name	Function and description								
А	Result	Shows result	hows result message.							
		Read	Shows parameter number, name, initial value, and error number of the reading error parameters.							
В	Result list	Write	Shows parameter number, name, data, and error number of the writing error parameters.							
		Verification	Shows parameter number, name, FR Configurator current value, and inverter read value of unmatched parameter between FR Configurator and the inverter.							
С	Export to File	Saves the re	sult in text format.							
	<ul> <li>Note</li> <li>When changing so value of related pa For example, if <i>Pr</i> deceleration time setting to "1" will a If parameter writing</li> <li>Parameter Clear or</li> </ul>	me specific pa rameters may : 21 Accelerati parameters (F utomatically cl g is performed All clear	arameters ( <i>Pr. 21 Acceleration/deceleration, Pr. 71 Applied motor etc.</i> ) with FR Configurator, setting also change. <i>ion/deceleration time increments</i> setting has been changed, the setting value of acceleration/ <i>Pr. 7, Pr. 8 etc.</i> ) may also change. (When <i>Pr. 21</i> ="0", and <i>Pr. 7</i> = "5.0s", and changing <i>Pr. 21</i> hange the setting of <i>Pr. 7</i> to "0.5s".) d with <u>Batch Write</u> or <u>Write</u> which causes a change of related parameters, or if is performed, the following dialog is displayed. Please perform update of parameter display.							
			Parameter writing completed. Current value and nuclements of other parameters may have been changed. Update the parameter display?							

• When "1" is set in *Pr. 342 Communication EEPROM write selection*, the parameter setting set from the FR Configurator is written into RAM only (can not be written to EEPROM). In addition, since batch write will perform writing process from the top, if *Pr. 342* is set to "1", parameters after *Pr. 342* are written to RAM only.

No No

### 4.6.5 Edit Individual List

Select and add parameters desired to register into the individual parameter list.

Click Edit Individual List in "Parameter List" window to display the following window.



No.	Name	Function and Description
А	Parameter List	Displays number and name of all parameters. Select a parameter and click to add it in
		the individial parameter list. Several parameters can be selected.
В	<u>A</u> dd >>	Adds parameters selected in the Parameter List in the individual list.
С	<< Delete	Deletes parameters selected in the individual list.
D	ОК	Saves edited information of the individual list and returns to the Parameter List window.
E	Cancel	Parameters set in the individual list are made invalid and reutrns to the Parameter List.
E	Individual List	Displays parameters added from the Parameter List.
	Inuiviuudi List	Parameters selected from the list are displayed in the individual Parameter List.

### 4.6.6 Parameter Search

Parameter name can be searched. Input searching character string, to jump to the matching parameters. Click Search in "Parameter List" window to display the following window.



No.	Name	Function and Description
Α	Search String	Input character string you like to search. Up to 64 double-byte characters can be input.
В	Case Sensitivity	Check when distinguishing between upper case and lower case.
С	Search Upward	Click to seach the parameter list upward.
D	Search Downward	Click to seach the parameter list downward.

### 4.7 Convert (System area)

Converting a parameter setting from a conventional model into 700 series inverter parameter setting is available. Select [Convert] in [View] menu to display "Convert".

• Compatible models for Convert

Source Inverter	Target Inverter	REMARKS
FR-V520(L)	FR-A720	Setting of plug-in options is changed. (Refer to page 113)
FR-V540(L)	FR-A740	Setting of plug-in options is changed. (Refer to page 113)
FR-A520(L)	FR-A720	
FR-A540(L)	FR-A740	
FR-A560(L)	FR-A760	
FR-E520	FR-E720	
FR-E520S	FR-D720S	
ED E540	FR-E740	
FR-E340	FR-D740	
FR-F520(L)	FR-F720	Setting of plug-in options is changed. (Refer to page 113)
FR-F540(L)	FR-F740	Setting of plug-in options is changed. (Refer to page 113)
FR-S520S(E)	FR-D720S	
FR-S540(E)	FR-D740	



Note

Parameter name in an inverter manual and the one in FR Configurator can be different, but the function of each parameter is the same.

#### 4.7.1 Convert image

performance, etc.



## 4.7.2 Explanation of window

	Convert											
≻	Source Information Set the information of the source inverter. Click to select a setting method.											
>	Perform parameter convert.											
≻	Reflect to	the Target	Reflect the co	inverted param	eter into the c	onne	cted inverter	parameter, or save to a	parameter file	(PR3).		
≻	Simultaneous Scroll of both Parameter List.     Clear Data											
►		Sour	ce: FR-E520-0."	1K		_		Targe	t FR-E720-0.	1K		
2	No.	Name	Unit	Initial Value	Settine	-	No.	Name	Unit	Initial Value	Setting	
/	0	Torque boost	0.1%	6	6		0	Torque boost	0.1%	6	6	
	>1	Maximum frequency	0.01 Hz	120	110		×	Maximum frequency	0.01 Hz	120	110	
	2	Minimum frequency	0.01 Hz	0	0		2	Minimum frequency	0.01 Hz	0	0	
	3	Base Frequency	0.01 Hz	60	60		3	Base Frequency	0.01 Hz	60	60	
	>4	Multi-speed setting (high speed)	0.01 Hz	60	65	1	>4	Multi-speed setting (high speed)	0.01 Hz	60	65	
	5	Multi-speed setting (middle speed)	0.01 Hz	30	30		5	Multi-speed setting (middle speed)	0.01 Hz	30	30	
	6	Multi-speed setting (low speed)	0.01 Hz	10	10		6	Multi-speed setting (low speed)	0.01 Hz	10	10	
	7	Acceleration time	0.1s	5	5		7	Acceleration time	0.1s	5	5	
	8	Deceleration time	0.1s	5	5		8	Deceleration time	0.1s	5	5	
	9	Electronic thermal O/L relay	0.01 A	0.68	0.68		9	Electronic thermal O/L relay	0.01 A	0.68	0.68	
	10	DC injection brake operation frequency	0.01 Hz	3	3		10	DC injection brake operation frequency	0.01 Hz	3	3	
	11	DC injection brake operation time	0.1s	0.5	0.5		11	DC injection brake operation time	0.1s	0.5	0.5	
	12	DC injection brake voltage	0.1%	6	6		12	DC injection brake operation voltage	0.1%	6	6	
	13	Starting frequency	0.01 Hz	0.5	0.5		13	Starting frequency	0.01 Hz	0.5	0.5	
	14	Load pattern selection	1	0	0		14	Load pattern selection	1	0	0	
$\setminus$	15	Jog frequency	0.01 Hz	5	5		15	Jog frequency	0.01 Hz	5	5	
	16	log	01s	0.5	0.5	-	16	Jog	0.1s	0.5	0.5	

No.	Name	Function and description
Α	Source Information	Displays "Convert Method" window. Set converting method, source and target model setting.
в	Parameter Convert	Displays "Convert Confirmation" window. Parameter converting is available.
В	i arameter convert	(Click after converting method, source and target model information is set.)
		Displays "Parameter saving" window. Reflect the converterd setting into a Parameter List of the
С	Reflect to the Target	selected inverter. Saving to a parameter file (PR3) is also available.
		(Click after the parameter is converted.)
		Checked : When scrolling one of source/target parameter list, the other parameter list goes scrolling
П	Simultaneous Scroll of both	too.
D	Parameter List	Without check : Even when scrolling one of source/target parameter list, the other parameter list
		does not scroll.
Е	Source inverter information	Shows the inverter type of the source.
F	Parameter List of source	Shows parameter setting read from the source. " >" appears next to the parameter number of which
1		the setting has been changed, and also a color turns green.
G	Clear data	Initialize the all setting data. Confirmation dialog is displayed when clicked. Click res to
G		initialize when a confirmation dialog is displayed.
Н	Target inverter information	Shows the inverter type of the target.
	Decemptor List of torget	Shows converted parameter setting. " > " appears next to the parameter number of which the setting
	Parameter List of target	has changed, and also a color turns green.

[Select an Inverter

### 4.7.3 Example of converting

#### (1) When selecting an inverter from a model list

- 1) Click <u>source internation</u> in "Convert" window to display "Convert Method".
- 2) Choose "Select an Inverter from a <u>M</u>odel List". Click

- Set the infomation of the source inverter in "Model Setting". Fill in the each items of the source inverter. Click determined after setting.
- A parameter requiring caution is displayed in a list.
   Parameter in the list is converted with an initial value.
   Click Mexton after confirmed.

(If a setting of parameter in the list is required, uncheck "Use Initial Value for all parameter", and change the required parameter setting.)

5) Select the target inverter on the "Target Inverter" window, and the convert setting is finished. Click







6) The value of some of the source parameter is available for changing. When changing the parameter setting value, enter a changed value in Setting field.
 When the convert setting is finished, <u>Parameter Convert</u> in "Convert" window becomes available. Click <u>Parameter Convert</u>

to display "Convert Confirmation".

#### Click to display "Convert Confirmation"

anvert					_						
Source	e Leormation	Set the	information o	f the source	int	rter. Oliak ta	select a setting net	hed.			
Paron	vetor Convert	Perform	parameter o	rvert							
	to the Tancel	Reflect									
Sincl	taneous Scrall of both	Parameter	List						Cle	or Dota	
	Source	: FR-E520-I	01K				Targe	t FR-E120-0	11K		
No.	Nerve	Unit	Initial Velos	Setting	•	Na	Name	Unit	<b>Evital Value</b>	Settine	E.
0	Torque boost	018	6	6		0	Torque boost	01%	6		10
1	Macinum	0.01 Hz	120	123	1	1	Maximum	0.01 Hz	120		1
2	Minimum frequency	0.01 Hz	0	0		2	Minimum	0.01 Hz	0		1
3	Base frequency	0.11 Hz	60	60		3	Base frequency	0.01 Hz	60		
4	Multi-speed setting frigh speed	0.01 Hz	80	80		4	Multi-speed setting frigh speed	0.01 Hz	60		1
5	Multi-speed setting (middle speed)	0.11 Hz	30	30		5	Multi-speed setting (middle speed)	0.01 Hz	30		1
6	Multi-speed setting Open speed)	0.01 Hz	10	10		6	Multi-speed setting Oon speed	0.01 Hz	10		1
7	Acceleration time	810	5	5		7	Acceleration time	010	5		d.
0	Deceleration time	D1s	5	5		0	Deceleration time	D1s	5		ъ
9	Electronic thermal 0/% selay	031 A	0.68	0.68		9	Electronic thermal O/L relay	A 11.0	0.68		1
10	DC injection brake operation frequency	0.01 Hz	3	3		13	DC injection brake operation frequency	0.01 Hz	3		1
11	DC injection brake operation time	010	0.5	05		11	DC injection brake operation time	010	0.5		

4

### 🌮 Convert (System area)

- Check the information of the source inverter and target inverter. Click <u>convert</u> to convert the parameter.
- 8) Click <u>Einish</u> when "Parameter converting is finished." is displayed.



9) Results of parameter converting is shown in "Convert" window.



- 10) Click <u>Perfect to the Target</u> in "Convert" window to display "Parameter Saving".
- 11) Check "Reflect in a Parameter List of the Selected <u>Station</u>", and <u>Enish</u> to reflect the converted parameter setting into the Parameter List. If a station has not finished model setting or the inverter model is different, that station is unavailable to select.
- 12) When saving the converted parameter setting as a file, check "Save <u>As</u>". Specify the file location, and click
   <u>Enish</u> to save the converted parameter setting into a parameter file (PR3).





#### (2) When convert from a parameter file (PRM)

- 1) Click <u>Source Information</u> in "Convert" window to display "Convert Method".
- 2) Select "Convert from a <u>P</u>arameter File (PRM)". Click



- Select the converting parameter file in "Select Parameter File" screen. Click \_\_\_\_\_ to display "Open" window. Select a parameter file in that window.
- 4) Click File Read to read the selected parameter file.
   "Selection of Import Data" is displayed. Select between Current Value or Setting Value for use. (*Refer to page 88*) Check File Read result, and click Next
- 5) Select the target inverter on the "Target Inverter" window, and the convert setting is finished. Click





- 6) The value of some of the source parameter is available for changing. When changing the parameter setting value, enter a changed value in Setting field.
  When the convert setting is finished, <u>Parameter Convert</u> in "Convert" window becomes available. Click <u>Parameter Convert</u> to display "Convert Confirmation".
- 7) Check the information of the source inverter and target inverter. Click convert the parameter.
- 8) Click <u>Einish</u>, when "Parameter converting is finished" is displayed.

#### Click to display "Convert Confirmation"





4

 Results of parameter converting is shown in "Convert" window.



- 10) Click <u>Perfect to the Target</u> in "Convert" window to display "Parameter Saving".
- 11) Check "Reflect in a Parameter List of the Selected Station", and <u>Emish</u> to reflect the converted parameter setting into the Parameter List.

If a station has not finished model setting or the inverter model is different, the station is unavailable to select.

12) When saving the converted parameter setting as a file, check [Save As]. Specify the file location, and click
 <u>Einish</u> to save the converted parameter setting into a parameter file (PR3).

Convert - FR Configurator SW3		
(Source Inverter)FR-E520-0.1K : (Target Inverter)FR-E720-0.1K		
Select a way of saving parameter, and click "Finish".		
Reflect in a Parameter List of the Selected Station		
St. No.		
1.0 Model HHE72D0.1K Comment		
C SaveAs		
,		
Help	Cancel	Einish



### The REMARKS

 $(\bullet)$ 

- Parameter file (PRM) is a text format file. If an nonexistent parameter is added to the source, a caution shown on right appears. The data about nonexistent parameter is not converted.
- If the parameter file (PRM) is broken, a caution shown on right appears when reading the file. In this case, select a normal parameter file, and perform read file again.
- If the parameter file (PRM) is a one from not-compatible inverter, a caution shown on right appears. In this case, select a parameter file of the compatible inverter, and perform Read File again.

Some unmatched parameter was detected.
Failed to read file.

Unsupported model for Convert was detected.

#### (3) When converting from the Connected Inverter through Communication

### POINT

Perform during a inverter stop. Do not input a start command.

1) Check that FR Configurator is ONLINE. (Click

### REMARKS

If FR-E500 is connected to the station number where FR-E700 is set for system setting, switching to ONLINE will display a communication error dialog. In this case, click OK, and proceed converting.

- 2) Click <u>source internation</u> in "Convert" window to display "Convert Method".
- Choose "Convert from the Connected Inverter through Communication". Click detection after selecting.



[Convert from the Connected Inverter through Communication]

4) Click <u>Detect Inverter</u> in "Connected Inverter Detection" window. Check the inverter detection result, and click
 <u>Next></u>.



5) Select the target inverter on the "Target Inverter" window, and the convert setting is finished. Click Enish

6) The value of some of the source parameter is available

value, enter a changed value in Setting field.

to display "Convert Confirmation".

for changing. When changing the parameter setting

When the convert setting is finished, Parameter Convert in "Convert" window becomes available. Click Parameter Convert



Click to display "Convert Confirmation"

Source	e Marmation	Set the	information o	the source	inver	ter, Olick to	select a setting met	×06.		
Parce	neter Convert	Perform	parameter oc	nat						
Reflec	to te Target	Petlect	he converted		nto ti				parameter fi	6 (PR3).
Sinal	taneous Scroll of both	Parameter	List.						Cie	or Dota
	Source	FR-EE20-0	11K				Tanpot	FR-E720-0	18	
					-					Setting
0	Tongue boost	0.18	6	6		0	Tarque boost	0.18	6	
1	Macimum frequency	E01Hz	120	120		1	Maximum frequency	0.01 Hz	120	
2	Minimum trequency	D01Hz	0	0		2	Minimum trequency	0.01 Hz	0	
3	Base frequency	001Hz	60	60		3	Base frequency	0.01Hz	60	
4	Multi-speed softing Righ speed)	DOTHE	60	60		4	Multi-speed opting thigh speed?	0.01 Hz	63	
5	Multi-spred softing (middle spred)	001Hz	30	30		5	Multi-speed setting (middle speed)	0.01 Hz	20	
6	Hulti-speed setting low speed)	001Hz	10	10		6	Multi-speed setting Gow speed	0.01 Hz	10	
7	Acceleration time	0.19	5	5		7	Acceleration time	0.16	5	
0	Deceleration time	0.16	5	5			Deceleration time	0.1s	5	
9	Electronic thermal 0/1, relay	E01A	83.0	0.68		3	Electronic thermal OV1 relay	0.01 A	0.68	
10	DC injection brake operation frequency	001Hz	3	3		10	DC injection brake operation trequency	0.01Hz	3	
11	DC injection brake operation	0.19	66	0.6		11	DC ejection brake operation	0.1s	0.5	

### 🌮 Convert (System area)

- 7) Check the information of the source inverter and target inverter. Click <u>convert</u> to convert the parameter.
- 8) Click <u>Einish</u> when "Parameter converting is finished." is displayed.



 Results of parameter converting is shown in "Convert" window.



- 10) Click Perfect to the Target in "Convert" window to display "Parameter Saving".
- 11) Check "Reflect in a Parameter List of the Selected Station", and click <u>Enish</u> to reflect the converted parameter setting into the Parameter List. If a station has not finished model setting or the inverter

model is different, the station is unavailable to select.

12) When saving the converted parameter setting as a file, check [Save <u>As</u>]. Specify the file location, and click
 <u>Enish</u> to save the converted parameter setting into a parameter file (PR3).





#### REMARKS

()

• Following confirmation dialog is displayed when reflecting the converted parameter setting.



• If an nonexistent parameter is added to the source, the nonexistent parameter data is not reflected in the target.

### 4.7.4 Precautions for Convert

Please note the following for using "Convert", and make a setting again if necessary. Refer to the inverter manual for details of the parameters.

### <When converting the FR-V500 (L) series to the FR-A700 series >

(1) When a plug-in option and inverter terminal are used for the FR-V500 (L), check the following item.

FR-V500(L	FR-A700			
Function	Options/terminal	Options/terminal		
Encoder connection	Inverter terminal for encoder	FR-A7AP or FR-A7AL		
Position control	FR-V5AP	FR-A7AL		
Encoder pulse division output	FR-V5AY	FR-A7AL		
Extension open collector output	FR-V5AY	Inverter output terminals		
16-bit digital input	FR-V5AH(FR-A5AX)	FR-A7AX		
High resolution analog input /				
thermistor interface		FR-AIAL		
Extension contact input	FR-V5AX	Inverter output terminals		
Bipolar analog output	Inverter terminal DA1	FR-A7AZ (terminal DA1)		
Torque setting input	Inverter terminal 3	FR-A7AZ (terminal 6)		

- (2) Since the following parameters are not converted, make a setting from "Parameter List" as required.
  - Pr. 133 PID action set point
  - Pr. 160 Extended function display selection
  - Pr. 900, 901 (FM, AM output terminal calibration)
  - PU contrast adjustment (Pr. 991)
- (3) The following parameters are adjustment parameters. Parameter readjustment according to the machine is recommended after converting.
  - Pr. 0 Torque boost
  - Pr. 12 DC injection brake voltage
  - Pr. 820, 821, 824, 825, 830, 831, 834, 835 (vector control, speed control/torque control gain)
  - Pr. 902, 903, 917, 918, 926, 927 (frequency setting input calibration parameter)
  - Pr. 919, 920, 928, 929 (torque/magnetic flux setting input calibration parameter)
- (4) When vector control is selected for the FR-V500 (L) series, check the following item.
  - When offline auto tuning (*Pr. 71 Applied motor* ="3, 4, 7, 8, 13, 14, 17, 18, 23, 24. 33, 34") is performed with the source inverter, it is recommended to perform tuning and parameter setting again with the target inverter.
  - Since the SF-VH motor compatible with the FR-V500L series is not supported by the FR-A700 series, make sure to perform tuning and parameter setting again same as other manufacturer's constant motors before use.
- (5) Communication related parameters (*Pr. 117 to Pr. 124, Pr. 331 to Pr. 337, 341*) are also converted. Depending on a setting, communication may not be established after writing the parameter. For example, setting "0" (initial value) in *Pr. 122* and *Pr. 336 Communication check time interval* makes parameter writing unavailable.

### 🌱 Convert (System area)

- (6) The following wiring needs to be changed. Refer to the FR-A700 series manual for details of wiring.
  - When terminal DA2 was used, change the connection to terminal AM.
  - When automatic restart after instantaneous power failure (*Pr: 57* is not "9999") was used, short STOP-SD (terminal STOP is changed to CS signal by Convert)
  - When using pulse train input of the FR-A5AP, change the connection to JOG/pulse train input terminal of the inverter (terminal JOG is changed to pulse train input by Convert). Note that a resistance is necessary when connecting.
  - When thermal protector is connected (*Pr.* 876 ="0"), change the connection to terminal CS (terminal CS was changed to OH signal by Convert. Note that a resistance is necessary when connecting.
  - When a relay output terminal of the FR-A5NR was used, change the connection to terminal ABC2 of the inverter.
  - Terminal DI1, DI2, DI3, and DI4 of the FR-V500 (L) series are replaced with terminal RL, RM, RH, and RT of the FR-A700 series.
  - Terminal DO1, DO2, and DO3 of the FR-V500 (L) series are replaced with terminal RUN, SU, and IPF of the FR-A700 series.
  - When performing PID control by measured value signal input (*Pr. 128* ="30, 31"), it is necessary to change the terminal of measured value signal from terminal 1 to terminal 4. Since terminal 4 is factory set to current input, any of the following change is necessary in such a case.
    - 1) Change to current input
    - 2) When Pr. 262 ="2", set Switch 1 on board to OFF and change terminal 4 input to 0 to 10V input.
  - When stop position command of orientation control was given from the FR-A5AX (*Pr. 350 ="2", Pr. 360 ="1"*) and the number of encoder pulses (*Pr. 369*) was 2048 and 4096, wire to the FR-A7AX as shown below.

When the number of encoder pulses (Pr: 369) is 2048

Change connection from X0 to X1.....from X11 to X12 (X0 is always open)

When the number of encoder pulses (Pr. 369) is 4096

Change connection from X0 to X2.....from X11 to X13 (X0 and X1 are always open)

- When terminal 3 is used as "Torque limit command", it can be assigned to terminal 4. Make sure that current input/ voltage input settings are correct when assigning to terminal 4.
- (7) There is a change in the following functions. Refer to the FR-A700 series manual for details.
  - Motors with the rated motor frequency higher than 120Hz are not supported.
  - *Pr. 285 Overspeed detection speed* and *Pr. 870 Speed deviation level* of the FR-V500 (L) series are integrated into *Pr. 285* for the FR-A700 series. When different values are set, make sure to check that the *Pr. 285* setting is as intended. If any problem occurs, set manually again.
  - Since the setting range of *Pr*: 357 *In-position zone* has been narrowed down due to orientation control, the value may be changed. Check that there is no problem for stop operation.
  - When stop position command of orientation control was given from the FR-A5AX (*Pr. 350 = 2, Pr. 360 = 1*), orientation with the number of encoder pulses (*Pr. 369*) 1025 to 2047, or 2049 to 4059 is not supported by Convert.
  - When using relay terminal of the FR-A5NR as remote output (*Pr. 496, 497*), bit assignment is changed. *Pr. 497* bit10 to *Pr. 496* bit6
  - When using CC-Link communication with the FR-A5NC, set the communication station number and baud rate in *Pr*: *542* and *Pr*: *543* according to the rotary switch setting of the FR-A5NC.
- (8) Following functions are not converted, since they have been deleted from the FR-A700 series.
  - Pr. 53 PU level display data selection
  - Setting value 36, torque monitor (driving/regenerative polarity switchover) of Pr. 54, Pr. 158, Pr. 306, Pr. 310
  - Setting value 10, 11, 12, machine end orientation of Pr. 369 (the number of encoder pulses of orientation) and Pr. 393
  - Pr. 400 to Pr. 405 extension input terminal
  - Pr. 400 to Pr. 412 extension output terminal
  - Pr. 446 password for Ethernet
  - Setting value 38, Y40 (trace status) signal, trace function of the FR-V500L series of Pr. 52, Pr. 520 to Pr. 538

#### <When converting the FR-A500 (L) series to the FR-A700 series >

- (1) Since the following parameters are not converted, make a setting from "Parameter List" as required.
  - Pr. 133 PID action set point
  - Pr. 160, Pr. 173 to Pr. 176 (User group selection)
  - Pr. 900, Pr. 901 (FM, AM output terminal calibration)
  - Pr. 991 PU contrast adjustment
- (2) The following parameters are adjustment parameters. Parameter readjustment according to the machine is recommended after converting.
  - Pr. 0 Torque boost
  - Pr. 12 DC injection brake voltage
  - Pr. 902 to Pr. 905 (frequency setting input calibration parameter)
- (3) Note the following when advanced magnetic flux vector control or vector control is selected for the FR-A500 (L) series (*Pr. 80 Motor capacity* is not "9999", *Pr. 81 number of motor poles* is not "9999").
  - Tuning and parameter setting of the target inverter is recommended, if offline auto tuning is performed (*Pr. 71 Applied motor* = "3, 4, 7, 8, 13, 14, 17, 18, 23, 24") or motor constants is directly input (*Pr. 71* = "5, 6, 15, 16") at the source inverter.
  - When SF-HR or SF-HRCA type motor is used, set *Pr*: 71 = "40, 43, 44, 50, 53, 54" after writing the converted parameter to the target inverter. (Conversion of *Pr*: 82, *Pr*: 85, *Pr*: 86, *Pr*: 89, *Pr*: 90 to *Pr*: 94 is not necessary)
- (4) Communication related parameters (*Pr. 117* to *Pr. 124, Pr. 331* to *Pr. 337, 341*) are also converted. Depending on a setting, communication may not be established after writing the parameter. For example, setting "0" (initial value) in *Pr. 122* and *Pr. 336 Communication check time interval* makes parameter writing unavailable.
- (5) The following wiring needs to be changed. Refer to the FR-A700 series manual for details of wiring.
  - When using pulse train input of the FR-A5AP was used, change the connection to JOG/pulse train input terminal of the inverter (JOG terminal is changed to pulse train input by Convert). Note that a resistance is necessary when connecting.
  - When a relay output terminal of the FR-A5NR was used, change the connection to terminal ABC2 of the inverter.
  - When stop position command of orientation control was given from the FR-A5AX (*Pr: 350 ="2", Pr: 360 ="1"*) and the number of encoder pulses (*Pr: 369*) was 2048 and 4096, wire to the FR-A7AX as shown below. When the number of encoder pulses (*Pr: 369*) is 2048

Change connection from X0 to X1.....from X11 to X12 (X0 is always open)

When the number of encoder pulses (Pr. 369) is 4096

Change connection from X0 to X2.....from X11 to X13 (X0 and X1 are always open)

### 커 Convert (System area)

- (6) There is a change in the following functions. Refer to the FR-A700 series manual for details.
  - When automatic restart after instantaneous power failure is performed with residual voltage detection system by T-SEN50 (*Pr. 162* ="11"), it is changed to automatic restart after instantaneous power failure with reduced voltage system. Fully check that there is no problem in automatic restart operation after instantaneous power failure. If there are any problem, consider changing to f search system, etc.
  - Y29 (acceleration speed detection) signal is deleted, and major fault by E.OS occurs instead.
  - When stop position command of orientation control was given from the FR-A5AX (*Pr. 360* =1), orientation with the number of encoder pulses (*Pr. 369*) 1025 to 2047, or 2049 to 4059 is not supported by Convert.
  - Since convert is performed using the full scale value of the motor torque as 200%, the full scale value of the load meter is converted as 200% (FR-A500 (L) series is 100%). Use *Pr. 866* to change. In such a case, note that the full scale value of the motor torque also changes accordingly.
- (7) Following functions are not converted, since they have been deleted from the FR-A700 series.
  - Pr. 53 PU level display data selection
  - Pr. 199 User initial value
  - Setting value 3, PRG signal (program operation) of Pr. 200 to Pr. 231 and Pr. 76, setting value 5 of Pr. 79
  - Pr. 371 Torque characteristic selection
  - Pr. 390 to Pr. 396 Trace function of the FR-A500L series
  - Pr. 450 to Pr. 453 Motor constant adjustment function for vector control of the FR-A500L series and FR-A5AP (encoder 50)

#### <When converting the FR-E500 series to the FR-D700 series >

- (1) The following parameters are not converted. Make a setting from "Parameter List" as required.
  - Pr. 133 PID action set point
  - Pr. 146 Frequency setting command selection
  - Pr. 900, Pr. 901 (FM, AM output terminal calibration)
  - Pr. 991 PU contrast adjustment
- (2) The following parameters are adjustment parameters. Parameter readjustment according to the machine is recommended after converting.
  - Pr. 0 Torque boost
  - Pr. 12 DC injection brake voltage
  - Pr. 245 Rated slip
  - Pr. 246 Slip compensation time constant
  - Pr. 902 to 905, 922, 923 (frequency setting input calibration parameter)
- (3) When general-purpose magnetic-flux vector control is selected (*Pr. 80 Motor capacity* is not "9999") for FR-E500 series, note the following precautions.
  - Tuning and parameter setting of the target inverter is recommended, if offline auto tuning is performed (*Pr. 71 Applied motor* = "3, 13, 23, 103, 113, 123") or motor constants is directly input (*Pr. 71* = "5, 6, 15, 16, 105, 106, 115, 116") to the source inverter.
  - When SF-HR or SF-HRCA type motor is used, set *Pr*: 71 = "40, 43, 44, 50, 53, 54" after writing the converted parameter to the target inverter. (Conversion of *Pr: 82, Pr: 86, Pr: 90* is not necessary)
- (4) Communication related parameters (*Pr. 117 to Pr. 124*) are also converted. Depending on a setting, communication may not be established after writing the parameter. For example, setting "0" (initial value) in *Pr. 122 PU communication check time interval* makes parameter writing unavailable.
- (5) When communication operation is selected with the FR-E500 series, parameter writing and operation command sending, etc. is made in PU operation mode. Therefore, one of the following setting is required for FR-D700 series.
  - Set *Pr*: 79 = "1"(PU operation mode always), *Pr*: 551 = "2"(PU control source is PU connector), and change to PU operation mode. Note that parameter writing and operation command from the operation panel is unavailable.
  - Set *Pr*: 79 = "0"(initial value), *Pr*: 340 = "1" (network operation mode at power-ON), and change to network operation mode.
- (6) If FR-E510W or FR-E520S is connected and convert from the connected inverter through communication is performed, the inverter is detected as FR-E520. Check that a compatible inverter is connected for source inverter, and then perform inverter detection.
- (7) Since FR-D700 series does not have *Pr. 21 (Acceleration/deceleration time increments)*, if *Pr. 21* = "1", the setting value of the hundredth place of the following parameters are rounded to the tenth place.
- (8) Following functions are not converted, since they have been deleted from the FR-D700 series.
  - Pr. 183 MRS terminal function selection
  - Pr. 191 FU terminal function selection
  - Pr. 160, 173 to 176 (User group selection)
  - Pr. 345 to 348 (DeviceNet communication)
  - Pr. 387 to 392 (LonWorks communication)
  - Pr. 500, 501 (communication option parameter)

### 🌱 Convert (System area)

### <When converting the FR-S500(E) series to the FR-D700 series >

- () indicates parameter number for FR-S500(E) series
- (1) The following parameters are not converted. Make a setting from "Parameter List" as required.
  - Pr. 133 PID action set point
  - Pr. 160 (P30) Extended function display selection
  - Pr. 900, Pr. 901 (FM, AM output terminal calibration)
  - Pr. 991 PU contrast adjustment
- (2) The following parameters are adjustment parameters. Parameter readjustment according to the machine is recommended after converting.
  - Pr. 0 Torque boost
  - Pr. 12 DC injection brake operation voltage
  - Pr. 245 (P95) Rated slip
  - Pr. 246 (P96) Slip compensation time constant
  - Pr. 902 to 905, 922, 923 (C3, C4, C6, C7) (frequency setting input calibration parameter)
- (3) When Automatic torque boost is selected (*Pr. 98 Motor capacity* is not "9999") for FR-S500(E) series, note the following precautions.
  - Tuning and parameter setting of the target inverter is recommended.
  - When SF-HR or SF-HRCA type motor is used, set *Pr*: 71 = "40, 43, 44, 50, 53, 54" after writing the converted parameter to the target inverter.
- (4) Communication related parameters (*Pr. 117 to Pr. 124 (n1 to n7, n11)*) are also converted. Depending on a setting, communication may not be established after writing the parameter. For example, setting "0" (initial value) in *Pr. 122 (n6) PU communication check time interval* makes parameter writing unavailable.
- (5) The following functions have different behavior due to specification change. Refer to the Instruction Manual of FR-D700 for details.
  - Since formula of *Pr. 23 Stall prevention operation level compensation factor at double speed* has been changed, operation level of stall prevention at double speed changes if the setting has been changed greatly from 100%.
  - *Pr. 992 (n16) PU main display screen data selection* is integrated into *Pr. 52*. Setting *Pr. 52* changes both operation panel display and PU display.

#### <When converting the FR-E500 series to the FR-E700 series >

- (1) The following parameters are not converted. Make a setting from "Parameter List" as required.
  - Pr. 133 PID action set point
  - Pr. 146 Frequency setting command selection
  - Pr. 160, Pr. 173 to Pr. 176 (User group selection)
  - Pr. 900, Pr. 901 (FM, AM output terminal calibration)
  - Pr. 991 PU contrast adjustment
- (2) The following parameters are adjustment parameters. Parameter readjustment according to the machine is recommended after converting.
  - Pr. 0 Torque boost
  - Pr. 12 DC injection brake voltage
  - Pr. 245 Rated slip
  - Pr. 246 Slip compensation time constant
  - Pr. 902 to Pr. 905 (frequency setting input calibration parameter)
- (3) When general-purpose magnetic-flux vector control is selected (*Pr. 80 Motor capacity* is not "9999") for FR-E500 series, note the following precautions.
  - When converting, motor pole is considered as 4poles (*Pr. 81 Number of motor poles* = "4"). Set the number of motor poles of the using motor in *Pr. 81*.
  - Tuning and parameter setting of the target inverter is recommended, if offline auto tuning is performed (*Pr. 71 Applied motor* = "3, 13, 23, 103, 113, 123") or motor constants is directly input (*Pr. 71* = "5, 6, 15, 16, 105, 106, 115, 116") to the source inverter.
  - When SF-HR or SF-HRCA type motor is used, set *Pr*: 71 = "40, 43, 44, 50, 53, 54" after writing the converted parameter to the target inverter. (Conversion of *Pr*: 82, *Pr*: 86, *Pr*: 90 is not necessary)
- (4) Communication related parameters (*Pr. 117 to Pr. 124*) are also converted. Depending on a setting, communication may not be established after writing the parameter. For example, setting "0" (initial value) in *Pr. 122 PU communication check time interval* makes parameter writing unavailable.
- (5) When communication operation is selected with the FR-E500 series, parameter writing and operation command sending, etc. is made in PU operation mode. Therefore, one of the following setting is required for FR-E700 series.
  - Set *Pr*: 79 = "1"(PU operation mode always), *Pr*: 551 = "2"(PU control source is PU connector), and change to PU operation mode. Note that parameter writing and operation command from the operation panel is unavailable.
  - Set *Pr*: 79 = "0"(initial value), *Pr*: 340 = "1" (network operation mode at power-ON), and change to network operation mode.
- (6) If FR-E510W or FR-E520S is connected and convert from the connected inverter through communication is performed, the inverter is detected as FR-E520. Check that a compatible inverter is connected for source inverter, and then perform inverter detection.
- (7) There is a change in the following functions. Refer to the FR-E700 series manual for details.
  - When CC-Link communication was made with the FR-E5NC, set the communication station number and baud rate in *Pr. 542 and Pr. 543* according to the rotary switch setting of the FR-E5NC.

### <When converting the FR-F500 (L) series to the FR-F700 series >

- (1) Since the following parameters are not converted, make a setting from "Parameter List" as required.
  - Pr. 133 PID action set point
  - Pr. 160, Pr. 173 to Pr. 176 (User group selection)
  - Pr. 900, Pr. 901 (FM, AM output terminal calibration)
  - Pr. 991 PU contrast adjustment
- (2) The following parameters are adjustment parameters. Parameter readjustment according to the machine is recommended after converting.
  - Pr. 0 Torque boost
  - Pr. 12 DC injection brake voltage
  - *Pr. 902 to Pr. 905 (frequency setting input calibration parameter)*
- (3) Automatic torque boost (*Pr. 38, Pr. 39*) of the FR-F500 (L) series has been changed to simple magnetic flux vector control for the FR-F700 series. When automatic torque boost is used and operation conditions meets simple magnetic flux vector control, then manually set simple magnetic flux vector control. Refer to the FR-F700 series manual for details.
- (4) Communication related parameters (*Pr. 117 to Pr. 124, Pr. 331 to Pr. 337, 341*) are also converted. Depending on a setting, communication may not be established after writing the parameter. For example, setting "0" (initial value) in *Pr. 122* and *Pr. 336 Communication check time interval* makes parameter writing unavailable.
- (5) The following wiring needs to be changed. Refer to the FR-F700 series manual for details of wiring.
  - When a relay output terminal of the FR-A5NR was used, change the connection to terminal ABC2 of the inverter.
- (6) There is a change in the following functions. Refer to the FR-F700 series manual for details.
  - Since formula of *Pr. 23 Stall prevention operation level compensation factor at double speed* has been changed, operation level of stall prevention at double speed changes if the setting has been changed greatly from 100%.
  - When CC-Link communication was made with the FR-A5NC, set the communication station number and baud rate in *Pr. 542 and Pr. 543* according to the rotary switch setting of the FR-A5NC.
- (7) Following functions are not converted, since they have been deleted from the FR-F700 series.
  - *Pr. 11* setting 8888 (external DC injection brake)
  - Pr. 53 PU level display data selection
  - Setting 3 of Pr. 60, Pr. 61 to Pr. 63 (optimum acceleration/deceleration)
  - Pr. 199 User initial value
  - Pr. 390 to Pr. 396 Trace function of the FR-F500L series

### 4.8 Diagnosis (System area)

"Diagnosis" displays fault information and parts life information of the inverter. Use "Diagnosis" to operate the following functions.

- Displays the faults history and monitor value of each fault occurrence.
- Inverter reset
- Faults history clear
- Measuring of the main circuit capacitor life
- Display of parts life and alarm
- File output of diagnosis data

### 4.8.1 Explanation of window



No.	Name	Function and description
Δ	Data Undate	Reads faults history and parts life information from the selected inverter and updates display.
~		(Available only when ONLINE.)
B	Inverter Reset	Resets the selected inverter. Confirmation window appears. Click via to proceed. (Available
		only when ONLINE.)
C	Faulte Clear	Clears the faults history of the selected station. Confirmation window appears. Click to
		proceed. (Available only when ONLINE.)
П	Main Circuit Capacitor Life	Starts life measuring of the main circuit capacitor. <i>Refer to page 122</i> for measuring procedure
D	Measuring	otarts life measuring of the main circuit capacitor. <i>Refer to page 122</i> for measuring procedure.
F	Data Output	Outputs diagnosis data of the selected inverter to a file (text format). Specify the file name and save
		the diagnosis data file.
F	Faults history	Displays faults history read from the inverter in a list. Also displays output frequency, output current,
		output voltage, and energization time of fault occurrence.
G	Faults description	Displays description of the selected fault.
н	Parts life information	Displays parts life information read from the inverter. A check mark is shown in the parts life alarm
		field for the parts recommended for replacement.

### 4.8.2 Procedure of Main circuit capacitor life measuring

1) Confirmation window appears before measuring. Check the

following items, and click

- Motor is connected?
- Motor is stopped?
- Enough time has been passed after the motor operation?
- Performs parameter setting for measuring the main circuit capacitor life. Click <a href="https://www.example.com">weathermain.circuit</a>
- Switch OFF inverter power. Click Power OFF after powering OFF the inverter.
- 4) After making sure that the POWER lamp of the inverter is off, switch ON the power supply again. Click Power ON>>> after powering ON the inverter.
- 5) Displays the measuring result of the main circuit capacitor life in "Measured Value". (Displays a previous value in "Last Value" if the main circuit capacitor life value measured last time is stored in the inverter when updating diagnostic information.)

Jiagnosis		×
Check before mea	suring	
Check the followin	- ar and click Nevt \	
Motor is connect	ed?	<i>.</i>
Motor is stopped	? been nacced after	motor operation?
Lindigin time has	been passed arter	motor operation:
Next >>	Cancel	Help
1		· · · · · · · · · · · · · · · · · · ·
Jiagnosis		×
Measuring Setting		
Satting 1 (Mascuri	oa) in Main Circuit	Capacitor
Life Measuring (Pi	.259).	Capacitor
Next >>	Cancel	
Diagnosis		×
D 055 /44		
Power OFF (Meas	urement/	
Click Power OFF.	and then turn the i	inverter power OFF.
and capacitor life	is measured.	ied to the motor,
Power OFF >>	Gancel	
Diagnosis		×
B 01/44		
Power UN (Measu	rement Result/	
Check that Power	Lamp is OFF, and	then turn the
power is ON. Mea:	surement Result is	displayed.
04		
	0.1.1	
Power ON >>	Cancel	

#### Measurement Result is displayed

L'e Arm			
Parts Life	Name	Indicatio	Remarks
	Main Gircuit Capacitor	Last Value : 100 N Measured Value : 100 N	85% or less is a guideline for replacement.
	Control Circuit Capacitor	100 N	10% or less is a guideline for replacement.
	Inrush Current Limit Circuit 100 N		10% or less is a guideline for replacement.
	Cooling Fan		Life alarm is displayed when the speed decreased lower than 50%
	Energization Time	14 h	Shows cumulative energization time after inverter shipment.

#### REMARKS

- When the main circuit capacitor life is measured under the following conditions, "forced end" (Pr.259="8") or "measuring error" (Pr.259="9") occurs or it remains in "measuring start" (Pr.259="1"). Therefore, do not measure in such case.
  - (a) FR-HC, FR-CV are connected.
  - (b) DC power supply is connected to terminal P/+ and N/-.
  - (c) The power supply switched on during measurement.
  - (d) The motor is not connected to the inverter.
  - (e) The motor is running (coasting)
  - (f) The motor capacity is two rank smaller as compared to the inverter capacity.
  - (g)The inverter is tripped or a fault occurred when power is off.
  - (h) The inverter output is shut off with the MRS signal.
  - (i) The start command is given while measuring.
  - (j) The parameter unit (FR-PU04/FR-PU07) is connected (FR-D700, E700 series only)
- (k) Use terminal PC as power supply (FR-D700, E700 series only)
- (I) I/O terminal of the control terminal block and plug-in option is on (continuity) (FR-D700, E700 series only)
- (m)Plug-in option is fitted. (only for the 0.75K or less of the FR-E700 series)
- Turning the power on during measuring before LED of the operation panel turns off, it may remain in "measuring" (*Pr. 259="2"*) status. In such a case, perform life measurement again.

### 4.9 Graph (Monitor area)

Sampling the output frequency or current, etc. of the inverter and displays the data in graph form (wave form). The sampling data can be saved in a file (Export). And the saved sampling data can be read and displayed (Import).

Select [Graph] under [View] menu, or click

on the tool bar to display "Graph".

There are two sampling methods.

# • High Speed sampling (only when the FR-E700 series is connected with USB without connecting through GOT)

Able to sample a data with minimum sampling interval about 1 [ms]. One station can be monitored.

 $\sim$ 

Graph

#### • Monitor sampling

Able to sample a data from multiple stations. Sampling interval varies depending on communication setting (communication speed and communication port) and a number of sampling items.

		Specifications
Sampling point	Sampling is available up to 10000 points per each CH	
	High Speed sampling:	Setting available from about 1 [ms] (mask count: 1) to 20 [ms] (mask count:
Sampling intorval		40)
Sampling interval	Monitor sampling:	Setting available from about 50 [ms] to 540000 [ms] (varies depending on
		communication speed, communication port or number of sampling items)
Sampling time [ms]	High Speed sampling:	Maximum sampling interval × 8000
	Monitor sampling: Max	ximum sampling interval × 10000
Analog data Sampling of 1CH to 4CH (4CHs) analog data is available.		CH (4CHs) analog data is available.
Digital data Sampling of 5CH to 8CH (4CHs) digital data is available.		CH (4CHs) digital data is available.



### Note

 During High Speed sampling, if other application is running or performing file handling with personal computer, communication error (Error code 0x8002007, 0x80020008) or buffer overflow error may occur, and unable to display data correctly. In this case, take measures such as, to close the other application, to refrain FR Configurator operation, or to set larger value in Mask count of sampling interval.

• Test operation ( \_\_\_\_\_, \_\_\_\_, \_\_\_\_, does not function during graph sampling of two or more stations by communication through GOT (FA transparent function).

### 4.9.1 Basic flow of Sampling

1) Sampling setting

Set sampling items. Changing of the sampling mode (High Speed or Monitor), sampling interval or sampling time, etc. is available for your purpose. When starting sampling with using a trigger, make a trigger setting.

#### 2) Start sampling

Click <u>Start</u> to start the sampling when sampling item is set already. If the trigger is set, sampling starts when the trigger condition is satisfied during "Waiting for Trigger" state which comes after "Sampling Pre-trigger Data" state.

#### 3) Sampling complete

Sampling stops in the following condition.

•When elapsed time from the beginning of the monitoring exceeds the sampling time

•When Stop is clicked

#### 4) Graph display

You can change a scale of the graph, show a numeric value of a wave at where cursors is laid, or show effective value of between any 2 points, maximum value, and minimum value. Exporting of graph data (*Refer to page 88*) for saving as a file is also available.



### Note

If an normal communication is not maintained (communication error, etc.), the sampling stops. If an fault occurs during sampling, sampling continues. During sampling, other communication tasks such as operation command or parameter reading, etc. are unavailable.

### 4.9.2 Explanation of window



No.	Name	Function and description
Α	Start	Starts sampling.
В	Stop	Stops sampling.
С	Clear	Clears the graph. If a graph has not been displayed yet, the setting of sampling item is cleared.
D	Trigger/Sampling	Click Trigger/Sampling to display trigger/sampling setting section. (Refer to page 128)
Е	СН	Click CH to display sampling item setting section. (Refer to page 126)
F	Sampling item setting section (Trigger/sampling setting section)	Click tabs to switch displaying Sampling item setting section ( <i>Refer to page 126</i> ) and Trigger/ sampling setting section ( <i>Refer to page 128</i> ).
G	Graph area	Shows sampling data in graph form.
н	Scale changing section (Cursor function section, History display section)	Click tabs to switch displaying Scale changing section ( <i>Refer to page 132</i> ), Cursor function section ( <i>Refer to page 133</i> ) and History display section ( <i>Refer to page 134</i> ).
Ι	Scale	Click Scale to display Scale changing section. (Refer to page 132)
J	Cursor	Click Cursor to display Cursor function section. (Refer to page 133)
к	History	Click History to display History display section. (Refer to page 134)
L	Graph (digital data)	Digital data drawn in graph form (CH5 to CH8). OFF is drawn on a grid line, and ON is drawn between the grid lines.
М	Graph (analog data)	Analog data drawn in graph form (CH1 to CH4). Graph is drawn based on the setting of Vertical Axis scale and 0 position adjust. Vertical Axis scale of each data (CH) can be changed separately.
N	Trigger Line	Shows a position of trigger start. "T" is displayed on top of Trigger Line.



### Note

Each graph displays their own CH number. Though when a graph data is out from Graph area, CH number may not be displayed. Adjust with 0 position adjust and scale changing to make a data visible inside of Graph area.

### 4.9.3 Sampling item setting

Click CH to display Sampling item setting section. Set station number and item for sampling. Analog data is set in CH1 to CH4, and digital data is set in CH5 to CH8.

	Start	Stop	Clear						
A		сн г	Trigger/Sampling						
B N	Color	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
	St. No.	00	None	None	None	None	None	None	None
C→	Name	Frequency Settin	None	None	None	None	None	None	None
Ъ	Cursor A								
Ľ٦	Cursor B								
E-	Eff. Val.								
_ J	Max. Val.								
۲Ì	Min. Val.								
									/
			For Ana	log data			For Digi	ital data	

No.	Name	Function and description	
Α	Color	Shows the color of the graph drawing.	
		Select station number for sampling.	
В	St. No.	For High Speed sampling, only CH1 is available for setting. CH2 to CH8 has the same station number as the one set	
		in CH1.	
С	Name	Select sampling item. Four analog data (CH1 to CH4), and four digital data (CH5 to CH8) are available.	
П	Cursor A	Shows measured value of surser A and P on a wave form	
D	(Cursor B)	Shows measured value of cursor A and B on a wave form.	
Е	Eff. Val	Shows calculated effective value between cursor A and B.	
E	Max. Val	Showe maximum value and minimum value between aureer A and R while aureer is displayed in Vertical Avia	
F	(Min. Val)	Shows maximum value and minimum value between cursor A and B while cursor is displayed in vehical Axis.	

### Sampling item list

Refer to the inverter manual for details of monitor item. Refer to the inverter manual for digital data sampling items.

Model	Sampling	Compling Itom		
Name	Mode	Samping tem		
FR-A700	Monitor	Output frequency, output current, output voltage, frequency setting value, running speed, motor torque, converter output voltage, regenerative brake duty, electronic thermal relay function load factor, output current peak value, converter output voltage peak value, input power, output power, load meter, motor excitation current, position pulse, cumulative energization time, orientation status, actual operation time, motor load factor, cumulative power, torque command, torque current command, motor output, feedback pulse, SSCNET III communication status, power saving effect, cumulative saving power, PID set point, PID measured value, PID deviation		
FR-D700	Monitor	Dower saving enect, cumulative saving power, PID set point, PID measured value, PID deviation           Output Frequency, Output Current, Output Voltage, Frequency Setting, Converter Output Voltage, Regenerative           Brake Duty, Electronic Thermal Relay Function Load Factor, Output Current Peak Value, Converter Output           Voltage Peak Value, Output Power, Cumulative Energization Time, Actual Operation Time, Motor Load Factor, Cumulative Power, PID Set Point, PID Measured Value, PID Deviation, Motor thermal load factor, Inverter thermal load factor, PTC Thermistor Resistance		
FR-E700	Monitor	Output Frequency, Output Current, Output Voltage, Frequency Setting, Motor Torque, Converter Output Voltage, Regenerative Brake Duty, Electronic Thermal Relay Function Load Factor, Output Current Peak Value, Converter Output Voltage Peak Value, Output Power, Cumulative Energization Time, Actual Operation Time, Motor Load Factor, Cumulative Power, PID Set Point, PID Measured Value, PID Deviation, Motor thermal load factor, Inverter thermal load factor		
	High Speed	Output Frequency, Output Current, Output Voltage, Frequency Setting, Motor Torque, Converter Output Voltage, Regenerative Brake Duty, Electronic Thermal Relay Function Load Factor, Output Current Peak Value, Converter Output Voltage Peak Value, Output Power, Cumulative Energization Time, Actual Operation Time, Motor Load Factor, Cumulative Power, PID Set Point, PID Measured Value, PID Deviation, Motor thermal load factor, Inverter thermal load factor, Output Frequency (instantaneous value), U Phase Output Current, V Phase Output Current, W Phase Output Current, Converter Output Voltage (instantaneous value), Output Current (all three phases without filtering), Excitation Current, Torque Current, Terminal 2, Terminal 4		
FR-F700	Monitor	Output frequency, output current, output voltage, frequency setting, running speed, converter output voltage, regemerative brake duty, electronic thermal relay function load factor, output current peak value, converter output voltage peak value, intput power, output power, cumulative energization time, actual operation time, motor load factor, cumulative power, powre saving effect, cumulative saving power, PID set value, PID measured value, PID deviation		



### Note

• Change the sampling mode (Monitor/High Speed) before setting sampling items. Since some monitor items are different between the sampling mode, the setting of uncommon sampling item is cleared when changing the sampling mode. (*Refer to page 128*)

When making sampling item setting, set analog data (CH1 to CH4) in ascending order from CH1, and digital data (CH5 to CH8) in ascending order from CH5.

### 4.9.4 Sampling setting

Click Triseer/Sampling to display Sampling setting section. Setting sampling mode, Single/Continuous setting, and sampling time are available.



For Monitor sampling

For High Speed sampling

No.	Name	Function and description
		Select between Single sampling or Continuous sampling.
		Single:
Δ	Single/Continuous	Sampling from start to end is performed only once.
~		Continuous:
		Sampling from start to end is performed continuously. When sampling ends, the data is
		added to History, and starts the next sampling. (Refer to page 134)
		Select between High Speed sampling or Monitor sampling.
		Select between Single sampling or Continuous sampling.         • Single:         Sampling from start to end is performed only once.         • Continuous:         Sampling from start to end is performed continuously. When sampling ends, the data added to History, and starts the next sampling. ( <i>Refer to page 134</i> )         Select between High Speed sampling or Monitor sampling.         High speed sampling is available only the FR-E700 series is connected with USB (not available when connected through GOT). Since some monitor items are different betwee the sampling mode, the setting of uncommon sampling item is cleared when changing t sampling interval is fixed depending on a number of sampling items and communication setting. ( <i>Refer to page 129</i> )         Set interval (cycle) of data sampling.         For High Speed sampling, set Mask count (available from 1 to 40) to fix the sampling interval is approximately equal to (Mask Count + 1) × 0.5ms         Example: when the Mask Count is 1         Sampling interval is approximately equal to (1 + 1) × 0.5ms = About 1ms         Set maximum sampling time can be set as follows. ( <i>Refer to page 129</i> )         High Speed sampling time can be set as follows. ( <i>Refer to page 129</i> )
В	Mode	available when connected through GOT). Since some monitor items are different between
		the sampling mode, the setting of uncommon sampling item is cleared when changing the
		sampling mode
		Set interval (cycle) of data sampling.
	Interval [ms]	Sampling interval is fixed depending on a number of sampling items and communication
		setting. (Refer to page 129)
		Set interval (cycle) of data sampling.
		For High Speed sampling, set Mask count (available from 1 to 40) to fix the sampling
С		Seturg. ( <i>Refer to page 129</i> ) Set interval (cycle) of data sampling. For High Speed sampling, set Mask count (available from 1 to 40) to fix the sampling interval. Refer to the following formula for sampling interval.
	Mask Count	Sampling interval is approximately equal to (Mask Count + 1) × 0.5ms
		Example: when the Mask Count is 1
		Sampling interval is approximately equal to $(1 + 1) \times 0.5$ ms = About 1ms
		Set maximum sampling time. When elapsed time exceeds the sampling time, sampling
		stops. Maximum sampling time can be set as follows. (Refer to page 129)
		High Speed sampling: Maximum sampling interval × 8000
П	Time [ms]	Monitor sampling: Maximum sampling interval × 10000
		Example: when the Mask Count is 1 for High Speed sampling
		Maximum sampling time = 8000ms

### • Setting range and setting increments of "Sampling Interval" and "Sampling Time"

Setting range of "Sampling Interval" and "Sampling Time" are different between High Speed sampling and Monitor sampling.

1) For High Speed sampling (only when using USB connection)

Sampling interval can be set from about 1 [ms] (Mask Count: 1) to about 20 [ms] (Mask Count: 40), and sampling time can be set up to "setting sampling interval × 8000".

### 2) For Monitor sampling

Setting range of "Sampling Interval" and "Sampling Time" varies according to communication setting. The minimum sampling interval is "number of sampling items × Lower limit of sampling interval". Refer to the following table for Lower limit of sampling interval.

Communication port	Communication speed [bps]	Lower limit of sampling interval [ms] *
	4800	250
DS 2320	9600	150
N3-2320	19200	100
	38400	100
USB	-	50

\* When making a communication through GOT (FA transparent function), minimum value of the sampling interval is 200ms regardless of communication speed.

Refer to the following table for the maximum value, the minimum value, and the setting increments of "Sampling Interval" and "Sampling Time" when the measuring conditions are actually set.

	Maximum value	Minimum value	Increments
Sompling interval		Lower limit of sampling	
[ms]	540000	interval × the number of the sampling items *	50
Sampling time [ms]	Sampling interval * 10000	Sampling interval * 100	Sampling interval

\* If a fault trigger is set, the fault trigger is also added to the measuring items.

Example: When connecting with RS-232C port, Communication Speed is 19200bps, and monitoring 3 items, "Output Frequency", "Output Current", and "Output Voltage".

Lower limit of sampling interval = 100 [ms]

Maximum value of sampling interval = 540000 [ms] (540 [s])Minimum value of sampling interval =  $100 \times 3 = 300 \text{ [ms]}$ Setting increments of sampling interval = 100 [ms]

Maximum value of sampling time =  $540000 \times 10000 = 5400000000$  [ms] (1500 [h]) Minimum value of sampling time =  $300 \times 100 = 30000$  [ms] (30 [s]) Setting increments of sampling time = 300 [ms]

### 4.9.5 Trigger setting

With making Trigger setting, sampling can be started at a fault occurrence or when sampling item meets a trigger condition.



No.	Name	Function and description
		Select a trigger type for sampling start. You can select the trigger type from the following
		three.
Α	Туре	Not used
		<ul> <li>Inside (Sampling starts when sampling item meets a trigger condition)</li> </ul>
		Fault (Sampling starts at a fault occurrence)
		Selecting item is different according to the trigger type.
		For Inside trigger:
в	CH/St No	Select a trigger item (CH1 to CH8).
		For Fault trigger:
		Select a station number for checking a fault. Station number from which sampling item is
		already set can be selected.
		Select a trigger meeting condition from Rise or Fall. (Only "Rise" can be selected for Fault
		trigger.)
	Start At	• Rise
C		For analog data: Starts when a value exceeds more than a setting of Trigger Level
U		For digital data: Starts when a signal turns ON from OFF
		• Fall
		For analog data: Starts when a value falls lower than a setting of Trigger Level
		For digital data: Starts when a signal turns OFF from ON
п		Set a level of trigger meeting condition for analog signal.
		(Setting is available only when Inside trigger is set, and analog data is selected.)
		Set a percentage for an amount of data before trigger meets the condition. The amount
F	Position [%]	based on the specified percentage of total sampling data is assigned for the data before
		trigger meets the condition.
		Value is 10% increments and can be set from 10% to 90%.

### D REMARKS

 $\mathbf{O}$ 

For starting with analog data

If the trigger condition has already met when <u>Start</u> is clicked, sampling will not start. Sampling starts only when a value exceeds more than the setting of "Level" when "Rise" is selected, or when the value falls lower than the setting of "Level" when "Fall" is selected.

Example: when trigger starts at "Rise", and "3" is set for Level

If the value is already 4 at sampling start, then this case does not meet trigger condition. If the value lower than 3 exceeds more than 3, then the case meets trigger condition, and starts sampling.

When monitor display is changed to the machine speed with a value other than 0 is set in *Pr. 37 Speed display* When setting "Output Frequency" or "Frequency Setting" for Inside trigger, set machine speed for trigger level directly into "Level" field.

For example, if 1800 is set in *Pr. 37 Speed display*, sampling "Output Frequency", and want to meet trigger condition at 900, then you can set 900 directly into "Level" field.

#### About trigger waiting state



4

### 4.9.6 Scale changing

Scale changing of the displayed graph is available. Graph area is divided into vertical 10 grids and horizontal 10 grids. Scale of vertical axis and horizontal axis can be changed by setting a value of each one grid.

Selected graph can be moved upper or lower with changing 0 position adjust.

Scale value shown on vertical axis changes along with the vertical scale setting.



No.	Name	Function and description
Α	Vertical Scale	Shows vertical axis scale of each CH. Scale of each analog data can be set separately.
В	▲ / ▼ (0 position adjust)	Click ▲ / ▼ to move the 0 position of the selected graph upper or lower.
С	Vertical Axis	Vertical scale of the selected CH can be changed. To change the scale, set a graph value proportional for each grid. (Each CH can be changed separately.) Unavailable to change when digital data is selected.
D	Y-axis Scale Optimization	Click button to adjust the wave form of each analog data of graph to fit in the window.
E	Scale display switching	Switchs the display of the vertical axis between the selected CH only or the vertical axis of all analog data (or all digital data). (When showing all vertical axis, scale changing and 0 position adjust are unavailable.)
F	Horizontal Scale changing	Horizontal scale of graph can be changed. To change the scale, set a graph value proportional for each grid. Setting is available between "sampling interval * 10" to "sampling time/10".
G	Horizontal Axis scroll	Scrolls the graph to right and left

### 4.9.7 Cursor Function

Shows a numeric value of a wave at where cursors is laid, or shows effective value of between any 2 points, maximum value, and minimum value.



No.	Name	Function and description
Α	Cursor A	Shows measured value of cursor A and B of the graph.
	(Cursor B)	
В	Eff. Val.	Shows calculated effective value between cursor A and B.
С	Max. Val.	Shows maximum value and minimum value between cursor A and B while cursor is
	(Min. Val.)	displayed in Vertical Axis.
D	Cursor Display	Switches the cursor displaying or hiding with a check box. Selecting Vertical Axis or
		Horizontal Axis switches the cursor display.
E	Cursor time	Shows time of cursor A and cursor B, and time between cursor A and B when cursor is
		displayed in Vertical Axis.
	Cursor Line	Shows a position of cursor A and B. Move a mouse near around the cursor line and click to
		move the cursor line to the mouse position. Cursor Line can be also moved with dragging.
		Dragging the cursor with Shift key pressed can move the both cursor A and B
		simultaneously.
F		
		Vertical Axis Horizontal Axis
		The position of cursor A and B does not switch.
G	Cursor mark	A numeric value of a wave at where cursors is laid is displayed in Sampling item field
	(A, B)	(Cursor A, B).

4

### 4.9.8 History display

The past 5 sampling data (including the current data) can be saved in History, and available to display again. When sampling ends, the graph data and comment is added to History. If there are already 5 data when adding to History, the oldest data is erased.

When there are several data in the history, two graphs can be drawn at the same time. When overwriting graphs, the graph currently displayed is shown in each CH color and the one for overwriting is shown in gray.

Click History tab to display History section.



No.	Name	Function and description
А	History display	Shows how old the displaying graph is from the newest graph.
В	Graph displayed now	Click the number to display the responding graph of that number.
С	Graph overwriting	Checked graphs are displayed in layer.
D	Comment	A field for comments. Sampling date and time is automatically inputted when the sampling
		is finished and saved to History.

## REMARKS

For Continuous sampling, the data is added to History sequentially, and starts the next sampling.

When overwriting graphs, cursor function is valid only for the currently displayed graph.

# 4.9.9 Example of Graph sampling (monitoring Output Frequency, terminal RUN, terminal FU)



(6) Graph data can be exported (*Refer to page 88*) for saving data as a file.

4

### Graph (Monitor area)

When sampling with Inside trigger, starting at the Rise of terminal RUN, with 10% of sampling data before the trigger meets the condition

Set "00" ->

Select "Output

- (1) Select "00" at St. No. field. Select "Output Frequency" at Name field in CH1, "RUN" in CH5, and "FU" in CH6.
- (2) Make trigger setting as follows: Select "Inside" at Type field. Select "CH5" at CH field. Select "Rise" at Start At field. Set "10" at Position [%] field.

Set sampling interval and sampling time.

- (3) Click Start to show "Sampling Pre-trigger Data", and retrieves the data before the trigger meets condition (10% of whole sampling time). After the retrieval of the data before the trigger meets condition, then the screen shows "Waiting for Trigger" and becomes the trigger waiting state.
- (4) When trigger meets the condition (Rise of terminal RUN), sampling starts automatically.
- (5) Click Stop , or the sampling time has passed, and the sampling is finished.
- (6) Graph is adjustable for a better viewing.
- Frequency' Select "FU" Select "Inside" Select "CH5" Set Sampling Interval Set Sampling Time Select "Rise Set "10 Sampling Pre-trigger Data Waiting for Trigger Click \_\_\_\_\_Stop icale Display 11 One 14 All Move the 0 position Set a value of each of the selected graph

Set a value of each

one vertical grid

one horizontal grid

Select "RUN'

(7) Graph data can be exported (Refer to page 88) for saving data as a file.

#### REMARKS

In this example, "Position [%]" is set to "10%". The Rise of terminal RUN during the 10% of the whole sampling time after clicking Start (during Pre-Trigger state) is ignored, and sampling is not started.

upper or lower

 $(\bullet)$ 

Select "RUN"

Select "Fault"

Set "90'

Select "00'

Select

"FU"

Set Sampling Interval

· Set Sampling Time

• When sampling with Fault trigger, starting at a fault occurrence, with 90% of sampling data before the fault occurrence

Set "00"

Select "Output

Frequency"

- (1) Select "00" at St. No. field. Select "Output Frequency" at Name field in CH1, "RUN" in CH5, and "FU" in CH6.
- (2) Make trigger setting as follows: Select "Fault" at Type field. Select "00" at St. No. field. Input "90" at Position [%] field.

Set sampling interval and sampling time.

- (3) Click Start to show "Sampling Pre-trigger Data", and retrieves the data before the trigger meets condition. After the retrieval of the data before the trigger meets condition, then the screen shows "Waiting for Trigger" and becomes the trigger waiting state.
- (4) When inverter fault occurs, sampling starts automatically.
- (5) Click Stop , or the sampling time has passed, and then the sampling is finished.
- (6) Graph is adjustable for a better viewing.
- Click Start Sampling Pre-trigger Data Waiting for Trigger Click Stop

Move the 0 position of the selected graph Set a value of each upper or lower one vertical grid

Set a value of each one horizontal grid

(7) Graph data can be exported (Refer to page 88) for saving data as a file.

#### REMARKS $(\bullet)$

In this example, "Position [%]" is set to "90%". The fault occurrence during the 90% of the sampling time after clicking (during Pre-Trigger state) is ignored, and sampling is not started.

4
## 4.10 Batch Monitor (Monitor area)

"Batch Monitor" is for monitoring various data of a selected station. Select [Batch Monitor] in [View] menu to display "Batch Monitor".

St. No. juu Wonitor State (Wonitor Ing		
Types of Monitor	Peak Value	Current Value
Output Frequency	60.93Hz	60.85 Hz
Output Current	0A	OA
Output Voltage	234.6V	234.6V
Frequency Setting	61.02Hz	60.9Hz
Motor Torque	0%	0%
Converter Output Voltage	362.3V	361.3V
Regenerative Brake Duty	0%	0%
Electronic Thermal Relay Function Load Factor	0%	0%
Output Current Peak Value	0.06A	0.06A
Converter Output Voltage Peak Value	370.7V	369.4V
Output Power	OKW	OkW
Oumulative Energization Time	13h	13h
Actual Operation Time	1 h	1 h
Motor Load Factor	0%	0%
Cumulative Power	OKW	OkW
PID Set Point	0%	0%
PID Measured Value	0%	0%
PID Deviation	0%	0%
Motor thermal load factor	0%	
inverter thermal load factor	0%	

No.	Name	Function and description
Α	Start	Starts monitoring.
В	Stop	Stops monitoring.
С	Clear	Clears Peak Value and Current Value.
D	Station number	Displays the station number beging monitored.
Ш	Monitor State	Shows a state of monitor. If an error occurs, the color changes to red to display an error stop. During monitoring, the following indication appears to indicate monitoring.
F	Types of Monitor	Displays monitor item.
G	Peak Value	Displays the maximum value deteceted in each monitor item.
Н	Current Value	Displays the current monitoring value being measured in each monitor item.

#### Monitor item list

Refer to the inverter manual for details of monitor item.

Model name	Sampling Item
	Output Frequency, Output Current, Output Voltage, Frequency Setting Value, Running Speed, Motor Torque, Converter
	Output Voltage, Regenerative Brake Duty, Electronic Thermal Relay Function Load Factor, Output Current Peak Value,
	Converter Output Voltage Peak Value, Input Power, Output Power, Load Meter, Motor Excitation Current, Position Pulse,
110-27.00	Cumulative Energization Time, Orientation Status, Actual Operation Time, Motor Load Factor, Cumulative Power, Torque
	Command, Torque Current Command, Motor Output, Feedback Pulse, SSCNET III Communication Status, Power Saving
	Effect, Cumulative Saving Power, PID Set Point, PID Measured Value, PID Deviation
	Output Frequency, Output Current, Output Voltage, Frequency Setting, Converter Output Voltage, Regenerative Brake Duty,
	Electronic Thermal Relay Function Load Factor, Output Current Peak Value, Converter Output Voltage Peak Value, Output
T K-D700	Power, Cumulative Energization Time, Actual Operation Time, Motor Load Factor, Cumulative Power, PID Set Point, PID
	Measured Value, PID Deviation, Motor thermal load factor, Inverter thermal load factor, PTC Thermistor Resistance
Output Frequency, Output Current, Output Voltage, Frequency Setting, Motor Torque, Converter Output Vo	
FR-E700	Regemerative Brake Duty, Electronic Thermal Relay Function Load Factor, Output Current Peak Value, Converter Output
	Voltage Peak Value, Output Power, Cumulative Energization Time, Actual Operation Time, Motor Load Factor, Cumulative
	Power, PID Set Point, PID Measured Value, PID Deviation, Motor Thermal Load Factor, Inverter Thermal Load Factor
	Output Frequency, Output Current, Output Voltage, Frequency Setting, Running Speed, Converter Output Voltage,
	Regemerative Brake Duty, Electronic Thermal Relay Function Load Factor, Output Current Peak Value, Converter Output
FK-F/00	Voltage Peak Value, Intput Power, Output Power, Cumulative Energization Time, Actual Operation Time, Motor Load Factor,
	Cumulative Power, Power Saving Effect, Cumulative Saving power, PID Set Value, PID Measured Value, PID Deviation



## Note

- If a communication error occurs, a batch monitor stops. To perform batch monitor again, solve a cause of the communication error first, set the system OFFLINE once, and then ONLINE.
  When an inverter fault has occurred during Batch Monitor, the monitored value of Output Frequency, Output Current, Output Voltage at fault occurrence are held.

## 4.11 I/O Terminal Monitor (Monitor area)

You can check terminal assignment status of I/O terminal of the inverter, and plug-in option (FR-A7AR, FR-A7AX, FR-A7AY), and ON/OFF state of each terminal. The monitor turns green when terminal is ON and turns black when terminal is OFF. You can also start Wizard (*Refer to page 141*) for function assignment of each I/O terminal from "I/O Terminal Monitor". Select [I/O Terminal Monitor] in [View] menu to display "I/O Terminal Monitor".



No.	Name	Function and Description
Α	Start	Starts monitoring of I/O terminal.
В	Stop	Stops monitoring of I/O terminal. (I/O terminal state is held at the monitor stop.
С	Clear	Clears signal status (ON/OFF state) of I/O terminal.
П	Assign	Starts I/O terminal assignment wizard (Refer to page 141). I/O terminal can be assigned when ONLINE
D	Assign	and during not monitoring.
Е	Station number	Displays the station number of the monitoring inverter.
		Shows a state of monitor. If an error occurs, the color changes to red to indicate an error stop. During
F	Monitor status	monitoring, the following indication appears to indicate monitoring.
	Worntor status	
G	Inverter input terminal state	Displays input terminal state and function assignment status of the inverter.
н	Inverter output terminal	Displays output terminal state and function assignment status of the inverter. If negative logic is set,
	state	"(negative logic)" is displayed after function name.
		Displays input terminal state of the plug-in option (FR-A7AX), function assignment status, and
I	Option input terminal state	numerical data of the terminal. Displays numerical data of the terminal in hexadecimal and decimal in
		parenthesis.
1	Option output torminal state	Displays output terminal state and function assignment status of the plug-in option (FR-A7AR, FR-
J		A7AY, FR-A7NC). If negative logic is set, "(Negative Logic)" is displayed after function name.

## **4.12 I/O Terminal Assignment**

Use "I/O Terminal Assignment" to assign signal to I/O terminals of the inverter or plug-in option.

Click Assign of "I/O Terminal Monitor" to display "I/O Terminal Assignment" window.

Select terminal location to change the screen.

Select a signal for each terminal, then click . Necessary settings according to each terminal and the selected signal are displayed in the Parameter List.

Click **Enish** to reflect the changed setting into the Parameter List, then returns to the Main flame. To write the parameter setting to the inverter, write from the Parameter List in the Main frame. (*Refer to page 97*)

> I/D Terminal Assignment         Parameter List         Terminal Selection         Invester Output Terminals         Terminal         Signal         RUN         RUNInverter Running         FU         FU         FU         ALM: Fault Output			
Terminal     Signal       RUN     RUN:Inverter Running       FU     FU:Output Frequency Detection       ABC     ALM:Fault Output	>1/O Terminal Assignment Parameter List	Assign a signal to a termin I. Terminal Selection	
		Terminal     Signal       RUN     RUNI/Inverter Running       FU     FU:Dutput Frequency Detection       ABC     ALM:Foult Output	Negative logic

No.	Name	Function and Description
Α	Terminal Selection	Select a location of terminal to be assigned. Select input terminal, output terminal or plug-in option.
В	Signal selection field	Select a signal to be assinged.
С	Negative Logic	Check when selecting negative logic for assigning signal of the output terminal.
D	Help	Shows Help window. (Refer to page 147)
Е	Cancel	Closes the window with the setting made invalid.
F	<u>N</u> ext>	Displays Parameter List.
		Closes I/O terminal assignment at the Parameter List window with the setting made valid.
G	<u>F</u> inish	Configured setting by I/Oterminal assignment is reflected into Parameter List.
		(Parameter writing to the inverter is not performed.)

# 4.13 Machine Analyzer (Monitor area) (FR-A700 with Vector Control)

Machine analyzer reads and analyzes the torque and speed data when the inverter oscillates the motor at random torque for about 0.5 to 4s.

This allows measuring of the response frequency characteristic of speed relative to the motor torque of the machine so that you can grasp the frequency at which the mechanical system has the resonance point.

The analyzed data can be saved in a file (Export). And the saved data can be read (Import) and displayed. (Refer to page 88)

Select [Machine Analyzer] under [View] menu to display "Machine Analyzer" screen.

• The Machine Analyzer function is available for only the system that can perform vector control with encoder (FR-A7AP required).

- Machine Analyzer will not work in the following cases.
  - Inverter running

Note

- When the second motor is selected (Pr. 450 is not "9999")
- When the control mode is other than the vector control mode (Pr. 800 is not "0 to 5")
- Modbus-RTU communication is selected (Pr. 549 = "1")
- If a motor shaft is locked when performing Machine Analyzer, correct data may not be obtained, forced to end Machine Analyzer. Check the load applied to the motor beforehand.

Before starting Machine Analyzer operation, set the oscillation conditions and oscillation mode.



Machine Analyzer screen

No.	Name	Function and Description
۸	Wayoform data	Frequency characteristic measuring results are displayed in the Bode diagram (gain,
A		phase).
В	Start	Starts the Machine Analyzer.
С	Stml Condition	Sets the oscillation conditions for Machine Analyzer.
D	Stml Mode	Sets the oscillation mode for Machine Analyzer.
-	Resonance Point, Anti Resonance	Used to directly enter and specify the resonance point and opposite resonance point when
E	Point	they cannot be detected automatically.
F	Y-axis Scale Optimization	Used to change the scale automatically so that the waveform is contained within the screen.

#### **Procedure of Machine Analyzer operation**

- (1) Set Stml condition.
- "% of rated Torque" ......Set the maximum oscillation torque for oscillating the motor under a random torque command. (Setting range: 1 to 100%)
- "Strok" ......Set the rotation range permitted for oscillation, beginning at the motor position when Machine Analyzer is started. If this range is exceeded, Machine analyzer is stopped immediately, and the motor is coasted in the vertical shaft mode or is coasted after deceleration in the normal mode. (Setting range: ± to ±1000)

Stml Condition	Stml Mode
% of rated Torqu	e <sup>50</sup> %
(Setting Ran	ige: 1 to 100)
Stroke	.* 10 Speed
(Setting Ran	ge: 1 to 1000)

#### REMARKS

- If a measuring result varies, accurate measuring may not have been made.
- Accurate measuring may not be made in a mechanical system whose oscillation torque is too small or whose friction is large. In such a case, increase the oscillation torque and restart Machine Analyzer.
- If the oscillation torque is too large relative to the load inertia moment, an overcurrent or similar alarm may occur. At that time, reduce the oscillation torque and restart Machine Analyzer.
- Starting oscillation automatically switches to the torque control mode and shifts the position. Before starting operation after oscillation, therefore, always make a home position return.

(2)	Select	the	Stml	mode
-----	--------	-----	------	------

- "Normal mode" ......The inverter operates in the torque control mode and oscillates the motor randomly.
- "Vertical Axis Mode" .....A servo lock is placed in the speed control mode, preventing a fall. Gain setting must have been made to ensure that stable servo lock operation will be performed.

ml Condition	Stmi Mode
Normal	Mode

Vertical Axis Mode

n the vertical axis mode, perform position and speed control at the present settings without oscillation pefore carrying out the Machine Analyzer operation.



#### In "Vertical Axis Mode"

- The accuracy of 100Hz or less on the low frequency side may become poor.
- The measuring accuracy becomes poor if the position loop gain (Pr. 422) is set too high.



#### Note

When the machine is a vertical shaft, always perform this function in the "Vertical Axis Mode" since a fall may occur.

(3) Press button to display a message to confirm that the operation is at a stop. Check that the operation status is at a stop, and click [OK].



A following screen appears when the "Vertical Axis Mode" is selected.

Machin	ie Analyzer 🛛 🛛 🔀
1	Wire the brake open to the "Operation Ready 2" signal of the inverter if an electromagnetic brake is equipped for drop prevention. The machine may drop or alarm may occur if this signal is not used.
	OK Cancel

Click [Cancel] button to return to the Machine Analyzer setting screen.

Click [OK] button to display the Machine Analyzer Operation start screen.

#### Note When

When Machine Analyzer is executed in the vertical shaft mode, a servo lock is first placed, and "Operation ready 2" signal is output, and then the motor is started in 0.5s.

- When an electromagnetic brake is used, assign the "Operation ready 2" signal to any of the output terminals and modify the circuit to open the electromagnetic brake using this signal. If this is not done, a machine drop or an overcurrent or similar alarm may occur. (For details of *Pr. 190 to Pr. 196* "output terminal function selection", refer to the Instruction Manual of the inverter.)
- (4) Click [OK] button in the Machine Analyzer Operation screen to start the operation.



Machine Analyzer Operation screen

Click [Cancel] button to return to the Machine Analyzer screen.

(5) When Machine Analyzer is started, a following screen appears so that you can check the Machine Analyzer progress conditions.

Oscillation	Reading Data
Step 1	100%
Step 2	39%
Step 3	0%
Analysis	0%

•Guideline of oscillation time

Step	Oscillation Time
Step 1	Approx. 0.5s
Step 2	Approx. 1s
Step 3	Approx. 4s
Analysis	Approx. 15s

Click [Cancel] button to stop the Machine Analyzer Operation, and return to the Machine Analyzer screen.

During oscillation, oscillation can be stopped with [Cancel] button, MRS signal (output stop signal) or the parameter unit [STOP] key.

A following screen appears if the motor rotation stroke exceeds the permissible range or the motor speed exceeds 3000r/min during oscillation.

Click [OK] button to return to the Machine Analyzer setting screen.

· If the motor rotation stroke exceeds the permissible range



· If the motor speed exceeds 3000r/min



(6) On completion of Machine Analyzer, the frequency characteristics are displayed on the Machine Analyzer screen.

(7) The frequency characteristics measured by Machine analyzer are displayed in Bode diagram. For the waveform data, you can change the vertical axis scale and/or move the resonance point and opposite resonance point cursors.



No.	Name	Function and Description	
А	Setting of the vertical axis scale	Click the [  ] to display the drop-down list. The unit of the vertical axis scale can be selected from the list. Click " Y-axis scale optimization" button to automatically change the scale to put the waveform within the screen.	
В	Moving the position of zero in the vertical axis	Click the [	
С	Resonance Point, Anti-Resonance Point cursors	The resonance point (red cursor) and opposite resonance point (yellow cursor) are normally detected automatically. In case not being detected automatically depending on the characterictic, move the cursors to the normal positions by directly writing the resonance point and opposite resonance point frequency.	

Help 🚿

## 4.14 Help

#### 4.14.1 Help

Checking a software manual and inverter manual is available with using Help function. There are following ways of displaying Help.

- (1) Select [Help] in [Help] menu to display.
- (2) Click

on the tool bar to display.

- (3) Press F1 key on the keyboard to display.
- (4) Click Help on the current window to display.
- (5) Press F1 key when selecting a parameter on the parameter list to display Help. Description of the selected parameter appears.



No.	Name	Function and description		
		Hides navigation panel, and Contents, Index, Search tabs. While hiding the navigation		
A	Hide	panel and tabs, the button changes to $\begin{array}{c} & & & \\ & \\ & \\ & \\ & \\ & \\ & \\ & \\ & $		
		and tabs again.		
В	Back	Returns to the previous help description.		
с	Forward	Click to read forward the help description again after using $\begin{bmatrix} \leftarrow \\ Back \end{bmatrix}$ and returned to the		
		previous description.		
D	Print	Prints help description.		
E	Minimize button	Click to minimize the help window.		
F	Maximize button	Click to maximize the help window.		
G	Close button	Click to close the help window.		
Н	Contents	Click when checking the contents. Displays Contents in navigation panel.		
I	Index	Click when checking index. Displays Index in navigation panel.		
J	Search	Click when using search function. Displays Search in navigation panel.		
K	Navigation	Displays Contents, Index and Search.		
L	Contents	Shows help description.		

4

#### • HTML format and link

Help description is displayed in the contents panel. Help description is displayed in HTML format. Hyperlink is available to jump to the related help description. Hyperlink in a text is shown in blue and underline.

#### Contents

Click Contents to display a list of content. Click a desired item in the list to show the help description.



#### • Index

Click Index to display a index of registered words.

Type characters to narrow down the registered words. Double-click the desired word in the list to show the help description of that word.



#### • Search

Click <u>Search</u> to display search panel. Type character string and click <u>List Topics</u> to perform full-text search with the character string. Double-click the desired topic in the search result to show the help description of that topic.



#### 4.14.2 Version Information

Select [About FR Configurator SW3...] in [Help] menu to display copyright, product name, type name, version information and license of FR Configurator.



No.	Name	Function and description
Α	Product name	Shows product name.
В	Version	Shows version information.
С	Copyright information	Shows copyright information.
D	Copyright description	Shows copyright description.
E	ОК	Click to close the version information window.

4

## **MEMO**



This chapter explains the "Trouble indication" of this product.

Always read the instructions before using the software.

5.1	Error Code	152
5.2	Error Display on a Dialog	159



## 5.1 Error Code

If a communication error is detected, the following communication error code and error message appears in communication error dialog (*Refer to page 32*).

#### 5.1.1 Communication error with inverter

Error Code (HEX)	Error Message	Cause	Countermeasure
0x80A00101	Failed to open a communication line.	<ol> <li>Communication setting is not set for USB while connecting with USB.</li> <li>No communication port existed on the PC. Or not recognized.</li> </ol>	<ol> <li>Check for connection configuration at [Options] in [Tool] menu. (<i>Refer to page</i> 85)</li> <li>Check that communication port exists on the PC.</li> </ol>
0x80A00104 0x80A00107 0x80A0010A	An unexpected error occurred to S/W.	Please contact your	sales representative.
0x80010000	Errors from computer in a row are more than the retry count.	<ol> <li>Setting of <i>Pr. 124 PU communication CR/LF selection, Pr. 341 RS-485 communication CR/LF selection</i> is different with software setting.</li> <li>Electromagnetic interference</li> <li>Cable breakage</li> </ol>	<ol> <li>Set Pr. 124 PU communication CR/LF selection, Pr. 341 RS-485 communication CR/LF selection same as the setting of the software.</li> <li>Set larger value in Pr. 121 Number of PU communication retries, Pr. 335 RS-485 communication retry count.</li> <li>Replacement of cable</li> </ol>
0x80010001	The parity check result does not match the specified parity.	<ol> <li>Setting of <i>Pr. 120 PU communication</i> parity check, <i>Pr. 334 RS-485</i> communication parity check selection is different with software setting.</li> <li>Electromagnetic interference</li> <li>Cable breakage</li> </ol>	<ol> <li>Set Pr. 120 PU communication parity check, Pr. 334 RS-485 communication parity check selection same as the setting of the software.</li> <li>Set larger value in Pr. 121 Number of PU communication retries, Pr. 335 RS-485 communication retry count.</li> <li>Replacement of cable</li> </ol>
0x80010002	The sum check code in the computer does not match that of the data received by the inverter.	<ol> <li>Communication setting is different between the inverter and the software.</li> <li>Data corrupted due to electromagnetic interference, etc.</li> </ol>	<ol> <li>Make a same communication setting.</li> <li>Check for electromagnetic interference and wiring.</li> </ol>
0x80010003	Data received by the inverter is in the wrong protocol, or data receive is not completed within the given time.	<ol> <li>Setting of <i>Pr. 124 PU communication CR/LF selection, Pr. 341 RS-485 communication CR/LF selection</i> is different with software setting.</li> <li>Electromagnetic interference</li> <li>Cable breakage</li> </ol>	<ol> <li>Set Pr. 124 PU communication CR/LF selection, Pr. 341 RS-485 communication CR/LF selection same as the setting of the software.</li> <li>Set larger value in Pr. 121 Number of PU communication retries, Pr. 335 RS-485 communication retry count.</li> <li>Replacement of cable</li> </ol>
0x80010004	The stop bit length differs from the initial setting.	<ol> <li>Setting of <i>Pr. 119 PU communication stop</i> <i>bit length, Pr.333 RS-485 communication</i> <i>stop bit length</i> is different with software setting.</li> <li>Electromagnetic interference</li> <li>Cable breakage</li> </ol>	<ol> <li>Set Pr. 119 PU communication stop bit length, Pr.333 RS-485 communication stop bit length same as the setting of the software.</li> <li>Set larger value in Pr. 121 Number of PU communication retries, Pr. 335 RS-485 communication retry count.</li> <li>Replacement of cable</li> </ol>

Error Code (HEX)	Error Message	Cause	Countermeasure
0x80010005	Due to wiring error, next data intruded before data reception is completed.	<ol> <li>Setting of <i>Pr. 123 PU communication</i> waiting time setting, <i>Pr.337 RS-485</i> communication waiting time setting is too small.</li> <li>Electromagnetic interference</li> <li>Cable breakage</li> </ol>	<ol> <li>Set larger value or 9999 in <i>Pr. 123 PU</i> communication waiting time setting, <i>Pr.337</i> <i>RS-485 communication waiting time</i> setting.</li> <li>Set larger value in <i>Pr. 121 Number of PU</i> communication retries, <i>Pr. 335 RS-485</i> communication retry count.</li> <li>Replacement of cable</li> </ol>
0x80010007	The character received is invalid (other than 0 to 9, A to F, control code).	<ol> <li>Setting of <i>Pr. 119 PU communication stop</i> <i>bit length</i>, <i>Pr.333 RS-485 communication</i> <i>stop bit length</i> is different with software setting.</li> <li>Electromagnetic interference</li> <li>Cable breakage</li> </ol>	<ol> <li>Set Pr. 119 PU communication stop bit length, Pr.333 RS-485 communication stop bit length same as the setting of the software.</li> <li>Set larger value in Pr. 121 Number of PU communication retries, Pr. 335 RS-485 communication retry count.</li> <li>Replacement of cable</li> </ol>
0x8001000A	A mode error occurred.	Parameter setting or frequency setting was performed in the operation mode such as external operation (EXT) etc. which has no parameter setting and speed command source with the FR Configurator.	Change the operation mode to the PU operation mode (or NET). Check the setting value of <i>Pr. 338</i> <i>Communication operation command source, Pr.</i> <i>550 NET mode operation command source</i> <i>selection, Pr. 551 PU mode operation command</i> <i>source selection.</i> (Operation command source changes according to inverter communication connection. <i>Refer to page 10, 24</i> )
0x8001000C	An unexpected error occurred to S/W.	Please contact your	sales representative.
0x80010011	You can not write a value out of range to parameter.	Tried to write a value out of setting range of the parameter.	Set a value within the setting range, and write.
0x80010012	A mode error occurred.	<ol> <li>Pr. 79 Operation mode selection is not set for PU/NET (RS-485).</li> <li>Parameter setting or frequency setting was performed in the operation mode such as external operation (EXT) etc. which has no parameter setting and speed command source with the FR Configurator.</li> </ol>	<ol> <li>Click [PU] button of Test Operation. Change the setting of <i>Pr. 79</i> for PU/ NET (RS-485).</li> <li>Change the operation mode to the PU operation mode (or NET). Check the setting value of <i>Pr. 339</i> <i>Communication speed command source, Pr.</i> <i>551 PU mode operation command source</i> <i>selection.</i> (Speed command source changes according to inverter communication connection. <i>Refer to</i> <i>page 10, 24</i></li> </ol>
0x80010013	Parameter writing during inverter operation is unavailable.	Parameter writing was attempted during inverter operation.	Perform parameter writing after inverter is stopped.
0x80010014	Parameter writing to a write disabled parameter is unavailable.	<ol> <li>Writing is disabled by <i>Pr.</i> 77 <i>Parameter</i> <i>write selection.</i> <i>Pr.</i> 77 = 1 (write disabled)</li> <li>Password lock is activated.</li> </ol>	<ol> <li>Change the setting of <i>Pr: 77 Parameter</i> <i>write selection</i> except for "1".</li> <li>Enter the password in <i>Pr: 297</i> to unlock the password lock.</li> </ol>
0x80010016	Can not read/write an nonexistent parameter.	<ol> <li>Version of inverter and version of setup software parameter file is not corresponding.</li> <li>Simple mode is set by <i>Pr: 160 User group</i> <i>read selection.</i></li> <li>Password lock is activated.</li> </ol>	<ol> <li>Reinstallation of the software</li> <li>Change the setting of <i>Pr. 160</i> except for simple mode setting.</li> <li>Enter the password in <i>Pr. 297</i> to unlock the password lock.</li> </ol>
0x80010017	Specified option is not installed in the inverter.	Reading of option parameter was attempted while the option is not installed.	Install the option to the inverter.

Error Code (HEX)	Error Message	Cause	Countermeasure
0x80010018	There is no difference between the analog setting of gain and bias.	There is only small difference between the analog setting of gain and bias.	Set larger setting between the analog setting of gain and bias.
0x8001001A	Unsupported model is connected.	If FR-E500 is connected to the station where FR-E700 is set for system setting, switching to ONLINE will display a communication error dialog. In this case, click OK, and proceed converting.	
0x80010021	Operation mode switching during inverter operation is unavailable.	Change the operation mode after the inverter stop.	Set "2" in <i>Pr. 77 Parameter write selection.</i> Stop the inverter.
0x80010022	When forward rotation signal (STF) is on, switching to External mode is unavailable.	Switching to External mode was attempted when forward rotation signal (STF) is on.	Change the operation mode after switching off of STF.
0x80010023	When reverse rotation signal (STR) is on, switching to External mode is unavailable.	Switching to External mode was attempted when reverse rotation signal (STR) is on.	Change the operation mode after switching off of STR.
0x80010024	Switching of operation mode is unavailable with current operation mode.	Attempted to switch the operation mode other than the one set in <i>Pr. 79 Operation mode selection</i> .	Change the setting of <i>Pr. 79 Operation mode selection.</i>
0x80010025	Reset is unavailable with current setting.	Reset is restricted by Pr. 75 Reset selection/ disconnected PU detection/PU stop selection.	Change the setting of <i>Pr.</i> 75 Reset selection/ disconnected PU detection/PU stop selection.
0x80010026	An unexpected error occurred to S/W.	Please contact your sales representative.	
0x80010101	Failed to make communication with the inverter during the time set with Time Out.	<ol> <li>Setting of <i>Pr. 122 PU communication check</i> <i>time interval</i>, <i>Pr. 336 RS-485</i> <i>communication check time interval</i>, <i>Pr. 548</i> <i>USB communication check time interval</i> is too small.</li> <li>Electromagnetic interference</li> <li>Cable breakage/damaged</li> <li>PC port is set invalid/port breakage</li> </ol>	<ol> <li>Set larger value or 9999 in <i>Pr. 122 PU</i> communication check time interval, <i>Pr. 336</i> <i>RS-485</i> communication check time interval, <i>Pr. 548 USB communication check time</i> interval.</li> <li>Set larger value for Time Out setting of the software.</li> <li>Cable connection/replacement</li> <li>Activate the port by using Device Manager/port replacement</li> </ol>
0x80010102	Illegal data is included in the data received by the computer.	<ol> <li>Setting of <i>Pr. 124 PU communication CR/LF selection, Pr. 341 RS-485 communication CR/LF selection</i> is different with software setting.</li> <li>Electromagnetic interference</li> <li>Cable breakage</li> </ol>	<ol> <li>Set Pr. 124 PU communication CR/LF selection, Pr. 341 RS-485 communication CR/LF selection same as the setting of the software.</li> <li>Set larger value in Pr. 121 Number of PU communication retries, Pr. 335 RS-485 communication retry count.</li> <li>Replacement of cable</li> </ol>
0x80020001	An unexpected error occurred to S/W.	Please contact your sales representative.	
0x80020002	You can not write a value out of range to parameter.	Tried to write a value out of setting range of the parameter.	Set a value within the setting range, and write.
0x80020003 0x80020004	An unexpected error occurred to S/W.	Please contact your	sales representative.
0x80020005 0x80020006 0x80020007 0x80020008	Failed to obtain the received data.	Failed to obtain the graph sampling data during High Speed sampling.	Close other applications. Set larger value for Mask Count.
0x80030001	Wrong communication port is assigned.	<ol> <li>Communication port is set invalid.</li> <li>Other application is already using the same port.</li> </ol>	<ol> <li>Activate the port by using Device Manager.</li> <li>Close other applications, and turn ONLINE.</li> </ol>

Error Code (HEX)	Error Message	Cause	Countermeasure	
0x80030002				
0x80030003				
0x80030004				
0x80030005				
0x80030006	An unexpected error			
0x80030007	occurred to S/W.	Please contact your sales representative.		
0x80030008				
0x80030009				
0x8003000A				
0x8003000B				
	Duplicated station number			
0x8003000C	were found with USB			
	communication.			
0×80030000	An unexpected error	Please contact your	sales representative	
0,00030000	occurred to S/W.	Please contact your sales representative.		
0x8003000E	Driver is not installed or	Driver is not installed or broken	Reinstallation of the software	
UNDECOUNCE	broken.			
0x8003000F	An unexpected error	Please contact your sales representative.		
0x80030010	occurred to S/W.			

## 5.1.2 Communication error when connected through GOT

Error Code HEX)	Error Message	Cause	Countermeasure
0x80110001	An unexpected error occurred to S/W.	GOT type error.	Check for the GOT type.
0x80110002 0x80110003	An unexpected error occurred to S/W.	Please contact your	sales representative.
0x80110004	Failed to make a communication with the inverter during the time set with Time Out.	<ol> <li>Communication protocol of the inverter and GOT are not the same.</li> <li>Setting of <i>Pr. 122 PU communication check</i> <i>time interval</i>, <i>Pr. 336 RS-485</i> <i>communiaction check time interval</i>, <i>Pr. 548</i> <i>USB communication check time interval</i> is other than "0".</li> <li>Electromagnetic interference</li> <li>Cable breakage/damaged</li> </ol>	<ol> <li>Set communication protocol of the inverter and GOT same.</li> <li>Set a value other than "0" in <i>Pr. 122 PU</i> communication check time interval, <i>Pr. 336</i> <i>RS-485 communiaction check time interval</i>, <i>Pr. 548 USB communication check time</i> <i>interval</i>.</li> <li>Set larger value for Time Out setting of the software.</li> <li>Cable connection/replacement Check for communication cable and power supply of devices.</li> </ol>
0x80110005	Failed to make a communication with the inverter during the time set with Time Out.	FR Configurator was started and a communication was made when GX drawing software was starting.	After closing GX drawing software, try communication again.
0x80110006	Failed to make a communication with the inverter during the time set with Time Out.	GX drawing software was started when FR Configurator was starting.	After closing GX drawing software, try communication again.
0x80110007	An unexpected error occurred to S/W.	Communication line quality error	Set lower baud rate and make a communication.
0x80110008	An unexpected error occurred to S/W.	Baud rate not supported by connected device	Check for the baud rate supported by connected devices.
0x80110009	Failed to make a communication with the inverter during the time set with Time Out.	<ol> <li>Electromagnetic interference</li> <li>Cable breakage/damage</li> </ol>	<ol> <li>Set larger value for Time Out setting of the software.</li> <li>Cable connection/replacement Check that line is connected.</li> </ol>
0x8011000A	Failed to make a communication with the inverter during the time set with Time Out.	Other process is ongoing in GOT and line is BUSY. (retry is performed in the EZSockt) A station not connected is being monitored.	Set a larger value for Time Out setting of the software. Monitor only the station which the GOT is connected. Check that the GOT is operating normally and try again.
0x8011000B	An unexpected error occurred to S/W.	Protocol type error	Check for protocol type.
0x8011000C	An unexpected error occurred to S/W.	Host name error	Check for connected GOT host name.
0x8011000D	An unexpected error occurred to S/W.	Socket port number error	Check for the port number.

Error Code	Frror Message	Cause	Countermeasure
HEX)	Error message	Cause	oounternicusure
0x80111001			
0x80111002			
0x80111003			
0x80111004			
0x80111005	Failed to make		
0x80111101	communication with the	Electromagnetic interference, etc. are	Set a larger value for Time Out setting of
0x00111102	inverter during the time set	propagated when receiving GOT software.	the software and try again.
0x80111104	with Time Out.		
0x80111105			
0x80111106			
0x80111107			
0x801111FF			
0x80112001	Wrong communication port	Serial line open error	Check for the communication port setting.
	An unexpected error		
0x80112002	occurred to S/W.	Serial line closed error	Try again.
0x80112003	An unexpected error occurred to S/W.	Serial line setting error	Try again.
0x80112004	An unexpected error	Serial line baud rate error	Try again.
	occurred to S/W.		
	Failed to make	Occurred before starting the FR	
0x80112005	communication with the	Configurator, or during communication	Connect the cable.
	inverter during the time set	RS-232C cable between the GOT and PC	
	An unexpected error	EZSocket COT is installed, but the file is	
0x80112201	An unexpected error	broken	Install software again.
	Failed to make	Before starting the FR Configurator	
	communication with the	1. A cable between the GOT and PC is	1. Connect the cable.
0x80112202	inverter during the time set	disconnected.	2. Power ON the GOT.
	with Time Out.	2. The GOT power is OFF.	
	Failed to make		
0x80112203	communication with the	Electromagnetic interference, etc. are	Set a larger value for Time Out setting of
0,000112200	inverter during the time set	affecting between the PC and GOT.	the software and try again.
	with Time Out.		
0x80112204	An unexpected error	USB line error (at the GOT device error	Try again.
	occurred to S/VV.	communication ending)	
0x80112205	occurred to S/W.	USB line error (sending function is invalid)	Try again.
0,20112206	An unexpected error	LISP line error (receiving function is involid)	
0x80112206	occurred to S/W.		Try again.
0x80112207	An unexpected error occurred to S/W.	USB line error (cable disconnection registration faillure)	After reconnecting with the GOT, try again.
		USB line error (cable was disconnected	
		halfway)	
	Failed to make	1. When a cable between the GOT and PC	1. Check for ashie connection
0x80112208	communication with the	was disconnected during	Check for cable connection.     Bower ON the COT
	with Time Out	communication.	2. Fower ON the GOT.
	with thine Out.	2. When the GOT power turned OFF	
		during communication	
0x80112401	An unexpected error	The GOT was not found on the network.	Check that the GOT is connected to the
	An unexpected error	Socket line open error (socker generation	Check that specified port number is correct
0x80112402	occurred to S/W	failed)	and specified IP address is for GOT
	An unexpected error	·····•••)	
0x80112403	occurred to S/W.	Please contact your sales representative.	
0x80112405	An unexpected error	Network error	Check that the GOT is connected to the network
	An unexpected error		Check that the GOT is not making a
0x80112406	occurred to S/W.	Connected socket forced disconection	communication in other connection method.

## 5.1.3 Other error (Task busy)

Error Code (HEX)	Error Message	Cause	Countermeasure
Error code other than above	Task busy state. Try the operation again.	Processing could not be completed, due to increase in load of software processing or comunication processing.	End unnecessary applications. Delete the setting of non-connected station.

## 5.2 Error Display on a Dialog

When using or closing FR Configurator, or at fault occurrence, a message dialog appears for providing information or for warning.

There are four types of message dialog.

lcon	Error Type	Mainly Used Button	Description
8	Warning	ОК	Appears if an attempted operation may have an affect on the human body, or may cause an inverter failure.
1	Caution	OK Cancel	Appears when a confirmation is required before the operation.
<b>i</b>	Information	<u>Y</u> es <u>N</u> o	Appears to provide information about the operation.
?	Inquiry	Yes No Cancel	Appears when replay to the inquiry message is variable

There are following message for warnings and caution.

Display	Description	
File does not exist, or file corrupted.	Appears when the file does not exist, or file is corrupted	
The file is locked.	Appears when writing to a looked file	
Unlock the file for saving.	Appears when whing to a locked life	
The following required files for this software are missing. Please	Appears when required files for starting up the software are missing	
perform setup again.		
File name: XXXXXXXXXXXXX		
The following required files for this software are broken. Please perform	Appears when required files for starting up the software are	
setup again.		
File name: XXXXXXXXXXXXX	broken (o byte me/me format is abriormal)	
System File is corrunted	Appears when the file set for "System File to be Read at Starting	
	up" is corrupted	
System File is not found	Appears when the file set for "System File to be Read at Starting	
	up" does not exist	
St. No.: XX		
	Appears at communication error occurrence	
Error description	(Refer to page 152)	
Communication Error Code: XXXXXXXXXX		
St. No.: XX		
Unknown error occurred.	Appears when unknown fault or communication error occurred	
Communication Error Code: XXXXXXXXXX		
Please contact your sales representative.		

5

\*The manual number is given on the bottom left of the back cover.

Print Date	*Manual Number	Revision
Sep., 2007	IB(NA)-0600306ENG-A	First edition (For Sample Version 0.01)
Jan., 2008	IB(NA)-0600306ENG-B	Additions Multiple connection of inverters Connection through GOT (FA transparent function) Additional functions (Tuning, Troubleshooting, Parameter List Enhancement, Diagnosis, Batch Monitor, I/O Terminal Monitor, I/O Terminal Assignment) (For Sample Version 0.20)
Apr., 2008	IB(NA)-0600306ENG-C	Additions • Compatible with FR-A700 series, FR-D700 series, FR-F700 series • Machine Analyzer (For Version 3.00)