

MLFB-Ordering data

6SL3210-1KE21-7AF1



Client order no. : Order no. : Offer no. : Remarks:

Item no.: Consignment no. : Project :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	
Rated current (LO)	21.50 A	
Rated current (HO)	18.20 A	
Output		
Number of phases	3 AC	
Rated voltage	400 V	
Rated power IEC 400V (LO)	7.50 kW	
Rated power NEC 480V (LO)	10.00 hp	
Rated power IEC 400V (HO)	5.50 kW	
Rated power NEC 480V (HO)	7.50 hp	
Rated current (IN)	17.00 A	
Rated current (LO)	16.50 A	
Rated current (HO)	12.50 A	
Max. output current	25.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

Overload capability		
Low Overload (LO)		

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a

High Overload (HO)

300 s cycle time

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
rower factor A	0.70 0.65	
Offset factor cos φ	0.95	
Efficiency η	0.97	
Sound pressure level (1m)	63 dB	
Power loss	0.24 kW	
Filter class (integrated)	Class A	

Ambient conditions		
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.009 m³/s (0.318 ft³/s)	
Installation altitude	1000 m (3280.84 ft)	
Ambient temperature		
Operation	-10 40 °C (14 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		

Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



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			Fig
Mechanical	data	Com	nmunication
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP
Size	FSB	Co	nnections
Net weight	2.30 kg (5.07 lb)	Signal cable	
Width	100 mm (3.94 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AW
Height	196 mm (7.72 in)	Line side	
Depth	208 mm (8.19 in)	Version	Plug-in screw terminals
Inputs / ou	tputs	Conductor cross-section	4.00 6.00 mm² (AWG 12 AW
tandard digital inputs		Motor end	
Number	6	Version	Plug-in screw terminals
Switching level: 0→1	11 V	Conductor cross-section	4.00 6.00 mm² (AWG 12 AW
Switching level: 1→0	5 V	DC link (for braking resistor)
Max. inrush current	15 mA	Version	Plug-in screw terminals
ail-safe digital inputs		Conductor cross-section	4.00 6.00 mm² (AWG 12 AW
Number	1	Line length, max.	15 m (49.21 ft)
igital outputs		PE connection	On housing with M4 screw
Number as relay changeover contact	1	Max. motor cable length	Off flousing with M4 screw
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)
Number as transistor	1	Unshielded	150 m (492.13 ft)
Output (resistive load)	DC 30 V, 0.5 A	S	tandards
analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low- Directive 2006/95/EC
witching threshold as digital in	put		
0→1	4 V		
1→0	1.6 V		

PTC/ KTY interface

Analog outputs

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$

1 (Non-isolated output)



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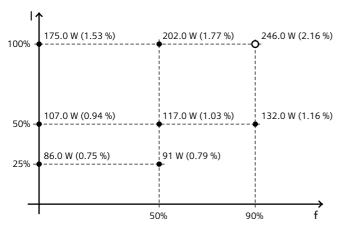
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Figure similar

Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-63.01 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values